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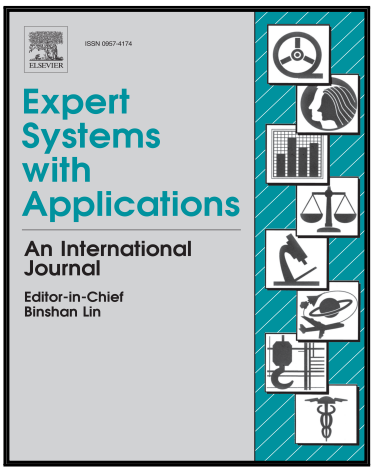

Towards a Common Implementation of Reinforcement Learning for Multiple Robotic Tasks

Angel Martínez-Tenor, Juan Antonio Fernández-Madrigal, Ana Cruz-Martín, Javier González-Jiménez

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Highlights

- A value-iteration-based algorithm is effectively applied to multiple robotic tasks.
- Novel exploration improves softmax action selection by structuring the inputs.
- Reinforcement Learning with novel exploration improves model-free solutions. Compatible with high dimensional Reinforcement Learning with low computational cost.

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