Accepted Manuscript

Assistive system based on nerve detection and needle navigation in ultrasound images for regional anesthesia

Oussama Hadjerci, Adel Hafiane, Nicolas Morette, Cyril Novales, Pierre Vieyres, Alain Delbos

PII: S0957-4174(16)30220-2 DOI: 10.1016/j.eswa.2016.05.002

Reference: ESWA 10660

To appear in: Expert Systems With Applications

Received date: 3 February 2016 Revised date: 30 April 2016 Accepted date: 1 May 2016



Please cite this article as: Oussama Hadjerci, Adel Hafiane, Nicolas Morette, Cyril Novales, Pierre Vieyres, Alain Delbos, Assistive system based on nerve detection and needle navigation in ultrasound images for regional anesthesia, *Expert Systems With Applications* (2016), doi: 10.1016/j.eswa.2016.05.002

This is a PDF file of an unedited manuscript that has been accepted for publication. As a service to our customers we are providing this early version of the manuscript. The manuscript will undergo copyediting, typesetting, and review of the resulting proof before it is published in its final form. Please note that during the production process errors may be discovered which could affect the content, and all legal disclaimers that apply to the journal pertain.

ACCEPTED MANUSCRIPT

Highlights

- Assistive system based on ultrasound images analysis and robotics guidance for UGRA.
- New approach based on machine learning and image processing to identify the nerve.
- Combination of template matching and active contour to segment the ROIs in US images.
- Real-time trajectory generation algorithm for guiding the needle.
- Direct model based method with adaptability to the environment dynamics.

Download English Version:

https://daneshyari.com/en/article/6855635

Download Persian Version:

https://daneshyari.com/article/6855635

<u>Daneshyari.com</u>