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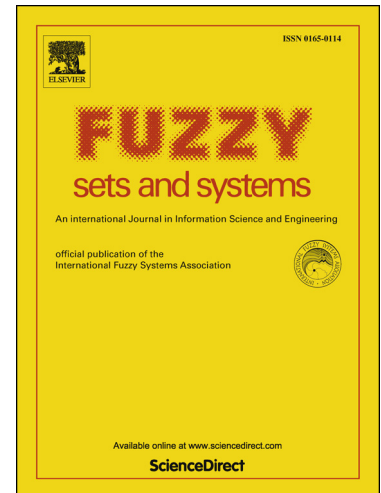
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Adaptive fuzzy control for feedback linearizable MIMO nonlinear systems with prescribed performance

Wuxi Shi [☆], Baoquan Li

*1.School of Electrical Engineering and Automation, Tianjin Polytechnic University,
Tianjin, China, 300387*

*2.Tianjin Key Laboratory of Advanced Technology of Electrical Engineering and Energy,
Tianjin, China, 300387*

Abstract

In this paper, a new adaptive fuzzy control scheme with prescribed performance is developed for a class of feedback linearizable uncertain MIMO nonlinear systems with unknown control direction and external disturbances. The fuzzy systems are employed to approximate the unknown nonlinear functions, and a Nussbaum-type function is applied to resolve the unknown control direction problems. By using the prescribed performance bounds, an adaptive fuzzy controller equipped with the Nussbaum-type gain function is developed. The proposed design scheme guarantees that all the signals in the closed-loop systems are bounded and that the tracking errors converge to a prescribed performance bounds by guaranteeing the convergence of the filtered tracking error to a predefined performance bounds. Two simulation

[☆]Corresponding author. Tel./fax: +86-22-83955415. E-mail address: shiwuxi@163.com

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