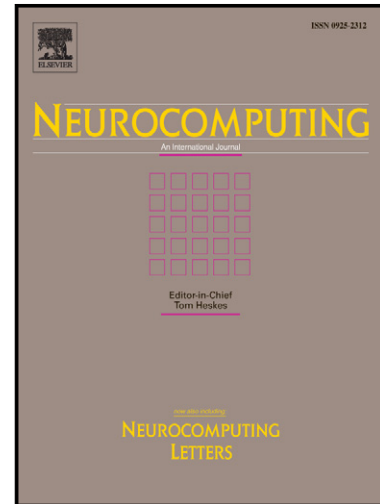


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Simplified adaptive neural control of strict-feedback nonlinear systems[★]

Yongping Pan^a, Yiqi Liu^b, Haoyong Yu^a

^a*Department of Biomedical Engineering, National University of Singapore, Singapore 117575*

^b*School of Automation Science and Engineering, South China University of Technology, Guangzhou 510640, China*

Abstract

This paper presents a simplified adaptive backstepping neural network control (ABNNC) strategy for a general class of uncertain strict-feedback nonlinear systems. During the backstepping design, all unknown functions at intermediate steps are passed down such that only a single neural network (NN) is needed to approximate a lumped uncertainty at the last step. The closed-loop system achieves practical asymptotic stability in the sense that all involved signals are bounded and the tracking error converges to a small neighborhood of zero. The contribution of this study is that the complexity growing problem of the traditional ABNNC design is substantially eliminated for a general class of uncertain strict-feedback nonlinear systems, where the constraints of control parameters that guarantees closed-loop stability is clearly demonstrated. An illustrative example has been provided to verify effectiveness of the proposed approach.

Key words: Adaptive control, backstepping, neural network, function approximation, strict-feedback, nonlinear system.

1 Introduction

Recent years, adaptive approximation-based control using fuzzy systems or neural networks (NNs) has attracted great concern due to its effectiveness of modeling functional uncertainties in nonlinear systems [1]. Some recent results

[★] Corresponding author: H. Yu.

Email addresses: biepany@nus.edu.sg (Yongping Pan), aulyq@scut.edu.cn (Yiqi Liu), bieyhy@nus.edu.sg (Haoyong Yu).

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