

Accepted Manuscript

Design of a 3-DOF tripod electro-pneumatic parallel manipulator

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PII: S0921-8890(15)00091-3

DOI: <http://dx.doi.org/10.1016/j.robot.2015.04.009>

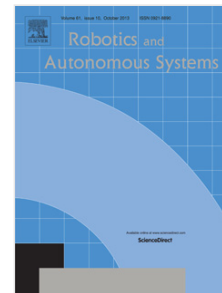
Reference: ROBOT 2471

To appear in: *Robotics and Autonomous Systems*

Received date: 8 February 2014

Revised date: 12 April 2015

Accepted date: 17 April 2015



Please cite this article as: P.A. Laski, J.E. Takosoglu, S. Blasiak, Design of a 3-DOF tripod electro-pneumatic parallel manipulator, *Robotics and Autonomous Systems* (2015), <http://dx.doi.org/10.1016/j.robot.2015.04.009>

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Conceptual design and analysis of the 3-UPRR parallel manipulator are performed.
Kinematics analysis are carried out for the proposed 3-DOF robot.
Electro-pneumatic parallel manipulator.

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