Accepted Manuscript

Clearance vs. tolerance for rigid overconstrained assemblies

Jean-François Rameau, Philippe Serré, Mireille Moinet

 PII:
 S0010-4485(17)30242-7

 DOI:
 https://doi.org/10.1016/j.cad.2017.12.001

 Reference:
 JCAD 2570

To appear in: *Computer-Aided Design*

Received date : 16 June 2016 Accepted date : 7 December 2017



Please cite this article as: Rameau J.-F., Serré P., Moinet M. Clearance vs. tolerance for rigid overconstrained assemblies. *Computer-Aided Design* (2017), https://doi.org/10.1016/j.cad.2017.12.001

This is a PDF file of an unedited manuscript that has been accepted for publication. As a service to our customers we are providing this early version of the manuscript. The manuscript will undergo copyediting, typesetting, and review of the resulting proof before it is published in its final form. Please note that during the production process errors may be discovered which could affect the content, and all legal disclaimers that apply to the journal pertain.

Clearance vs. tolerance for rigid overconstrained assemblies

Jean-François Rameau^{a,b,*}, Philippe Serré^b, Mireille Moinet^b

^aDassault Systèmes, 10 rue Marcel Dassault, 78140 Vélizy-Villacoublay, France ^bQUARTZ, EA7393, 3 rue Fernand Hainaut, 93407 Saint Ouen, France

Abstract

In order to manage quality, companies need to predict performance variations of products due to the manufacturing components deviations. Usually, to enable the assembly of overconstrained mechanical structure, engineers introduce clearance inside joints. We call mechanical assembly, a set of undeformable components connected together by mechanical joints. This paper presents a solution: firstly, to compute the minimum value of clearance for any given components sizes, and, secondly, to simulate variation of the minimum clearance value when the components dimensions vary between two limits. To achieve this goal, a regularized closure function G is defined. It depends on dimensional parameters, u, representing components dimensions, on positional parameters, p, representing components positions and on clearance parameters, j, representing mechanical joints clearance. A constrained optimization problem is solved to determine the minimum clearance value. An imaginative solution based on numerical integration of an ordinary differential equation is proposed to show the clearance variation. The method is designed to be used during the preliminary phase of overcontrained assemblies design. An advantage is the small number of input data unlike the tolerance analysis dedicated software.

Keywords:

Clearance, Tolerance, Overconstrained, Assembly

*Corresponding author. Tel.:+33 1 61 62 40 79; fax.: +33 1 70 73 43 88. *Email address:* jfr@3ds.com (Jean-François Rameau)

Preprint submitted to Computer-Aided Design

December 15, 2017

Download English Version:

https://daneshyari.com/en/article/6876447

Download Persian Version:

https://daneshyari.com/article/6876447

Daneshyari.com