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## A network model for the real-time communications of a smart grid prototype

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### ABSTRACT

Within a large-scale distributed (or centralized) smart grid, the communication network is designed to connect multiple power management systems and collect data from hundreds or thousands of power sensors over a large geographical area. Due to the ripple effect of inconsistent communication delays, the network performance becomes a major concern to support power system applications. For example, in a large NSF project Future Renewable Electric Energy Delivery and Management (FREEDM), we implement a smart grid prototype, called the FREEDM Hardware-in-the-loop (HIL) testbed. The Distributed Grid Intelligences (DGIs) in the prototype can group specific peers to exchange the power among the power demands and supplies. But the grouping sometimes is not successful due to the inconsistent delays. In this paper, we present a queueing model to describe the performance of the grouping network that supports the communications among the DGIs in our smart grid prototype. First, we develop a queueing model to describe the communication traffic among the DGIs in the network with different topologies. Second, based on the network model, we analyze the delay performance and illustrate that the model can be used to predict the grouping delays. Third, we have collected extensive experimental data which is used to demonstrate the accuracy of the model. Finally, we have implemented the HIL testbed with the capabilities of integrated real-time communication and power exchange. The network model is used to investigate the influence of the communication inconsistency on the total cycle time of power operations so that new grouping protocols can be designed in the future.

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#### 1. Introduction

The prospect of smart grids (SG) are green, power efficient, and economical to its customers. Many emerging innovations have reached a consensus that the traditional power grids need to be combined with modern data networks, in order to establish a new platform that supports distributed renewable energy devices, electrical measuring sensors, intelligent energy management and control systems, etc. For example, an energy management system is proposed to connect data aggregators with renewable energy devices within the network area (Cecati et al., 2011). A wireless sensor network is used to provide the communications between SG data centers and consumers, and manage residential energy with an optimization-based scheme (Erol-Kantarci and Mouftah, 2011). In smart grids, the stability of an energy management scheme becomes heavily dependent on accurate real-time communications among

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intelligent energy management agencies in residential homes, microgrids, and the main grid (Adika and Wang, 2014).

The existing work contributes a variety of SG platforms to integrate power and communication systems. In the FREEDM project, we build a smart grid testbed, which is a new platform that combines an HIL power system and a real-time communication system. The power system devices are managed by the DGIs that are connected to the communication networks. The DGIs act as intelligent energy management agencies for the power system, while information nodes for the communication networks. The DGI instances are coded on embedded computer boards with processing and communication capabilities. A DGI represents its power device to communicate with other DGI instances or DGI nodes. DGIs being connected in LAN and WAN may be grouped together to meet the power demand and supply requirement. A DGI group may cover a LAN, or a LAN and WAN simultaneously, depending on the location of DGI nodes. When electrical faults isolate a section from the power system, in communicational sense, the section is still connected to and can exchange the information of grid states with other sections in the power system. The realtime and HIL features of the testbed are reflected in the design of both power and communication systems. To implement the concept of HIL

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in the power system, some power devices are implemented by realworld electrical hardware, while other devices are simulated in the Real Time Digital Simulator (RTDS) platform (Meka et al., 2013). To implement the concept of HIL in the communication system for the DGIs, the DGI LANs are implemented by Ethernet switch, while the DGI WAN is simulated in real-time by OPNET, a network simulator program. Within OPNET, there is a system-in-the-loop (SITL) interface that interprets the DGI traffic between real-packet formats and simulated formats (Cai et al., 2013).

There are two major research issues regarding the smart grid communications.

The first issue is how to trade-off the network capacity and scalability for specific interface access scheme or consistent local service rate. In practice, the traditional power line communications (PLC) or fieldbus control systems are used to support smart grid applications. The traditional systems for communication and control are also combined with large-scale data networks to build smart grids. Thus, we need to find specific access schemes at the junctions of traditional systems and data networks.

20 The second issue is how to find a practical solution to model 21 and connect the distributed energy management agencies (e.g., 22 DGIs). The agencies are inter-connected by large-scale and timing-23 inconsistent networks to support many power applications such as 24 dynamic grouping under power demand and supply constraints. 25 For power system applications, the innovative algorithms are based on specific data networks, which must be able to provide 26 27 a communication environment with some timing or delay guar-28 antees, i.e., QoS. Usually, there is inconsistency in the delay among 29 different packets of the same applications. The inconsistency is 30 caused by not only the internal events of communication net-31 works, such as queueing, link failure, and re-routing events, but 32 also the applications of distributed agencies, such as the dynamic 33 grouping.

34 As for our FREEDM testbed, a time-varying set of DGIs dyna-35 mically exchange with each other the power state information. 36 The DGIs form a logically connected group so that the represented 37 power devices can exchange power between the supply and the 38 04 demand. If some group participants (DGI nodes) change, the 39 logical group is altered accordingly, which may even need to cover 40 different networking areas. The DGIs communicate over different 41 networks will cause inconsistent communication delays to the 42 power applications. A direct impact is that it may take too long for 43 the grouping to succeed, and thus no power application can be 44 supported, such as power exchange. 45

In this work, we focus on modeling the communication networks that support the DGI operations. We want to find a practical solution to estimate the queueing time of DGI networks so that the grouping can succeed by adjusting the grouping timer dynamically.

#### 2. Related work

Currently, there are two methods to approach the above communication issues. The first one is to build special communication tunnels for certain I/O ports within a local SG system, or combine such a system with other wide packet switching networks. The second one is to address and connect different power devices unanimously by using various customized Ethernet switching networks.

The first method is for solving specific problems for SG communications, particularly, in medium-voltage grids covering vast and complex suburban geographical areas. If the existing public WANs cannot satisfy the performance requirements, e.g., capacity, security, and stability, one choice is to build a new wide area data network. For such a fast control system, the cost is substantially considerable. The long distance transmission of wireless signals is easily faded by environmental noise (Papadopoulos et al., 2013). Although the PLC technique leaves much to be desired, it indeed has very attractive 67 68 deployment cost in comparison with wireless technology, since the 69 lines are already there. In Lelvesque and Maier (2014), the optical 70 access control is quantified by a metric, i.e., the availability of connected equipment, with a real-world scenario of SG communica-71 72 tion traffic. To solve the problem of QoS degradation on the junction 73 link between a WLAN and an optical network, a QoS control scheme based on cooperative strategy is proposed for real-time SG commu-74 nications (Md Fadlullah et al., 2013). In Galli et al. (2011), the authors 75 elaborate the possible applications of PLC techniques in modern SG. 76

Nowadays, PLC begins to share its dominant field at electrical 77 metering and sensoring grids with other packet switching net-78 79 works. Many advanced meters or sensors have been loaded with real-time Ethernet protocols for local control applications. They 80 have been used to implement the Internet monitoring and 81 management functions for large-scale applications. The commu-82 nication quality of PLC is compromised by its low data rate and 83 electromagnetic compatibility issues. The complex SG system 84 needs to exploit not only the PLC network, but also multiple data 85 communication technologies, either wired or wireless. The PLC 86 also adopts some techniques from data networks. As shown in 87 Yoon et al. (2014), the single-hop PLC transmission is extended to 88 89 be a multi-hop multi-path routing data network. The opportunistic routing mechanism is used to overcome the PLC disadvantages 90 in transmission performance. An actual local Ethernet scheme 91 with processing buses for the field applications in smart substa-92 tions is proposed in Zhao et al. (2015). A purely localized timing 93 synchronization system is implemented to manage various sub-94 station devices on the local Ethernet network. 95 96

The second method is to utilize the Ethernet switching networks for various SG communication needs. There are many standardized protocols for SG applications over the Ethernet, such as DNP3/TCP, Modbus/TCP, and IEC 61850. In Yang et al. (2014), the authors evaluate the performance of a multi-vendor protection 100 scheme based on the IEC 61850-9-2 processing buses in a substa-101 tion LAN with Ethernet mesh transmissions. To solve the problem 102 of interference between home WLAN and Zig-Bee metering, a SG 103 home network is proposed to be a cognitive local network that 104 supports the management of home appliances (Lee et al., 2012). To 105 aggregate the sporadic data of smart meters and sensors in a large-106 scale placement, a WAN is deployed to connect the data fusions, 107 for which the optimal planning is handled by a minimum-cost-108 forwarding-based asynchronous distributed algorithm (Lu and 109 Wen, 2014). 110

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In this work, the proposed network models can be used to 111 facilitate the distributed systems on the communication LAN of 112 substations, because the DGIs are potentially equipped on the substa-113 tion apparatus. The network models can be also migrated into the PLC 114 WAN systems, because the evolved PLC networks are similar to packet 115 switching networks. Based on the above-related work, it is clear that 116 the design of SG distributed systems can be relied on the supportive 117 Ethernet technologies either in LAN or in WAN. 118

#### 3. The SG prototype: FREEDM real-time HIL testbed

The SG prototype is shown in Fig. 1, which is our testbed for the 124 FREEDM project. It can be seen that the power system has multiple 125 rings hanged up on a large power transmission loop, which is 126 sketched as a double straight line at the top of Fig. 1. The prototype 127 is built with two grids, as shown by Grid\_1 and Grid\_2, each with a 128 ring topology. The communication system is implemented by two 129 130 Ethernet packet switching LANs, and a real-time simulated Gigabit IP-131 routing WAN. The LAN is a geographically deployed Gigabit switching network. 132

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