

Accepted Manuscript

Adaptive Generation of Challenging Scenarios for Testing and Evaluation of Autonomous Vehicles

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PII: S0164-1212(17)30254-6
DOI: [10.1016/j.jss.2017.10.031](https://doi.org/10.1016/j.jss.2017.10.031)
Reference: JSS 10060



To appear in: *The Journal of Systems & Software*

Received date: 4 February 2017
Revised date: 13 October 2017
Accepted date: 25 October 2017

Please cite this article as: Galen E. Mullins, Paul G. Stankiewicz, R. Chad Hawthorne, Satyandra K. Gupta, Adaptive Generation of Challenging Scenarios for Testing and Evaluation of Autonomous Vehicles, *The Journal of Systems & Software* (2017), doi: [10.1016/j.jss.2017.10.031](https://doi.org/10.1016/j.jss.2017.10.031)

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Highlights

- A novel framework for generating test cases for autonomous vehicles is proposed.
- Adaptive sampling significantly reduces the number of simulations required.
- Adjacency clustering identifies performance boundaries of the system.
- Approach successfully applied to complex unmanned underwater vehicle missions.

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