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Regularity criteria for the three dimensional Ericksen-Leslie system in homogeneous Besov spaces

Zujin Zhang

School of Mathematics and Computer Science, Gannan Normal University, Ganzhou 341000, Jiangxi, PR China

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ABSTRACT

In this paper, we establish some regularity criteria involving homogeneous Besov spaces for both the simplified and the general three dimensional Ericksen-Leslie system. This improves many previous results, and can be viewed as the ultimate optimal regularity criterion in the Besov space framework.

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1. Introduction

The hydrodynamic theory of liquid crystals was initialled by Ericksen and Leslie [1-4]. Due to its complexity, Lin-Liu [5]introduced the standard penalty approximation to simplify it as

$$\begin{cases} \partial_t \boldsymbol{u} + (\boldsymbol{u} \cdot \nabla)\boldsymbol{u} - \Delta \boldsymbol{u} + \nabla \boldsymbol{P} = -\nabla \cdot [\nabla \boldsymbol{d} \odot \nabla \boldsymbol{d}], \\ \partial_t \boldsymbol{d} + (\boldsymbol{u} \cdot \nabla)\boldsymbol{d} = \Delta \boldsymbol{d} - \boldsymbol{f}(\boldsymbol{d}), \\ \operatorname{div} \boldsymbol{u} = \boldsymbol{0}, \\ (\boldsymbol{u}, \boldsymbol{d})|_{t=0} = (\boldsymbol{u}_0, \boldsymbol{d}_0), \end{cases}$$
(1)

where $\boldsymbol{u} = (u_1, u_2, u_3)^t$ is the fluid velocity field, $\boldsymbol{d} = (d_1, d_2, d_3)^t$ models the (averaged) macroscopic/continuum molecule orientation, P is the pressure arising from the usual assumption of incompressibility div u = 0, and

$$\boldsymbol{f}(\boldsymbol{d}) = \frac{1}{\eta^2} (|\boldsymbol{d}|^2 - 1) \boldsymbol{d}, \quad (\nabla \boldsymbol{d} \odot \nabla \boldsymbol{d})_{ij} = \partial_i d_k \partial_j d_k$$
(2)

with $\eta > 0$. Here and hereafter, we shall use the summation convention over repeated indices.

The global existence of a weak solution and the local-in-time strong solutions to (1) was already estimated in [5]. However, the global regularity remains unanswered. Fan–Guo [6] first showed the following two fundamental Serrin type regularity criteria involving \boldsymbol{u} or $\nabla \boldsymbol{u}$:

$$\boldsymbol{u} \in L^p(0,T;L^q(\mathbb{R}^3)), \quad \frac{2}{p} + \frac{3}{q} = 1, \quad 3 < q \leq \infty,$$
(3)

$$\nabla \boldsymbol{u} \in L^p(0,T; L^q(\mathbb{R}^3)), \quad \frac{2}{p} + \frac{3}{q} = 2, \quad \frac{3}{2} < q \leq \infty,$$
(4)

E-mail address: zhangzujin361@163.com.

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with the margin cases $\boldsymbol{u} \in L^2(0, T; L^{\infty}(\mathbb{R}^3))$ and $\nabla \boldsymbol{u} \in L^1(0, T; L^{\infty}(\mathbb{R}^3))$ extended to be

$$\boldsymbol{u} \in L^2(0,T; \dot{B}^0_{\infty,\infty}(\mathbb{R}^3)), \quad \nabla \boldsymbol{u} \in L^1(0,T; \dot{B}^0_{\infty,\infty}(\mathbb{R}^3))$$
(5)

by Fan–Ozawa [7]. Here, $\dot{B}_{p,q}^{s}(\mathbb{R}^{3})$ with $s \in \mathbb{R}$ and $1 \leq p, q \leq \infty$ is the homogeneous Besov spaces, one is referred to [8] for definitions, fine properties and its utilization in fluid dynamical systems.

The first purpose of this paper is to show an intermediate regularity criterion.

Theorem 1. Let $u_0 \in H^1(\mathbb{R}^3)$ with div $u_0 = 0$, $d_0 \in H^2(\mathbb{R}^3)$. Assume that (u, d) is the corresponding local smooth solution pair to (1) on [0, T). If additionally,

$$\boldsymbol{u} \in L^{\frac{z}{1+r}}(0,T;\dot{B}^{r}_{\infty,\infty}(\mathbb{R}^{3}))$$
(6)

for some 0 < r < 1, then the solution can be extended smoothly past T.

Remark 2. The margin case r = 0 or r = 1 is just (5), which was shown in [7]. This is why we call our result is intermediate.

The main idea in proving Theorem 1 is the following trilinear estimates, which could have its own interest.

Lemma 3. For
$$f \in B^{r}_{\infty,\infty}(\mathbb{R}^{3})$$
, $g, h \in H^{1}(\mathbb{R}^{3})$ and any $\varepsilon > 0$, $0 < r < 1$, $k \in \{1, 2, 3\}$, we have

$$\int_{\mathbb{R}^3} \partial_k f \cdot gh \, \mathrm{d}\, x \leqslant C \|f\|_{\dot{B}^r_{\infty,\infty}}^2 \|(g,h)\|_{L^2}^2 + \varepsilon \|\nabla(g,h)\|_{L^2}^2. \tag{7}$$

Proof.

$$\begin{split} \int_{\mathbb{R}^{3}} \partial_{t} f \cdot gh \, dx &= -\int_{\mathbb{R}^{3}} f \cdot \partial_{k}(gh) \, dx = -\int_{\mathbb{R}^{3}} \Lambda^{r} f \cdot \Lambda^{-r} \partial_{k}(gh) \, dx \quad \left(\Lambda = (-\Delta)^{\frac{1}{2}}\right) \\ &\leq C \left\|\Lambda^{r} f\right\|_{\dot{B}_{\infty,\infty}^{0}} \left\|\Lambda^{-r} \partial_{k}(gh)\right\|_{\dot{B}_{1,1}^{0}} \quad (by [8, \text{Proposition 2.29}]) \\ &\leq C \left\|f\right\|_{\dot{B}_{\infty,\infty}^{r}} \left(\|g\|_{L^{2}}\|h\|_{\dot{B}_{1,1}^{1-r}} + \|g\|_{\dot{B}_{2,1}^{1-r}}\|h\|_{L^{2}}\right) \\ &\qquad (by \text{ analogues of } [8, \text{Corollary 2.54}]) \\ &\leq C \left\|f\right\|_{\dot{B}_{\infty,\infty}^{r}} \left(\left\|g\right\|_{L^{2}}\|h\|_{\dot{B}_{2,\infty}^{r}}\|h\|_{\dot{B}_{2,\infty}^{1-r}} + \|g\|_{\dot{B}_{2,\infty}^{r}}\|g\|_{\dot{B}_{2,\infty}^{1-r}}\|h\|_{L^{2}}\right) \\ &\qquad (by [8, \text{Proposition 2.22}]) \\ &\leq C \left\|f\|_{\dot{B}_{\infty,\infty}^{r}} \left(\|g\|_{L^{2}}\|h\|_{L^{2}}^{1-r} + \|g\|_{L^{2}}^{r}\|\nabla g\|_{L^{2}}^{1-r}\|h\|_{L^{2}}\right) \\ &\qquad (by [8, \text{Proposition 2.39}]) \\ &\leq C \left\|f\|_{\dot{B}_{\infty,\infty}^{r}} \|(g,h)\|_{L^{2}}^{1+r} \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &\leq C \left\|f\|_{\dot{B}_{\infty,\infty}^{r}} \|(g,h)\|_{L^{2}}^{2+r} \varepsilon \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &= C \left\|f\|_{\dot{B}_{\infty,\infty}^{r}}^{\frac{1+r}{2}} \|gh\|_{L^{2}}^{1+r} \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &\leq C \left\|f\|_{\dot{B}_{\infty,\infty}^{r}}^{\frac{1+r}{2}} \|(g,h)\|_{L^{2}}^{2+r} \varepsilon \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &= C \|f\|_{\dot{B}_{\infty,\infty}^{r}}^{\frac{1+r}{2}} \|gh\|_{L^{2}}^{1+r} \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &\leq C \|f\|_{\dot{B}_{\infty,\infty}^{r}}^{\frac{1+r}{2}} \|(g,h)\|_{L^{2}}^{2+r} \varepsilon \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &= C \|f\|_{\dot{B}_{\infty,\infty}^{r}}^{\frac{1+r}{2}} \|gh\|_{L^{2}}^{1+r} \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &\leq C \|f\|_{\dot{B}_{\infty,\infty}^{r}}^{1+r} \|gh\|_{L^{2}}^{1+r} \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &\leq C \|f\|_{\dot{B}_{\infty,\infty}^{r}}^{1+r} \|gh\|_{L^{2}}^{1+r} \|\nabla (g,h)\|_{L^{2}}^{1-r} \\ &\leq C \|f\|_{L^{2}}^{1+r} \|gh\|_{L^{2}}^{1+r} \|gh\|_{L^{2}}^{1+r} \|gh\|_{L^{2}}^{1} \|gh\|_{L^{2}}^{1+r} \|gh\|_{$$

When $\eta \rightarrow 0^+$, system (1) reduces to

$$\begin{cases} \partial_t \boldsymbol{u} + (\boldsymbol{u} \cdot \nabla) \boldsymbol{u} - \Delta \boldsymbol{u} + \nabla \boldsymbol{P} = -\nabla \cdot (\nabla \boldsymbol{d} \odot \nabla \boldsymbol{d}), \\ \partial_t \boldsymbol{d} + (\boldsymbol{u} \cdot \nabla) \boldsymbol{d} = \Delta \boldsymbol{d} + |\nabla \boldsymbol{d}|^2 \boldsymbol{d}, \\ \operatorname{div} \boldsymbol{u} = 0, \quad |\boldsymbol{d}| = 1, \\ (\boldsymbol{u}, \boldsymbol{d}_0)|_{t=0} = (\boldsymbol{u}_0, \boldsymbol{d}_0). \end{cases}$$
(8)

This system recently attracts many authors' attention. Fan–Guo [6] showed the fundamental Serrin type regularity criterion:

$$\mathbf{u} \in L^{p}(0, T; L^{q}(\mathbb{R}^{3})), \quad \frac{2}{p} + \frac{3}{q} = 1, \quad q > 3,$$

$$\nabla \mathbf{d} \in L^{r}(0, T; L^{s}(\mathbb{R}^{3})), \quad \frac{2}{r} + \frac{3}{s} = 1, \quad s > 3.$$

$$(9)$$

Later on, Fan–Gao–Guo [9] established the following two blow-up criteria:

$$\boldsymbol{u}, \, \nabla \boldsymbol{d} \in L^2(0, T; \dot{B}^0_{\infty,\infty}(\mathbb{R}^3)), \tag{10}$$

$$\boldsymbol{\omega} \stackrel{\text{def}}{=} \nabla \times \boldsymbol{u}, \ \Delta \boldsymbol{d} \in L^1(0, T; \dot{B}^0_{\infty,\infty}(\mathbb{R}^3)).$$
(11)

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