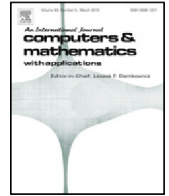




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A regularity criterion for a generalized Hall-MHD system

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ABSTRACT

This paper proves a regularity criterion for a 3D generalized Hall-MHD system in terms of velocity gradient in negative Besov spaces.

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1. Introduction

In this paper, we consider the following 3D generalized Hall-MHD system:

$$\partial_t u + u \cdot \nabla u + \nabla \left(\pi + \frac{1}{2} |b|^2 \right) + (-\Delta)^\alpha u = b \cdot \nabla b, \quad (1.1)$$

$$\partial_t b + u \cdot \nabla b - b \cdot \nabla u + (-\Delta)^\beta b + \operatorname{rot}(\operatorname{rot} b \times b) = 0, \quad (1.2)$$

$$\operatorname{div} u = \operatorname{div} b = 0, \quad (1.3)$$

$$(u, b)(\cdot, 0) = (u_0, b_0) \quad \text{in } \mathbb{R}^3. \quad (1.4)$$

Here u , π and b denote the velocity, pressure and magnetic field of the fluid, respectively. $0 < \alpha, \beta$ are two constants. The fractional Laplacian operator $(-\Delta)^\alpha$ is defined through the Fourier transform, namely, $(-\Delta)^\alpha f(\xi) = |\xi|^{2\alpha} \hat{f}(\xi)$.

The applications of the Hall-MHD system cover a very wide range of physical objects, for example, magnetic reconnection in space plasmas, star formation, neutron stars, and geo-dynamo.

When the Hall effect term $\operatorname{rot}(\operatorname{rot} b \times b)$ is neglected, the system (1.1)–(1.4) reduces to the well-known generalized MHD system, which has received many studies [1–4].

When $\alpha = \beta = 1$, the system (1.1)–(1.4) reduces to the well-known Hall-MHD system. The paper [5] gave a derivation of the isentropic Hall-MHD system from a two-fluid Euler–Maxwell system. Chae–Degond–Liu [6] proved the local existence of smooth solutions. Chae and Schonbek [7] showed the time-decay and some regularity criteria were proved in [8,9].

Local well-posedness is established in [10] when $0 < \alpha \leq 1$ and $\frac{1}{2} < \beta \leq 1$ even for u_0 and b_0 in different spaces.

When $\frac{3}{4} \leq \alpha < \frac{5}{4}$ and $1 \leq \beta < \frac{7}{4}$, Jiang and Zhu [11] prove the following regularity criteria

$$\nabla b \in L^t(0, T; L^s) \quad \text{with} \quad \frac{2\beta}{t} + \frac{3}{s} \leq 2\beta - 1, \quad \frac{3}{2\beta - 1} < s \leq \infty, \quad (1.5)$$

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and one of the following two conditions

$$u \in L^p(0, T; L^q) \quad \text{with} \quad \frac{2\alpha}{p} + \frac{3}{q} \leq 2\alpha - 1, \quad \frac{3}{2\alpha - 1} < q \leq \frac{6\alpha}{2\alpha - 1}, \quad (1.6)$$

or

$$\Lambda^\alpha u \in L^p(0, T; L^q) \quad \text{with} \quad \frac{2\alpha}{p} + \frac{3}{q} \leq 3\alpha - 1, \quad \frac{3}{3\alpha - 1} < q \leq \frac{6\alpha}{3\alpha - 1}. \quad (1.7)$$

When $1 \leq \alpha < \frac{5}{4}$ and $1 \leq \beta < \frac{7}{4}$, Ye [12] showed the following regularity criterion

$$u \in L^p(0, T; L^q) \quad \text{and} \quad \nabla b \in L^\ell(0, T; L^k),$$

where p, q, ℓ and k satisfy the relation

$$\frac{2\alpha}{p} + \frac{3}{q} \leq 2\alpha - 1, \quad \frac{2\beta}{p} + \frac{3}{q} \leq 2\beta - 1, \quad \frac{2\beta}{\ell} + \frac{3}{k} \leq 2\beta - 1, \quad (1.8)$$

and

$$\max\left(\frac{3}{2\alpha - 1}, \frac{3}{2\beta - 1}\right) < q \leq \infty, \quad \frac{3}{2\beta - 1} < k \leq \infty.$$

For other related results, we refer to [13–15] and references therein.

Very recently, He–Ahmad–Hayat–Zhou [16] show the following regularity criterion

$$\text{rot } u \in L^{\frac{2\alpha}{2\alpha-2-s_1}}(0, T; \dot{B}_{\infty, \infty}^{-s_1}) \quad \text{with} \quad 0 < s_1 < \min(1, 2\alpha - 2), \quad (1.9)$$

when $1 < \alpha = \beta < \frac{7}{4}$, and the following regularity criterion

$$(-\Delta)^{\frac{m-1}{2}} \text{rot } u \in L^2(0, T; L^2) \quad \text{with} \quad m > \frac{7}{2}, \quad (1.10)$$

as $\alpha = \beta = 1$. As far as we know, it is the first work to establish regularity criteria only on the velocity field u .

The aim of this paper is to prove a new regularity criterion, we will prove the following theorem.

Theorem 1.1. Let $0 < \alpha < \frac{5}{4}$ and $\frac{7}{4} \leq \beta < 3$ and $u_0, b_0 \in H^s$ with $s \geq 2$ and $\text{div } u_0 = \text{div } b_0 = 0$ in \mathbb{R}^3 . If ∇u satisfy

$$\nabla u \in L^{\frac{2\alpha}{2\alpha-\gamma}}(0, T; \dot{B}_{\infty, \infty}^{-\gamma}), \quad \text{with} \quad 0 < \gamma < 2\alpha, \quad (1.11)$$

then the solution (u, b) can be extended beyond T .

In the following proofs, we will use the following bilinear product and commutator estimates due to Kato–Ponce [17]:

$$\| \Lambda^s(fg) \|_{L^p} \leq C(\| \Lambda^s f \|_{L^{p_1}} \| g \|_{L^{q_1}} + \| f \|_{L^{p_2}} \| \Lambda^s g \|_{L^{q_2}}), \quad (1.12)$$

$$\| \Lambda^s(fg) - f \Lambda^s g \|_{L^p} \leq C(\| \nabla f \|_{L^{p_1}} \| \Lambda^{s-1} g \|_{L^{q_1}} + \| \Lambda^s f \|_{L^{p_2}} \| g \|_{L^{q_2}}), \quad (1.13)$$

with $s > 0$, $\Lambda := (-\Delta)^{\frac{1}{2}}$ and $\frac{1}{p} = \frac{1}{p_1} + \frac{1}{q_1} = \frac{1}{p_2} + \frac{1}{q_2}$.

We will also use the improved Gagliardo–Nirenberg inequalities [18–20]:

$$\| \nabla u \|_{L^3}^3 \leq C \| \nabla u \|_{\dot{B}_{\infty, \infty}^{-\gamma}} \| \nabla u \|_{\dot{H}^{\frac{\gamma}{2}}}^2, \quad (1.14)$$

$$\| \nabla u \|_{L^{\frac{2(k+\gamma+\alpha-1)}{\gamma}}} \leq C \| \nabla u \|_{\dot{B}_{\infty, \infty}^{-\gamma}}^{\frac{k+\alpha-1}{k+\gamma+\alpha-1}} \| \nabla u \|_{\dot{H}^{k+\alpha-1}}^{\frac{\gamma}{k+\gamma+\alpha-1}}, \quad (1.15)$$

$$\| \Lambda^k u \|_{L^{\frac{4(k+\gamma+\alpha-1)}{2k+\gamma+2\alpha-2}}} \leq C \| \nabla u \|_{\dot{B}_{\infty, \infty}^{-\gamma}}^{\frac{\gamma}{2(k+\gamma+\alpha-1)}} \| \Lambda^k u \|_{\dot{H}^{\frac{2k+\gamma+2\alpha-2}{2(k+\gamma+\alpha-1)}}}^{\frac{\gamma(k+\gamma-1)}{2k+\gamma+2\alpha-2}}, \quad (1.16)$$

for $k > 0$, $0 < \gamma < \alpha$. Some more efficient inequalities was used in [21–23].

2. Proof of Theorem 1.1

This section is devoted to the proof of Theorem 1.1, we only need to prove a priori estimates.

First, testing (1.1) by u and using (1.3), we see that

$$\frac{1}{2} \frac{d}{dt} \int |u|^2 dx + \int |\Lambda^\alpha u|^2 dx = \int (b \cdot \nabla) b \cdot u dx.$$

Testing (1.2) by b and using (1.3), we find that

$$\frac{1}{2} \frac{d}{dt} \int |b|^2 dx + \int |\Lambda^\beta b|^2 dx = \int (b \cdot \nabla) u \cdot b dx.$$

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