

Accepted Manuscript

Scheduling last-mile deliveries with truck-based autonomous robots

Nils Boysen, Stefan Schwerdfeger, Felix Weidinger

PII: S0377-2217(18)30477-6
DOI: [10.1016/j.ejor.2018.05.058](https://doi.org/10.1016/j.ejor.2018.05.058)
Reference: EOR 15171



To appear in: *European Journal of Operational Research*

Received date: 1 August 2017
Revised date: 23 May 2018
Accepted date: 27 May 2018

Please cite this article as: Nils Boysen, Stefan Schwerdfeger, Felix Weidinger, Scheduling last-mile deliveries with truck-based autonomous robots, *European Journal of Operational Research* (2018), doi: [10.1016/j.ejor.2018.05.058](https://doi.org/10.1016/j.ejor.2018.05.058)

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Highlights

- We consider a novel last-mile concept relying on autonomous robots.
- A novel scheduling problem for launching robots from trucks is derived.
- Efficient solution procedures for this problem are provided.
- We benchmark the novel concept with traditional truck deliveries.

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