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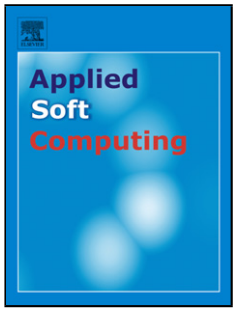

Title: Continuous Greedy Randomized Adaptive Search Procedure for data clustering

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PII: S1568-4946(18)30419-8
DOI: https://doi.org/doi:10.1016/j.asoc.2018.07.031
Reference: ASOC 4999

To appear in: *Applied Soft Computing*

Received date: 19-2-2018
Revised date: 7-7-2018
Accepted date: 13-7-2018

Please cite this article as: Eduardo Queiroga, Anand Subramanian, Lucídio dos Anjos F. Cabral, Continuous Greedy Randomized Adaptive Search Procedure for data clustering, *<![CDATA[Applied Soft Computing Journal]]>* (2018), https://doi.org/10.1016/j.asoc.2018.07.031

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We propose a novel algorithm based on continuous GRASP for cluster analysis

Computational experiments were carried out in well-known datasets

The results show that the proposed algorithm is robust and highly competitive

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