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## ACCEPTED MANUSCRIPT

# Six sigma robust multi-objective optimization modification of machine-tool settings for hypoid gears by considering both geometric and physical performances

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#### Highlights

- $6\sigma$  robust optimization formulation to evaluate machine-tool setting modification.
- MOO modification mode considering the both geometric and physical performances.
- $6\sigma$  robust MOO machine-tool setting modification for the hypoid gears.
- A data-driven decision and optimization process to get the accurate computation.

#### Abstract:

With the increasing demands of low noise and high strength from gear transmission system in industry applications, a collaborative optimization considering both geometric and physical performances has been increasingly significant for high-performance complex manufacturing of the hypoid gears. More recently, the machine-tool setting modification has provided an important access to this optimization design. However, its data-driven robustness or reliability is of a great difficulty. To deal with this problem, this paper presents a six sigma ( $6\sigma$ ) robust multi-objective optimization (MOO) modification of machine-tool settings. Firstly, the  $6\sigma$  robust optimization formulation is applied in the numerical result evaluations. Then, a novel data-driven model for MOO modification of machine-tool settings is established by establishing the functional relationships between the machine-tool setting modification for hypoid gears having higher quality requirements. Finally, with the decision and optimization process, an achievement function approach was applied to solve MOO modification for the Pareto front, and the sensitivity-based variability estimation is used to identify the robust solution. The numerical applications are given to verify the proposed methodology.

**Keywords:** hypoid gears; machine-tool setting modification; multi-objective optimization (MOO); six sigma ( $6\sigma$ ) robust optimization; an achievement function approach.

#### Nomenclature

$6\sigma$ six sigma	
MOO multi-objective optimization	
UMC universal motion concept	
LTCA loaded tooth contact analysis	
SGEs spatial geometric errors	
TCA tooth contact analysis	
UTCA unloaded tooth contact analysis	
eTCA tooth contact analysis with errors	
DTCA dynamic tooth contact analysis	
SOA service-oriented architecture	
DFSS design for six sigma	
ppm parts per million	
$S_{\text{Rob}}$ robust solution	
$S_{\text{Opt}}$ optimal solutions	
$S_0$ the initial design	
$S_i$ the <i>i</i> -th design	
LSL lower performance specification limit	
USL upper performance specification limit	

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