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PSO Tuned FLC for Full Autopilot Control of Quadrotor to Tackle Wind Disturbance Using Bond Graph Approach

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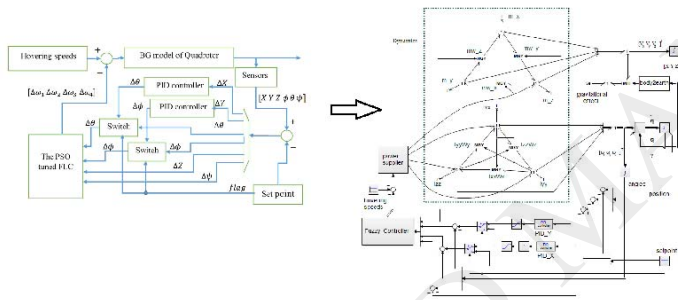
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Graphical abstract



Highlights

- Quadrotor model in bond graph approach is considered
- An FLC-PID controller is proposed for full controlling the quadrotor
- Fuzzy rules are obtained via Particles Swarm Optimization (PSO)
- Gimbal lock problem is eliminated by quaternion equations
- Robustness of the controller against wind disturbance is simulated

Abstract The ability of Bond Graph (BG) in modeling multi-domain structures results in a more precise and expansive interface. Hence, this paper develops the model of a quadrotor using BG approach. Then, the paper introduces and optimizes a Fuzzy Logic Controller (FLC) with the aim of making intelligent decisions close to human decisions. Additionally, a Particle Swarm Optimization (PSO) algorithm is utilized to have minimum 4 rules for FLC, which leads the controller to be quick. It is because a fast FLC is necessary in the next part to convert the

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