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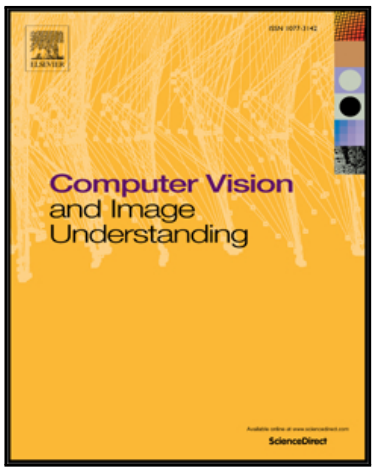

An efficient solution to the perspective-three-point pose problem

Ping Wang, Guili Xu, Zhengsheng Wang, Yuehua Cheng

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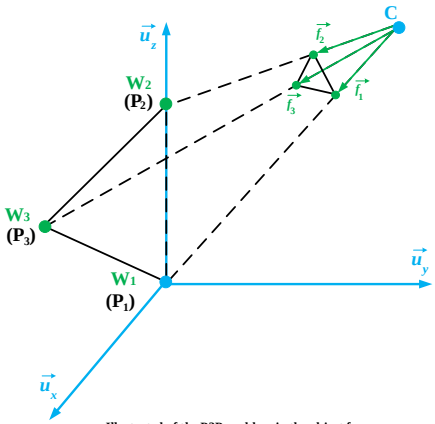
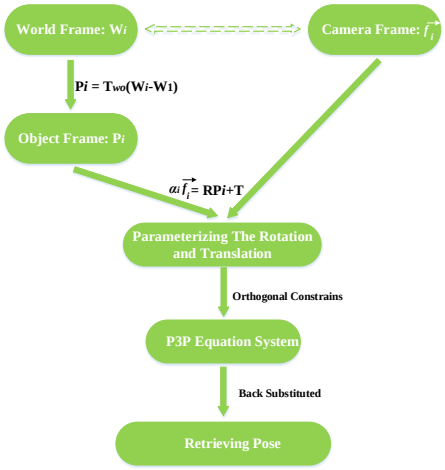
Graphical Abstract



Illustrated of the P3P problem in the object frame



The main frame of proposed approach

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