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A data-driven method to enhance vibration signal decomposition for rolling bearing fault analysis

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ABSTRACT

Health condition analysis and diagnostics of rotating machinery requires the capability of properly characterizing the information content of sensor signals in order to detect and identify possible fault features. Time–frequency analysis plays a fundamental role, as it allows determining both the existence and the causes of a fault. The separation of components belonging to different time–frequency scales, either associated to healthy or faulty conditions, represents a challenge that motivates the development of effective methodologies for multi-scale signal decomposition. In this framework, the Empirical Mode Decomposition (EMD) is a flexible tool, thanks to its data-driven and adaptive nature. However, the EMD usually yields an over-decomposition of the original signals into a large number of intrinsic mode functions (IMFs). The selection of most relevant IMFs is a challenging task, and the reference literature lacks automated methods to achieve a *synthetic* decomposition into few physically meaningful modes by avoiding the generation of spurious or meaningless modes. The paper proposes a novel automated approach aimed at generating a decomposition into a minimal number of relevant modes, called Combined Mode Functions (CMFs), each consisting in a sum of adjacent IMFs that share similar properties. The final number of CMFs is selected in a fully data driven way, leading to an enhanced characterization of the signal content without any information loss. A novel criterion to assess the dissimilarity between adjacent CMFs is proposed, based on probability density functions of frequency spectra. The method is suitable to analyze vibration signals that may be periodically acquired within the operating life of rotating machineries. A rolling element bearing fault analysis based on experimental data is presented to demonstrate the performances of the method and the provided benefits.

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1. Introduction

Sensor signals involved in health condition analysis of rotating machinery usually exhibit a multi-scale information content, due to the superimposition of features on different time–frequency scales, either stationary or non-stationary. Typical rolling bearing faults are caused by localized defects that generate impact vibrations. Thus, time–frequency analysis is a powerful approach to characterize both the time of impacts and the corresponding frequency ranges. Empirical Mode Decomposition (EMD) gained increasing influence in the technical literature to this aim. This kind of analysis relies on a

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Nomenclature			
BSF	Ball Spin Frequency	$m_u(t)$	Mean of envelopes at the u th step of the sifting algorithm
$c_i(t)$	i th IMF extracted from the signal $Y(t)$, $i = 1, \dots, n$	\mathbf{p}	Vector of “locations” k corresponding to peaks in the $D_{k,k+1}$ function
$c_{s_k}(t)$	k th sequential CMF extracted from the signal $Y(t)$, $k = 1, \dots, n$	$\hat{\mathbf{p}}$	Vector \mathbf{p} with elements sorted in descending peak amplitude order
$c_{s_k}^*(t)$	k th final CMF extracted from the signal $Y(t)$, $k = 1, \dots, K$	PDF	Probability density function
CMF	Distance (dissimilarity) between the k th and the $(k+1)$ th IMFs from $Y(t)$	q_k	Number of IMFs included into the k th CMF, $k = 1, \dots, K$
$D_{k,k+1}$	Distance (dissimilarity) between the k th and the $(k+1)$ th IMFs from $Y(t)$	r_i	Normalized sample correlation coefficient between $Y(t)$ and the i th IMF
EMD	Empirical Mode Decomposition	$r_n(t)$	Sum-of-squares between the K^* CMFs from $Y(t)$
EEMD	Ensemble Empirical Mode Decomposition	rms	Sum-of-squares between the K^* CMFs from $Y(t)$
n	Number of IMFs extracted from the signal $Y(t)$	SSB(K^*)	Sum-of-squares between the K^* CMFs from $Y(t)$
$f(x)$	Probability density function of random process $x(t)$	SSW(K^*)	Sum-of-squares within the K^* CMFs from $Y(t)$
$\hat{f}(x)$	Kernel estimator of the probability density function of random process $x(t)$	T	Time window length
F_s	Sampling frequency	tol	Tolerance threshold
FFT	Fast Fourier Transform	UCV	Unbiased Cross Validation
FTF	Fundamental train frequency	$UCV_k(\hat{h})$	Unbiased cross-validation statistic for k th CMF from $Y(t)$, with bandwidth \hat{h}
h	Bandwidth of the kernel function	$w_k(\omega)$	Weight function in the PDF for the k th CMF from $Y(t)$
\hat{h}	Optimal bandwidth of the kernel function	$x_k(\omega)$	Amplitude of frequency spectrum of the k th CMF from $Y(t)$
$h_u(t)$	Difference between the signal $Y(t)$ and $m_u(t)$, at u th step of the sifting algorithm	$Y(t)$	Vibration signal
K^*	Number of iteratively generated CMFs	λ	Threshold used in the index-based approach for IMF selection
K	Final number of CMFs extracted from the signal $Y(t)$	$\rho(\bullet, \bullet)$	Sample cross-correlation coefficient
Ker(x)	Kernel function	ω	Frequency location
IMF	Intrinsic Mode Function		
M	Number of peaks in the $D_{k,k+1}$ function		

decomposition of vibration signals into their embedded modes. Signal decomposition is a critical step that strongly influences the capability of isolating fault features and determining the health condition of the system. The achievement of a good characterization of the multi-scale content of the signal is of great importance to detect and diagnose faulty conditions in order to reduce plant downtime and to rapidly react to performance worsening caused by degraded states of the machine components. Although several multi-resolution techniques may be applied to this aim [1,2], the achievement of a synthetic decomposition into a minimal number of physically meaningful and interpretable oscillation modes still represents an open issue. In some cases, a number of decomposition levels is imposed *a-priori* and the signal is reconstructed by applying level-dependent thresholding techniques [3]. In many practical applications, the signal is first decomposed into a number of scales (usually larger than the one required to describe the relevant content), and a subset of modes of interest is then selected [4–6]. However, this latter approach yields a potential information loss. Furthermore, mode selection may be a troublesome task in practice, being usually based on the human expert’s knowledge and difficult to apply in an automatic way. Among time–frequency analysis techniques, the EMD proposed by Huang et al. [7] has several attractive properties that make it suitable to fault detection and diagnosis problems. The EMD is a nonparametric, data-driven and adaptive method that allows decomposing any signal into a number of Intrinsic Mode Functions (IMFs), without any prior basis selection. Due to its data-driven nature, the number of IMFs may vary over time, when the EMD is applied to periodically acquired signals. As an example, a higher frequency content in vibration signals caused by a defective bearing may lead to a larger number of IMFs than the ones extracted from the signal under healthy conditions, due to increased frequency ranges and energy levels [8]. In addition, the sifting algorithm is known to be affected by the so-called “mode mixing” problem [9], which may cause either a splitting of one intrinsic mode into two (or more) adjacent IMFs, or a merging of different scales into a single IMF. The EMD usually yields an over-decomposition of the signal, which can be inflated by the *mode mixing* effect and/or by the specific choice of the stopping criterion, leading to the presence of IMFs with no physical meaning. The introduction of the Ensemble Empirical Mode Decomposition (EEMD) [9] helped to mitigate mode mixing effects, but the EEMD is not able to avoid the over-decomposition imposed by the sifting algorithm. As a matter of fact, the literature devoted to the EMD and other multi-scale analysis methods lacks automated approaches for the achievement of a synthetic decomposition into a

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