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Low-rank group inspired dictionary learning for hyperspectral image classification

5 Zhi He^{a,*}, Lin Liu^{a,b}, Ruru Deng^c

17 ^a School of Geography and Planning, Center of Integrated Geographic Information Analysis, Sun Yat-sen University (SYSU), Guangzhou 510275, China

^b Department of Geography, University of Cincinnati (UC), Cincinnati 45221, USA
^c School of Geography and Planning, Centre for Remote Sensing and Geographical Information Sciences, Sun Yat-sen University (SYSU), Guangzhou 510275, China

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ABSTRACT

Dictionary learning has yielded impressive results in sparse representation based hyperspectral image (HSI) classification. However, challenges remain for exploiting spectralspatial characteristics. In this paper, we make the first attempt to classify the HSI via lowrank group inspired dictionary learning (LGIDL). Core ideas of the LGIDL are threefold: (1) super-pixel segmentation is implemented to obtain homogeneous regions, which can be viewed as spatial groups for LGIDL; (2) non-negative low-rank coefficient and dictionary are updated alternatively in the optimization problem of LGIDL. The low-rank group prior helps to seek lowest-rank representation of a collection of data samples jointly. Pixels in the same group share common low-rank pattern, which facilitates the integration of spectral-spatial information; (3) the low-rank coefficients of test samples are adopted to determine the corresponding class labels in linear support vector machine (SVM). Experimental results demonstrate that the LGIDL achieves better performance to the state-of-the-art HSI classification methods on several challenging datasets even with small labeled samples.

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43 **1. Introduction**

Hyperspectral imaging sensors capture the radiance of materials from hundreds of contiguous narrow spectral bands, providing rich information for various land covers [1–3]. Due to the significant advances in remote sensing, hyperspectral image (HSI) has attracted extensive attention over the past decade. One of the fundamental tasks for HSI is classification [4–6], which can potentially benefit from the discriminative information contained in high spectral resolution pixels.

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http://dx.doi.org/10.1016/j.sigpro.2015.09.004 0165-1684/© 2015 Published by Elsevier B.V. In HSI classification, sufficient training samples are usually crucial to obtain reliable results due to the curse of dimensionality, i.e. Hughes phenomenon [7]. Unfortunately, the difficulty in determining the class labels of samples poses a great challenge to the classification task. Despite the high spectral resolution of HSI, identical land covers may have quite different spectral signatures, whereas distinct materials may share similar spectral signatures. The above-mentioned problems, together with other disadvantages such as noise from the sensors, will seriously influence the classification accuracy.

To deal with the obstacles described above, several feature extraction/selection [4,8,9] and classification techniques [10,11] have sprung up over the past few years. However, the discriminative information will get lose in case too few dimensions are reserved in feature extraction/selection methods. On

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^{57 *} Corresponding author. Tel.: +86 20 84113057; fax: +86 20 84112593. *E-mail address:* hezh8@mail.sysu.edu.cn (Z. He).

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1 the other hand, a plenty of kernel methods have also been applied to the classification of HSI, among which support vector machine (SVM) [12,13] is a state-of-the-art approach 3 that performs well in high-dimensional data. Many variations of SVM-based methods have been developed to improve the 5 classification performance, including SVM with composite 7 kernel (SVMCK) [14], which combines both spectral and spatial information in kernels, and multiple kernel learning (MKL) [15,16], which enhances the flexibility of kernels in machine 9 learning. However, SVM-based methods are sensitive to para-11 meters selection.

More recently, the sparse representation classifier (SRC) 13 [17–19], which is derived from the compressed sensing. has opened up new avenues for the classification of HSI. 15 Motived by the sparsity prior of HSI, an unknown test sample can be approximately represented by the combi-17 nation of a few training samples from the entire dictionary whereas the corresponding sparse representation vector 19 encodes the class information implicitly. Significant efforts have been carried out in the literature to exploit the 21 inherent structure of neighboring pixels. Typical methods include the joint sparsity model (JSM) [20], group sparse 23 coding (GSC) [21], Laplacian regularized Lasso [22] and collaborative group Lasso [23]. However, the dictionary of 25 SRC is conventionally constructed by all of the training samples, which is inefficient for capturing the crucial 27 class-discriminative information. In this regard, one needs to learn a dictionary from specific training samples.

Much work has been carried out to gain suitable dictionary, and two major categories can be highlighted:

• Determining a dictionary by mathematical mode-based 33 method. Several traditional dictionaries [24], such as Fourier, curvelet, contourlet, bandelet and discrete 35 cosine transform (DCT) based dictionaries, belong to this category. Those methods characterize the diction-37 ary by analytic formulations and fast implementations. However, the dictionaries are fixed and cannot repre-39 sent the high-dimensional HSI adaptively.

Learning a dictionary to perform best on the training 41 samples. Many dictionary learning methods have been proposed to learn a compact and discriminative dic-43 tionary, which include the method of optimal directions (MOD) [25], K-Singular Value Decomposition (K-SVD) [26] and online dictionary learning [27]. To incorporate 45 the contextual information, the learning vector quanti-47 zation (LVQ) [28] based dictionary are customized for patch-based SRC, whereas the spatial-aware dictionary 49 learning (SADL) [29] method is designed by dividing the pixels of HSI into a number of contextual groups. Those 51 methods are flexible to adapt to specific data and gaining popularity in recent years. However, the spar-53 sity criterion fails to capture global structure of the data, and the HSI is forcibly partitioned into many squared patches, which ignores the dissimilarity of different

55 neighboring pixels. 57

Moreover, the low-rank representation (LRR), which is 59 initially presented by Liu et al. [30,31], has achieved great success in various applications, including subspace clus-61 tering [31], objective detection [32], image classification

[33], etc. Specifically, LRR has also drawn great attention in 63 the HSI community. The spatial structure of the abundance vectors is exploited by LRR model in [34]. Low-rank prior 65 [23] is enforced on the coefficient matrix to obtain more 67 flexible and significant performance than joint sparsity prior. A maximum a posteriori (MAP) framework is con-69 structed upon LRR for hyperspectral segmentation in [35]. Low-rank constraint [36] is employed to exploit the global redundancy and correlation (RAC) in spectral domain for 71 HSI denoising. Low-rank reconstruction is incorporated in 73 [37] to obtain a robust domain adaptation method for semi-supervised classification of remote sensing image.

75 In this paper, a low-rank group inspired dictionary learning (LGIDL) method is proposed for HSI classification. 77 We integrate a low-rank group term to sparse representation for dictionary learning: (1) principle component 79 analysis (PCA) is employed to obtain the first principle component (PC1) and a fast super-pixel segmentation 81 method [38] is implemented on the PC1 to obtain homogeneous regions, which can be taken as spatial groups for 83 LGIDL; (2) an optimization problem is constructed to alternatively update the non-negative low-rank coefficient 85 by inexact augmented Lagrange multiplier (IALM) [31,39] and the dictionary by block coordinate descent (BCD) 87 strategy [40]; (3) notably that the low-rank coefficients are discriminative enough, a linear SVM is trained to classify 89 each test sample. As will be shown later, the pixels in the same group are able to incorporate both spectral and 91 spatial characteristics, and the low-rank group prior in the optimization problem facilitates to capture the global 93 structure of HSI, providing an effective strategy for dictionary learning in HSI classification. 95

The main contributions of this paper are as follows:

• We apply a fast super-pixel segmentation method to gain spatial groups in more natural forms.¹

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• We propose a LGIDL method to learn structured dictionary for capturing global structure of the HSI.

The layout of this paper is as follows. Section 2 103 describes the proposed LGIDL together with its optimization strategies. Experimental results are discussed in Sec-105 tion 3, and conclusions are drawn in Section 4. Moreover, the acronyms used in this paper are summarized in Table 1 107 for convenience.

2. The proposed LGIDL method

2.1. Construction of spatial groups

Notably that pixels within a small contextual patch 115 usually consist of similar land covers, a fast super-pixel segmentation approach [38] is employed to over-segment 117 the PC1 into homogenous regions, which can be viewed as the spatial groups for LGIDL. The super-pixel segmentation 119 can not only provide spatial groups for the subsequent dictionary learning step but also detect much more flexible 121

¹ As opposed to artificial shapes.

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