



# Churning losses analysis on the thermal-hydraulic model of a high-speed electro-hydrostatic actuator pump

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## ABSTRACT

The speed of Electro-Hydrostatic Actuator (EHA) pump can recently reach a maximum of 20,000 rpm due to its high power density requirements. The thermodynamics of EHA pumps become increasingly important because the oil in the casing is used to cooling the high speed electric motor and solving the “hot spots” problem in the EHA system. In order to realize the boundary condition for the motor cooling at high speeds, more investigations should be given to the churning losses in terms of the large centrifugal forces of piston/cylinder assemblies and high fluid kinetic energy in high-speed conditions. This paper analyzes the influence of churning losses on the thermal-hydraulic model. Using the control volume method, heat transfer analysis of the piston pump is presented and the heat flow inside the piston pump produced by churning losses is described in details. The steady-state leakage temperatures of the high-speed EHA pump are simulated and validated through experiments. The experimental results show that the churning power losses need to be considered on the thermal-hydraulic model to ensure good performance for the prediction of the leakage temperature in EHA pump.

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## 1. Introduction

The Electro-Hydrostatic Actuator (EHA) has been successfully applied to More Electric Aircraft (MEA) to replace inefficient and centralized hydraulic systems [1–3]. As shown in Fig. 1, the EHA system consists of an electrically controlled pump, several check valves, an accumulator and a hydraulic actuator forming a closed circuit. The hydraulic fluid is used to move the hydraulic actuator of primary flight control surfaces in the EHA system, the velocity and direction of hydraulic actuator are controlled by the fluid flow from an electric motor driven hydraulic pump called EHA pump [4–6].

Fig. 2 shows a typical configuration of an EHA pump rotating group consisting of a valve plate, a cylinder block, nine pistons, nine slippers, a swash plate, a retainer mechanism, several bearings and a shaft. The pistons are arranged in a circular array within the block at equal angular intervals along the shaft centerline. The piston heads are mounted in the slippers. Under the limitation of the swash plate and retainer mechanism, pistons periodically reciprocate within the cylinder block bores suctioning and discharging oil through a valve plate which is fixed to the pump casing.

The EHA system has significant advantages, such as weight saving, high efficiency and improved maintainability. However, the closed circuit of an EHA system could cause the localized “hot spots” such as high-power motor because the EHA system removes the effective heat transfer network in the centralized hydraulic system [7,8]. The high temperature of the motor in the EHA system accelerates ageing of the winding insulation material, and the insulation performance of the material is greatly reduced. The service life of the motor is significantly reduced, which might cause the motor on fire and the electric shock hazard. Therefore, the EHA pump rotating group moves in a casing filled with oil and shaft is hollow as shown in Fig. 2. And the high-speed motor is cooled by the leakage oil in the casing of the EHA pump to reduce the high temperature of the motor. In order to solve thermal equilibrium of the high-speed motor in the EHA system, the leakage temperature of EHA pump is needed to be obtained as the boundary condition.

Theoretical and experimental studies have been carried out on the thermal-hydraulic models to investigate the leakage temperature in EHA pumps [9–14]. Andersson et al. firstly analyzed the thermodynamic model of hydraulic components and simulated the temperature of EHA systems in the HOPSAN simulation package [9,10]. Power losses including the volumetric and mechanical losses were considered in the mathematical model. Sidders et al. developed a set of lumped parameter mathematical models based

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## Nomenclature

$A_{fw}$	area of fluid/wall heat transfer ( $m^2$ )	$R_1$	inside radius of the inner region of the sealing land on the valve plate (m)
$A_{wa}$	area of wall/air heat transfer ( $m^2$ )	$R_2$	outside radius of the inner region of the sealing land on the valve plate (m)
$C_d$	drag coefficient related to the Reynolds number	$R_3$	inside radius of the outer region of the sealing land on the valve plate (m)
$c_p$	specific heat ( $J/kg \cdot ^\circ C$ )	$R_4$	outside radius of the outer region of the sealing land on the valve plate (m)
$\bar{c}_p$	mean value of specific heat ( $J/kg \cdot ^\circ C$ )	$R_5$	inner radius of auxiliary support on the valve plate (m)
$D$	displacement of the pump ( $m^3/r$ )	$R_6$	outer radius of auxiliary support on the valve plate (m)
$d_1$	diameter of the piston (m)	$R_c$	radius of the cylinder block (m)
$d_2$	outer diameter of sealing land at the bottom of slipper (m)	$\bar{T}$	mean value of temperature ( $^\circ C$ )
$d_3$	inner diameter of sealing land at the bottom of slipper (m)	$T$	temperature ( $^\circ C$ )
$E$	sum of the internal energy, the kinetic energy and the potential energy (J)	$T_a$	temperature in the air ( $^\circ C$ )
$\dot{E}$	rate of $E$ (J/s)	$T_{in}$	temperature in the oil tank ( $^\circ C$ )
$h$	specific enthalpy (J/kg)	$T_l$	temperature in the leakage node ( $^\circ C$ )
$h_{in}$	enthalpy of mass which enters the control volume (J/kg)	$T_t$	temperature in the inlet fluid node ( $^\circ C$ )
$h_{out}$	enthalpy of mass which leaves the control volume (J/kg)	$T_w$	temperature of the mass node ( $^\circ C$ )
$KE$	kinetic energy (J)	$T_p$	temperature in the outlet fluid node ( $^\circ C$ )
$k_{fw}$	coefficient of fluid/wall heat transfer ( $W/m^2 \cdot ^\circ C$ )	$t$	time (s)
$k_{wa}$	coefficient of wall/air heat transfer ( $W/m^2 \cdot ^\circ C$ )	$t_1$	gap between the piston and cylinder block (m)
$l_0$	length of the piston out of the cylinder block (m)	$t_2$	gap between the slipper and swash plate (m)
$l_1$	length of the piston guide in cylinder block (m)	$t_3$	gap between the cylinder block and valve plate (m)
$l_c$	length of the cylinder block (m)	$t_4$	gap between the cylinder block and the housing internal surface (m)
$L_p$	additional power losses of per revolution (J/r)	$U$	internal energy (J)
$m$	mass of the internal energy (kg)	$u$	internal energy of per mass (J/kg)
$\dot{m}_{in}$	rate of mass which enters the control volume (kg/s)	$V$	control volume ( $m^3$ )
$\dot{m}_{out}$	rate of mass which leaves the control volume (kg/s)	$V_l$	volume in the leakage fluid node ( $m^3$ )
$m_l$	mass of the leakage node (kg)	$V_p$	volume in the outlet fluid node ( $m^3$ )
$m_p$	mass of the outlet node (kg)	$V_t$	volume in the inlet fluid node ( $m^3$ )
$m_t$	mass of the inlet node (kg)	$\dot{W}$	rate of work done by the control volume (J/s)
$m_w$	mass of the mass node (kg)	$\dot{W}_b$	rate of boundary work (J/s)
$n$	rotational speed of shaft (rpm)	$\dot{W}_s$	rate of shaft work (J/s)
$PE$	potential energy (J)	$z$	number of pistons
$P_c$	churning losses in the casing filled with oil (W)	$\alpha$	reduction coefficient of the multi-pistons
$P_{cc}$	churning losses power due to the cylinder block (W)	$\alpha_p$	volume expansion coefficient of the control volume ( $m^3/^\circ C$ )
$P_{cp}$	churning losses power due to the piston/slipper units (W)	$\bar{\alpha}_p$	mean value of volume expansion coefficient of the control volume ( $m^3/^\circ C$ )
$P_{cv}$	viscous friction losses of the cylinder block/valve plate pair (W)	$\rho$	fluid density ( $kg/m^3$ )
$P_{pc}$	viscous friction losses of the piston/cylinder block pair (W)	$\gamma$	swashplate angle ( $^\circ$ )
$P_{ps}$	viscous friction losses of the piston/slipper pair (W)	$\mu$	dynamic viscosity of oil (Pa·s)
$P_v$	viscous friction losses of three friction pairs (W)	$\nu$	specific volume of the control volume ( $m^3/kg$ )
$p$	pressure (Pa)	$\bar{\nu}$	mean value of specific volume ( $m^3/kg$ )
$p_l$	pressure in the leakage node (Pa)	$\omega$	angular velocity of shaft (rad/s)
$p_p$	pressure in the outlet fluid node (Pa)	$\eta_m$	mechanical efficiency of axial piston pump
$p_t$	pressure in the inlet fluid node (Pa)	$\eta'_m$	modified mechanical efficiency of axial piston pump
$\dot{Q}$	rate of heat transfer (J/s)	$\theta_1$	wrap angle of auxiliary support on the valve plate (rad)
$Q_{il}$	internal leakage flow rate ( $m^3/s$ )	$\varphi_0$	sealing angle of the valve plate (rad)
$Q_{el}$	external leakage flow rate ( $m^3/s$ )		
$R$	pitch circle radius of piston bores (m)		

on conservation of mass and energy for the hydraulic system [11]. After that, Jiao et al. presented a kind of modeling approach to study the thermal-hydraulic piston pump used in the EHA system [12–14]. Heat transfer analysis of the EHA pump was also performed and the heat flow inside the EHA pump was described in detail in the model. However, heat generation of high-speed EHA pump comes from not only the power losses of friction pairs but also the churning losses caused by the internal rotating components stirring the hydraulic fluid in the casing. Although a considerable amount of research has been devoted to the thermal-

hydraulic model of EHA pumps in terms of power losses, little information is available on the churning losses because its effect is minor for pumps with the nominal speeds of 1500–3000 rpm [15–18]. With an increasing speed, the proportion of churning losses in axial piston pumps gradually increases, especially for high-speed EHA pumps. In general, the EHA pump is characterized as a very small displacement so that it can be easily mounted next to or even the inside actuator. However, an EHA system usually needs a large flow to drive hydraulic actuators with good speeds. It means that a very high rotating speed is required for the EHA

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