



## Review

## Analytical determination of oscillating frequencies and onset temperatures of standing wave thermoacoustic heat engines



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## ABSTRACT

This paper determines analytically the oscillating frequency and onset temperature of a simple standing wave thermoacoustic heat engine as eigenvalues of wave problem. The method to treat is based on the linear theory of thermoacoustics and the analytical solution of wave equation. The influence of geometrical parameters such as stack position, stack length, engine total length, and the influence of operational parameters such as charge pressure, on the oscillating frequency and onset temperature for four different working gases of Hydrogen, Helium, Nitrogen and Argon are investigated. Moreover, the eigenvalues are calculated for binary gas mixtures of four mentioned gases.

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## 1. Introduction

Thermoacoustics was qualitatively described about 130 years ago by Rayleigh [1] with the following statements about air oscillations inside a tube: “at the phase of greatest condensation heat is

received by the air, and at the phase of greatest rarefaction heat is given up from it, and thus there is a tendency to maintain the vibrations.” This was the basis of the twenty’s century researches which quantitatively studied thermoacoustic phenomena. The first main mathematical description of thermoacoustic effects was presented by Rott in 1969 [2]. He developed the mathematics describing the acoustic oscillations in a gas in a channel with an axial temperature gradient, with lateral channel dimensions of the order of the gas thermal penetration which are much shorter than the

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### Nomenclature

$A$	cross-sectional area	$u$	velocity
$a$	speed of sound	$x_L$	position of left end of stack
$B$	matrix of coefficients	$x_R$	position of right end of stack
$C_p$	isobaric specific heat	$x$	longitude coordinate
$C_s$	specific heat of solid	$y_0$	half of plate spacing
$C_v$	specific heat at constant volume		
$E$	total energy flow	<i>Greek letters</i>	
$f_v$	Rott's viscous function	$\alpha$	thermal diffusivity
$f_k$	Rott's thermal function	$\gamma$	specific heat ratio
$i$	imaginary unit	$\delta_k$	thermal penetration depth
$Im$	imaginary part	$\delta_v$	viscous penetration depth
$J_0$	Bessel function of zeroth order	$\mu$	dynamic viscosity
$J_1$	Bessel function of first order	$\xi$	gas–solid capacity ratio
$k$	thermal conductivity	$\rho$	density
$L$	length	$\phi$	porosity
$l$	half of plate thickness	$\omega$	oscillating frequency
$L_S$	length of stack	$\nu$	kinematic viscosity
$L_R$	length of resonator		
$M$	molecular mass	<i>Subscripts</i>	
$P$	pressure	0	mean value
$P_{ch}$	charge pressure	1	acoustic value
$Pr$	Prandtl number	S	solid
$R$	gas constant		
$Re$	real part	<i>Superscripts</i>	
$r_0$	radius of engine	' (dot)	time derivative
$T$	temperature	*	complex conjugate
$t$	time		
$U$	volume flow rate		

wavelength. Subsequently, from 1973 to 1983, Rott presented several articles under various aspects of "Thermally Driven Acoustic Oscillations". Since 1983, Swift [3,4] has extensively promoted the quantitative and qualitative description of thermoacoustic phenomena and utilities based on the Rott's researches. Afterwards, many researchers have studied thermoacoustic systems (standing wave, traveling wave, and cascade).

Onset of the self-excitation of a thermoacoustic device is of the most interesting phenomena to be investigated along with its two key characteristics: onset temperature of hot source and first mode natural frequency. Like all the heat engines, a thermoacoustic engine works with the temperature difference between the hot source and the cold sink at the two sides of the stack. Initiating the oscillations in the thermoacoustic engine requires a critical temperature gradient along the stack. Fixing the cold end of the stack at ambient temperature, there is a lower limit of the hot-end temperature of the stack, at which self-excited oscillations occur and growth toward a stable condition with natural frequency. This temperature and corresponding heat input are usually called the onset temperature and the onset heat input, respectively. The stability limit is expressed in an amount of heat, or a temperature difference in the engine, for which neutrally stable oscillations can exist. Summarily, oscillation frequency and onset temperature are two basic characteristics of thermoacoustic oscillations in relevant engines for which three main categories of experimental, analytical and numerical procedure are implemented.

Frequency of oscillations can be achieved experimentally, numerically, and analytically. To calculate the frequency of oscillations, analytically, Tu et al. [5] proposed a network method based on the principle of the impedance matching at components interfaces. The method is straightforward, but leads to a complex frequency value which has no solid physical background. Later, Dai

et al. [6] introduced a simple method for frequency calculation through numeric investigation. According to their iterative method, frequency can be decided if it leads to an inflection point of the amplitude of volume flow rate, which is also a local minimum, most close to the volume flow rate node boundary. Compared with experimental data, the method proved to be very reliable.

Onset temperature is of great importance besides the frequency because the hot end temperature of stack must be controlled below the overheating temperature of solid materials (mostly about 900 K) due to safety requirements. Experimental works were done on the onset and damping processes of the oscillation in standing wave [7], traveling wave [8], and cascade [9] thermoacoustic engines. The effects of different working gases on the performance and onset characteristics of a solar powered standing wave thermoacoustic engine and a small traveling wave thermoacoustic engine were investigated experimentally by Shen et al. [10] and by Chen et al. [11], respectively. Hariharan et al. experimentally studied the influence of operational and geometrical parameters on the performance of a twin thermoacoustic heat engine and compared the results to the results attained by DeltaEC [12–14]. The impact of regenerator hydraulic radius, resonator length, and the mean pressure on the characteristics of a looped traveling wave thermoacoustic heat engine is investigated by Yu et al. [15]. The experimental results indicate that the ratio of penetration depth over hydraulic radius plays an important role in the excitation and pressure amplitude of the two acoustic modes and there is a measured optimal relative penetration depth, which leads to the lowest onset temperature difference.

A.T.A.M. de Waele [16] treated the basic onset and damping features of the traveling-wave thermoacoustic engines. By the assumption of the constant hot-end temperature, A.T.A.M. de Waele described the dynamics of the system by a fourth-order

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