## Accepted Manuscript

Title: Fabrication of flexible tactile force sensor using conductive ink and silicon elastomer

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PII:	S0924-4247(15)30212-0
DOI:	http://dx.doi.org/doi:10.1016/j.sna.2015.10.051
Reference:	SNA 9390
To appear in:	Sensors and Actuators A
Received date:	31-8-2015
Revised date:	29-10-2015
Accepted date:	30-10-2015

Please cite this article as: Chullhee Cho, Youngsun Ryuh, Fabrication of flexible tactile force sensor using conductive ink and silicon elastomer, Sensors and Actuators: A Physical http://dx.doi.org/10.1016/j.sna.2015.10.051

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## ACCEPTED MANUSCRIPT

## Fabrication of flexible tactile force sensor using conductive ink and silicon elastomer

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