



Review

Assessing punching shear failure in reinforced concrete flat slabs subjected to localised impact loading

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ARTICLE INFO

Article history:

Received 2 September 2013

Received in revised form

27 February 2014

Accepted 6 April 2014

Available online 19 April 2014

Keywords:

Punching shear

Flat slabs

Impact loading

Strain-rate effects

Critical shear crack theory

ABSTRACT

Reinforced concrete flat slab structures are used widely in construction projects due to their economic and functional advantages. Punching shear failure in such structures can have catastrophic effects in the case of, for example, multi-storey framed structures and the designer aims to ensure that ductile flexural deformation occurs before the brittle shear failure.

Shear mechanisms generally govern the behaviour of reinforced concrete structures subjected to localised impact loads. Existing experimental results investigating punching shear in flat slabs subjected to impact loading shows that when increasing the loading rate, the punching shear strength also increases whereas the deformation capacity reduces. This behaviour is due to a combination of inertial effects and material strain-rate effects which leads to a stiffer behaviour of the slab for higher loading rates. This can also lead to a change of mode of failure from flexural to pure punching shear with increasing loading rates. Current empirical formulae for punching shear are unable to predict this behaviour since the slab deformations are not considered for calculating the punching shear strength.

This paper presents an analytical model based on the Critical Shear Crack Theory which can be applied to flat slabs subjected to impact loading. This model is particularly useful for cases such as progressive collapse analysis and flat slab-column connections subjected to an impulsive axial load in the column. The novelty of the approach is that it considers (a) the dynamic punching shear capacity and (b) the dynamic shear demand, both in terms of the slab deformation (slab rotation). The model considers inertial effects and material strain-rate effects although it is shown that the former has a more significant effect. Moreover, the model allows a further physical understanding of the phenomena and it can be applied to different cases (slabs with and without transverse reinforcement) showing a good correlation with experimental data.

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1. Introduction

1.1. High-rate loading

The design of most reinforced concrete (RC) structures is typically governed by ultimate limit state performance of the various structural elements when subjected to static loading, e.g. dead (or permanent) loads and live (or imposed or variable) loads. Whilst the former are typically static in nature (e.g. structure's self-weight, finishes etc.), the magnitude of live loading tends to be variable with time (e.g. pedestrian or vehicular traffic loading). However, in most cases, such loadings can be idealised as quasi-static, since the rate at which this loading is applied, typically described by the strain-rate, $\dot{\epsilon}$, is of a very small magnitude.

Fig. 1 gives typical ranges of strain-rates for different loading sources.

Dynamic loads are often also idealised as being quasi-static or replaced by equivalent static loadings but in the case of extreme events, such as blast or impact loading, such simplifications could be inadequate and further consideration is necessary [2]. Reliable structural modelling is essential to accurately predict the response and damage in structures subjected to loads at high strain-rates. The effects of strain-rate effects can be considered on two levels, viz. the effects on the material properties of the structure's constituents and the effects on the response of the structure itself.

1.2. Effect of strain-rate on material properties

The effect of strain-rate on the mechanical properties of most engineering materials is well-known. This includes the

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Nomenclature		Latin upper case	
<i>Latin lower case</i>		\bar{A}_x	projected contact areas in the X direction for an unit crack area, [–]
a	penetration constant, [T ⁻²]	\bar{A}_y	projected contact areas in the Y direction for an unit crack area, [–]
b	penetration constant, [L ⁻²]	A	impactor section pressure, [M L ⁻¹ T ⁻²]
b_0	punching control perimeter, [L]	E_c	concrete elastic modulus, [M L ⁻¹ T ⁻²]
c_1	tension softening constant, [–]	E_s	steel reinforcement elastic modulus, [M L ⁻¹ T ⁻²]
c_2	tension softening constant, [–]	G_c	concrete shear modulus, [M L ⁻¹ T ⁻²]
c_{s0}	slab initial damping co-efficient, [M T ⁻¹]	G_f	fracture energy, [M T ⁻²]
c_s	slab damping co-efficient, [M T ⁻¹]	G_{f0}	reference fracture energy, [M T ⁻²]
d_g	concrete maximum aggregate size, [L]	K	material constant, [M ⁻¹ L ² T ²]
d_{g0}	reference concrete aggregate size, [L]	L_{eff}	slab effective span, [L]
d_v	shear-resisting slab effective depth, [L]	M_{Rd}	unit slab flexural capacity, [M L T ⁻²]
d	slab effective depth, [L]	M_{sd}	unit slab bending moment, [M L T ⁻²]
f_c	concrete compressive strength, [M L ⁻¹ T ⁻²]	N	crack normal force component, [M L T ⁻²]
f_{c0}	reference concrete compressive strength, [M L ⁻¹ T ⁻²]	$P(t)$	contact force, [M L T ⁻²]
f_{ct}	concrete tensile strength, [M L ⁻¹ T ⁻²]	\dot{P}	loading rate, [M L T ⁻³]
f_y	steel reinforcement yield stress, [M L ⁻¹ T ⁻²]	P^*	section limiting load, [M L T ⁻²]
g	acceleration due to gravity, [L T ⁻²]	R_i	impactor radius, [L]
h_i	drop height of impactor, [L]	S	crack shear force component, [M L T ⁻²]
h_s	slab thickness, [L]	V	penetration velocity, [L T ⁻¹]
k_c	contact stiffness, [M T ⁻²]	V^*	velocity factor, [–]
k_{s0}	slab initial stiffness, [M T ⁻²]	V_0	impactor initial velocity, [L T ⁻¹]
k_s	slab stiffness, [M T ⁻²]	V^*	velocity constant, [L T ⁻¹]
m_i	mass of impactor, [M]	V_d	shear force, [M L T ⁻²]
m_{s0}	slab initial mass, [M]	V_R	punching shear strength, [M L T ⁻²]
m_s	slab mass, [M]	X	penetration depth, [L]
r_c	column radius, [L]	\ddot{X}	penetration acceleration, [L T ⁻²]
r_s	position of zero bending moment with respect to support axis, [L]	<i>Greek lower case</i>	
r_{s0}	initial position of zero bending moment during contact time, [L]	β	shear modulus retention factor, [–]
t	time, [T]	γ	concrete dilatation angle, [–]
t_c	contact time, [T]	δ	crack separation, [L]
t_E	time to peak response, [T]	$\dot{\epsilon}$	strain-rate, [T ⁻¹]
$u_i(t)$	impactor displacement, [L]	μ	co-efficient of friction, [–]
$\dot{u}_i(t)$	impactor velocity, [L T ⁻¹]	ν	Poisson's ratio, [–]
$\ddot{u}_i(t)$	impactor acceleration, [L T ⁻²]	ρ	flexural reinforcement ratio, [–]
$u_s(t)$	slab displacement, [L]	ρ_c	concrete density, [M L ⁻³]
$\dot{u}_s(t)$	slab velocity, [L T ⁻¹]	ρ_v	shear reinforcement ratio, [–]
$\ddot{u}_s(t)$	slab acceleration, [L T ⁻²]	σ_{ca}	concrete aggregate interlock normal stress, [M L ⁻¹ T ⁻²]
v_c	concrete shear wave velocity, [L T ⁻¹]	σ_{ct}	concrete tensile stress, [M L ⁻¹ T ⁻²]
w	crack width, [L]	σ_p	cement paste plasticisation stress, [M L ⁻¹ T ⁻²]
w_c	maximum crack width, [L]	τ_{ca}	concrete aggregate interlock shear stress, [M L ⁻¹ T ⁻²]
		$\varphi(x)$	slab deformed configuration shape function, [–]
		ϕ	reinforcement bar diameter, [L]
		ψ	slab rotation, [–]
		ψ_R	slab rotation at failure, [–]

constituents of RC structures, namely the concrete and the steel reinforcement.

1.2.1. Concrete properties

It has been shown by many researchers (e.g. Refs. [3–11]) that the tensile and compressive strengths of concrete both increase with loading rate. A very comprehensive review of experimental data in this respect has been carried out by Cotsovos and Pavlović [12].

The 1990 and 2010 Model Codes [1,13,14] provide relationships which give the increase in strength and modulus with strain-rate.

These relationships are valid for strain rates up to 300/s covering low to moderate impacts. The increases in compressive (f_c) and tensile (f_t) strengths are given by (1) and (2) respectively as:

$$\frac{f_{c,dynamic}}{f_{c,static}} = \begin{cases} \left(\frac{\dot{\epsilon}}{30 \times 10^{-6}}\right)^{0.014}, & \dot{\epsilon} \leq 30/s \\ 0.012 \left(\frac{\dot{\epsilon}}{30 \times 10^{-6}}\right)^{\frac{1}{3}}, & 30/s \leq \dot{\epsilon} \leq 300/s \end{cases} \quad (1)$$

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