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# Failure mechanism dependence and reliability evaluation of non-repairable system

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**Abstract:** Reliability study of electronic system with physics-of-failure method has been promoted due to the increase knowledge of electronic failure mechanisms. System failure initiates from independent failure mechanisms, have effect on or affect by other failure mechanisms and finally result in system failure. Failure mechanisms in a non-repairable system have many kinds of correlation. One failure mechanism developing to a certain degree will trigger, accelerate or inhibit another or many other failure mechanisms, some kind of failure mechanisms may have the same effect on the failure site, component or system. The destructive effect will be accumulated and result in early failure. This paper presents a reliability evaluation method considering correlativity among failure mechanisms, which includes trigger, acceleration, inhibition, accumulation, and competition. Based on fundamental rule of physics of failure, decoupling methods of these correlations are discussed. With a case, reliability of electronic system is evaluated considering failure mechanism dependence.

**Keywords:** failure mechanism dependence; trigger; acceleration; reliability evaluation; non-repairable system

## Nomenclature

$M_i$	the $i_{th}$ mechanism	$\Delta X$	accumulated damage in unit time
$t_i$	the failure time of $M_i$	$F(t)$	failure probability function of system
$F$	system failure	$F_i(t)$	failure probability function of $M_i$
$\zeta$	system lifetime	$f_i(t)$	failure density function of $M_i$
$X_{th}$	the threshold of system due to damage	$T_{tr}$	trigger time
$X_{M_{ith}}$	the threshold of damage caused by $M_i$	$F_{tr}(t)$	failure probability function of $T_{tr}$
$X_{M_i}(t)$	damage that $M_i$ brings to the system and varies with time $t$	$f_{tr}(t)$	failure density function of $T_{tr}$
$\Delta X_i$	damage in unit time due to $M_i$		

## 1 Introduction

Failure dependence has been extensively treated in reliability modeling for complicated system in aerospace, aviation, naval and nuclear power plants system. For example, a two-component parallel system, when one of the components fails, the stress places on the surviving component will change. Dependent failure will increase joint-failure probabilities, and then reduce system reliability<sup>[1]</sup>. Thus, for many complicated system, a modeling approach incorporating dependent failure resembles the true system reliability behavior in a more realistic manner.

Failure dependence exists in different levels of real-life system, these levels includes system level, component level and failure process or failure mechanism level. On system or component level, considerable research efforts have been devoted to modeling common cause failure (CCF), which is defined as a subset of dependent failures in which two or more component functional fault states exist at the same time, or within a short interval, as a result of a shared cause. For example, Jose and Coit<sup>[2]</sup>proposed three different reliability optimization models for redundancy system subject to CCF and results show that the consideration of common cause failures will lead to different optimal design strategies.

Levitin<sup>[1]</sup> believes that CCFs of a system may cause by external cause as well as internal cause. Failures caused by common internal cause are called propagated failures. And for a component, the failure can be classified

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