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Computational simulation of manufacturing processes

Some insights on the modelling of chip formation and its morphology during metal cutting operations

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ABSTRACT

The present paper deals with the mechanisms of chip formation during cutting operations. It deals with some experiments characterising the chip morphologies and microstructure chip investigations under high loadings. In this contribution, mechanisms of chip segmentation are presented. The effect of cutting conditions on cutting forces is treated. Consequently, the chip segmentation phenomenon was correlated to cutting forces evolutions. Also, an investigation on chip strain localisation is carried out. Numerical simulations dealing with chip formation and considering thermomechanical phenomena are also presented. Some numerical results related to chip formation based on the theory of strain gradient plasticity are also discussed. Moreover, the effect of machining system stiffness on chip segmentation is analysed.

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1. Introduction

In the framework of machining, it is essential to have predictive approaches helping to complement the knowledge necessary for a comprehensive and industrial understanding of the process. There are various experimental methods dedicated to cutting studies in terms of tool wear investigation [1,2], evolution of cutting forces, etc. In particular the investigation of chip formation such as the quick-stop testing, temperature measurement systems or methods of chip visualisation were proposed, etc. However, these methods have limitations because of their costs and also because of difficulties in providing a comprehensive and relevant understanding.

It is important to note that analytical cutting models are still essentially driving from experimentation. Some parameters and coefficients of these experimental models are obtained with tests codified both by the scientific community and the industrial sector concerned. Measurement methods are standardised to allow their transmission and their interchangeability. Analytical cutting models of a two-dimensional representation (orthogonal case) are elaborated for these experimental scientific approaches. These empirical analytical models are usually defined for a given Couple Workpiece/Tool

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Nomenclature

List of symbols		$\sigma_{\rm n}$	Normal stress (MPa)
A	Initial vield stress (MPa)	$\bar{\varepsilon}_{0i}$	Plastic strain at damage initiation
a _n	Cutting depth or axial depth of cut (mm)	$\dot{\bar{\varepsilon}}^{\mathrm{p}}$	Plastic strain rate (s ⁻¹)
B	Hardening modulus (MPa)	$\dot{\bar{\varepsilon}}_{0}^{p}$	Reference strain rate (10^{-3} s^{-1})
b	Burgers vector (nm)	$\bar{\sigma}$	von Mises plastic equivalent stress (MPa)
С	Strain rate dependency coefficient	σ_{v}	Yield stress (MPa)
C_{eq}	Equivalent linear damping of machining sys-	$ au_{ m f}$	Friction shear stress (MPa)
	tem $(kg s^{-1})$	$\bar{\sigma}_{\rm IC}$	Johnson–Cook equivalent stress (MPa)
C_p	Specific heat $(J kg^{-1} K^{-1})$	$\tau_{\rm V}$	Yield shear stress (MPa)
Ď	Overall damage variable	λ	Edge inclination angle (deg)
$D_1 \dots D_s$	5 Coefficients of Johnson-Cook material shear	α_{t}	Taylor's constant
	failure initiation criterion	α_0	Flank/clearance angle (deg)
D_{T}	Tool diameter in milling (mm)	νο	Rake/cutting angle (deg)
Ε	Young's modulus (MPa)	χr	Edge entering angle (deg)
f	Feed rate (mm/rev)	u n	Friction coefficient
Fi	Cutting force (N) along various axis ($i = axial$,	ω	Damage initiation criterion
	radial, tangential)	r.	Insert radius (mm)
G	Shear modulus (MPa)	ζ _{ασ}	Fourivalent damping ratio of the machining
G_{f}	Fracture energy (N/m)	Seq	system
K _C	Fracture toughness (MPa \sqrt{m})	n	Strain gradient coefficient
K _r	Insert attack angle or entering angle (deg)	יי ג	Thermal conductivity $(Wm^{-1}K^{-1})$
k_{eq}	Equivalent linear stiffness of machining system	~	Density of the material (kgm^{-3})
	(N/m)	р х	Comparing factor defining the density of CND
1	Intrinsic characteristic length of the cut mate-	X	Poisson's ratio
	rial	ν	
L _C	Tool rake face-chip contact length (µm)	List of ab	breviations
т	Thermal softening coefficient	AIF	Arbitrary Lagrangian-Fulerian formulation
m_{eq}	Equivalent moving mass (kg)	CWT	Couple Workpiece/Tool
Ν	Spindle rotation frequency (rev/min)	FF	Finite Element
п	Work-hardening exponent	Fa .	, Chin segmentation measured by gathering
Р	Hydrostatic pressure (MPa)	¹ Seg-signa	signal (Hz)
r_{β}	Tool hone edge radius (µm)	Frag and	Chin segmentation measured on chin mor-
T T	Temperature at a given calculation instant (°C)	1 Seg-geo	phology (Hz)
I _m	Melting temperature (°C)	CND	Ceometrically Necessary Dislocation
10	Room temperature (°C)	HDC	Hybrid Dynamic Cutting model
u _	Equivalent plastic displacement (mm)		Johnson, Cook
$u_{\rm f}$	Equivalent plastic displacement at failure	rom	Pevolution per minute
	(mm)	rpin sc	Strain Cradient
Δu	Relative displacement of spring element (mm)	3G UCT	Stidli Giduleit
VC	Cutting speed (m/min)		Mith aut
$P/\sigma_{\rm JC}$	Stress triaxiality	w/u סר	Without Two dimensional model
Е ^н	Equivalent plastic strain		rwo unnensional model
\mathcal{E}_{f}	Equivalent plastic strain at failure	P52 667	Chip Frimary Shear Zone
$\Delta \mathcal{E}^{P}$	Equivalent plastic strain increment	33Z	Chip Secondary Snear Zone

(*CWT*) methodology [3] and are exploited to obtain a range of optimal cutting parameters with a minimum of experiments. Nevertheless, it is underlined that cutting experimentation is always costly, due to the need for specialised equipment such as dynamometers, accelerometers, and data acquisition systems. Generally, a complete *CWT* is accomplished when it is necessary to determine ranges of cutting parameters for achieving a given quality criteria or a production cost function.

In this context, the simulation of machining processes appears to be an important approach to control and monitor operating cutting parameters. Developing a machining numerical model for predictive purposes, based on a physical understanding, is possible only through proper comprehension of thermomechanical phenomena occurring during the toolworkpiece interaction [4]. Imperfect knowledge of certain physical effects on this interaction constitutes a real obstacle to the development of a robust numerical simulation of processes. From a numerical point of view, the modelling of machining is referring to the theory of finite transformation considering both thermomechanical coupling and also tribological phenomena during the dynamic cutting process. According to the literature, three approaches can be adopted in machining modelling. Definitions and boundaries of these approaches are not always in agreement within the scientific community:

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