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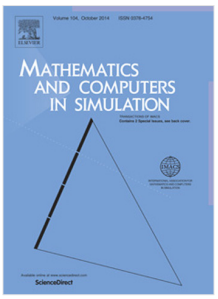

High performance rigid body simulation of modularized robots using constraint-based models

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PII: S0378-4754(17)30274-4
DOI: http://dx.doi.org/10.1016/j.matcom.2017.07.003
Reference: MATCOM 4478

To appear in: *Mathematics and Computers in Simulation*

Received date : 23 June 2016
Revised date : 10 May 2017
Accepted date : 13 July 2017

Please cite this article as: L. Sobehart, H. Harada, High performance rigid body simulation of modularized robots using constraint-based models, *Math. Comput. Simulation* (2017), http://dx.doi.org/10.1016/j.matcom.2017.07.003

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