



Entropy generation-based computational geometry optimization of the pore structure of high-conductivity graphite foams for use in enhanced heat transfer devices



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ABSTRACT

A computational fluid dynamics-based shape optimization process is employed to determine a pore-level geometry for high-conductivity graphitic foams which is optimal with respect to the criterion of entropy generation minimization, under operating conditions relevant to the implementation of such a foam in an enhanced heat transfer device. The optimization procedure is applied to a single pore, subject to operating conditions which reflect a typical pore in the bulk of the foam, far removed from the influences of the macroscopic boundaries of the porous region. Constraints are imposed upon the geometry to ensure the pore structure arrived at may be manufactured by a reasonable process, and to ensure the validity of the analysis. The optimal, ellipsoidal pore geometry obtained is found to achieve a significant reduction in the resistance to convective thermal exchange between constituents, at the cost of an increased resistance to fluid flow.

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1. Introduction

In recent years, there has been a great deal of interest in the use of high-porosity, high-conductivity, open-celled foams in enhanced heat transfer devices. These materials are attractive for such devices because they provide a large amount of exposed surface area for convective heat transfer in a given volume, resulting in designs which may be much lighter and more compact than those based upon conventional extended surfaces. At the same time, the high effective solid constituent thermal conductivities of such foams minimize the resistance to thermal diffusion through their interconnected solid constituents. Accordingly, high-conductivity foams have found a variety of application in the field of enhanced heat transfer, including heat exchangers for aircraft and heat sinks for electronic devices, where compactness and light weight of the thermal management system are of key importance [1]. In the present work, we are particularly concerned with high-conductivity graphite foams of the type illustrated in Fig. 1(c) [2,3]. The interfacial surface area between solid and fluid constituents, per unit volume, arising from the pore-level geometry of such a foam is typically much greater than that found in foams based upon aluminum or other metals [3]. Similarly, the

effective solid constituent thermal conductivities of presently available graphite foams are typically much larger than those found for other metal foams, due to the extremely high material conductivity of the graphitized carbon matrix [4]. As a result of the high solid constituent effective thermal conductivity, the resistance to thermal diffusion through the solid matrix of graphite foams tends to be very small. However, the large exposed surface area per unit volume and the characteristics of the pore-level geometries of presently available high-conductivity graphitic foams also lead to a generally strong resistance to fluid flow through the foam, so that large pressure gradients are often required to induce the desired flow rates.

Considering the recent study of Straatman et al. [3], in which the hydrodynamic and thermal performance of simple heat exchangers based upon a variety of graphite foams were compared with previous results for aluminum foam devices, it is evident that a substantial potential exists for the improvement of presently available graphitic foams. Though the graphite foams considered by Straatman et al. [3] possess solid constituent effective thermal conductivities which are typically greater than those of the comparison aluminum foams by an order of magnitude or more, greatly reducing the resistance to diffusion of heat through the pore structure, the heat dissipated by the aluminum foams under identical conditions is often similar. At the same time, the pressure drops observed in the graphitic foams are in all cases much greater, so that the pore-level geometry of the graphitic foam results both

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Nomenclature

a	spherical pore radius (m)	\mathbf{u}	fluid velocity $\mathbf{u} = u_i \mathbf{e}_i$ (m/s)
a_i	ellipsoid semi-axis length in x_i direction (m)	U	mean inlet velocity (m/s)
a_{sf}	specific surface area (m^{-1})	$\hat{\mathbf{u}}$	advecting velocity (m/s)
A	area (m^2)	V	averaging volume or general volume (m^3)
A_{sf}	interfacial surface area within averaging volume (m^2)	\mathbf{x}	Cartesian coordinates $\mathbf{x} = x_i \mathbf{e}_i$ (m)
b	cube side half-length (m)	\mathbf{X}	mapping function (m)
b_i	hexahedron side half-length in x_i direction (m)	$\langle \rangle$	denotes volume averaging
Be	Bejan number		
Bi	Biot number		
c_p	constant pressure specific heat (J/kg K)	Greek symbols	
d	pore-level length scale (m)	δ	characteristic grid spacing (m)
\mathbf{d}	line search direction vector	δ_{∇}	tolerance for satisfaction of critical point criterion
d_{eq}	equivalent spherical diameter (m)	δ_{feas}	tolerance for satisfaction of feasibility criteria
D	averaging volume length scale (m)	ε	porosity of porous medium
\mathbf{D}	vector between associated periodic points (m)	$\tilde{\gamma}$	penalty parameter
$\bar{\mathbf{D}}$	diagonal mapping matrix	Γ	diffusion coefficient
\mathbf{e}_i	Cartesian unit vector in direction x_i	φ	general scalar, vector, or tensor function
\mathbf{e}_i^{κ}	unit vector in direction κ_i	ϕ	vector of dependent variables
Ec	Eckert number	Φ	viscous dissipation function (s^{-2})
f_i	constraint function defining feasible region	$\boldsymbol{\kappa}$	vector of optimization parameters
\mathbf{H}^{-1}	positive definite estimate to inverse of objective function Hessian tensor	$\bar{\boldsymbol{\kappa}}$	optimal point in space of optimization parameters
k	thermal conductivity (W/m K)	$\boldsymbol{\kappa}'$	critical point in space of optimization parameters
J	general objective function	$\Delta\boldsymbol{\kappa}_i$	finite difference step size for calculation of derivatives with respect to κ_i
\hat{J}	augmented objective function	λ	line search step size
\dot{m}	mass flow rate	$\boldsymbol{\Lambda}$	scaling matrix
\mathbf{n}	outward normal unit vector	μ	kinematic viscosity (kg/m s)
N_{opt}	number of optimization parameters	η	ratio of ellipsoid semi-axis length to corresponding hexahedron side half-length
N_S'''	local volumetric entropy generation number	Ψ	advective flux limiter
\bar{N}_S	total average entropy generation number	$\theta, \bar{\theta}$	dimensionless temperature
Nu_{sf}	interfacial Nusselt number	Θ	dimensionless heat load
P	fluid pressure (Pa)	ρ	density (kg/m^3)
Pr	Prandtl number	Ω	spatial domain in three dimensions (m^3)
q	rate of heat transfer (W)	$\Omega_{\boldsymbol{\kappa}}$	feasible region
\mathbf{q}''	heat flux vector (W/m^2)	$\partial\Omega$	area bounding Ω (m^2)
q'''	volumetric heat load (W/m^3)	$\partial\Omega_{\boldsymbol{\kappa}}$	boundary of feasible region
Re_1	Reynolds number based on streamwise semi-axis length	Subscripts and superscripts	
$Re_{int,1}$	Reynolds number based on intrinsic velocity and streamwise semi-axis length	<i>bind</i>	boundary node
$Re_{int,23}$	Reynolds number based on intrinsic velocity and transverse semi-axis length	<i>f</i>	fluid constituent
s	specific entropy (J/kg K)	<i>ip</i>	face-centered integration point
S'''	general volumetric source term	<i>nb</i>	face neighbor of node <i>P</i>
\dot{S}_{gen}	total rate of entropy generation (W/K)	<i>P</i>	cell-centered node under consideration
\dot{S}_{gen}'''	volumetric rate of entropy generation ($\text{W}/\text{m}^3 \text{K}$)	<i>s</i>	solid constituent
t	time (s)	<i>svp</i>	spherical void phase
T	temperature (K)	*	denotes dimensionless quantity
T_b	bulk temperature (K)		

in greater resistance to local thermal exchange between constituents, and in greater resistance to fluid flow through the pore structure, as compared with the aluminum foam pore geometry. Indeed, though the total interfacial surface area between fluid and solid constituents is typically significantly greater for graphite foams than for aluminum foams [3], the results of the recent computational study of Karimian and Straatman [5], who considered the pore-level fluid flow and heat transfer problems in an idealized periodic spherical void phase foam, illustrated in Fig. 1(a) and (b), suggest that much of the interfacial area provided by the pore structure of actual graphitic foams is inaccessible to the flow. This poor interconnectedness of the fluid constituent between pores obviously leads to substantially greater resistances to both

convective heat transfer and fluid flow in the presently available foams than would be the case for a foam more closely approximating the idealized structure. These observations are further supported by the findings of Betchen and Straatman [6], who developed a volume-averaged form of the local volumetric entropy generation function valid for fluid flow and heat transfer in high-conductivity porous foams under the assumption of local thermal non-equilibrium, and employed it to consider the entropy generation characteristics of presently available graphite foams. In that work, it was found that in spite of the high resistance to fluid flow observed in present foams, the entropy generation is strongly dominated by the resistance to thermal exchange between constituents. Then, motivated by the foregoing discussion, the present

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