



Group classification and conservation laws of nonlinear filtration equation with a small parameter



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ABSTRACT

Group classification of the perturbed nonlinear filtration equation is performed assuming that the perturbation is an arbitrary function of the dependent variable. The nonlinear self-adjointness of the equation under consideration is investigated. Using these results, the approximate conservation laws are constructed.

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1. Introduction

We consider the nonlinear filtration equation with a small parameter:

$$u_t \approx k(u_x)u_{xx} + \varepsilon f(u). \quad (1.1)$$

In particular, this equation describes a pressure distribution in a porous medium. In this paper we make the group classification of Eq. (1.1) and search approximate conservation laws for this equation using its symmetries.

Throughout paper the approximate equation

$$f(x) \approx g(x)$$

means that

$$f(x, \varepsilon) = g(x, \varepsilon) + o(\varepsilon).$$

2. Group classification

The generator of an approximate transformation group admitted by Eq. (1.1) will be written in the form (see [1])

$$X = \xi^1(t, x, u, \varepsilon) \frac{\partial}{\partial t} + \xi^2(t, x, u, \varepsilon) \frac{\partial}{\partial x} + \eta(t, x, u, \varepsilon) \frac{\partial}{\partial u}, \quad (2.2)$$

where

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$$\begin{aligned} \xi^i(t, x, u, \varepsilon) &\approx \xi_{(0)}^i(t, x, u) + \varepsilon \xi_{(1)}^i(t, x, u), \quad i = 1, 2, \\ \eta(t, x, u, \varepsilon) &\approx \eta_{(0)}(t, x, u) + \varepsilon \eta_{(1)}(t, x, u). \end{aligned} \tag{2.3}$$

The determining equation for the operator (2.2) has the form

$$(\varepsilon f'(u)\eta_{(0)} - \zeta_{1(0)} - \varepsilon \zeta_{1(1)} + k'(u_x)u_{xx}(\zeta_{2(0)} + \varepsilon \zeta_{2(1)}) + k(u_x)(\zeta_{22(0)} + \varepsilon \zeta_{22(1)}))|_{(1,1)} \approx 0, \tag{2.4}$$

where $\zeta_{i(j)}, \zeta_{22(j)}$ are obtained by the usual prolongation formulae:

$$\begin{aligned} \zeta_{i(j)} &= D_i(\eta_{(j)}) - u_t D_i(\xi_{(j)}^1) - u_x D_i(\xi_{(j)}^2), \quad i = 1, 2, \quad j = 0, 1, \\ \zeta_{22(j)} &= D_2(\zeta_{2(j)}) - u_{tx} D_2(\xi_{(j)}^1) - u_{xx} D_2(\xi_{(j)}^2). \end{aligned}$$

After replacing u_t by $k(u_x)u_{xx} + \varepsilon f(u)$ in (2.4) and splitting this equation by variable ε we obtain the following system (see [1])

$$\zeta_{1(0)} - \zeta_{2(0)}k'(u_x)u_{xx} - k(u_x)\zeta_{22(0)} = 0, \tag{2.5}$$

$$\zeta_{1(1)} - f'(u)\eta_{(0)} - \zeta_{2(1)}k'(u_x)u_{xx} - k(u_x)\zeta_{22(1)} = 0. \tag{2.6}$$

Eq. (2.5) is the determining equation for the nonlinear filtration equation

$$u_t = k(u_x)u_{xx}. \tag{2.7}$$

We will use the known result of the group classification of Eq. (2.7) (see, e.g. [2]). This result is summarized in Table 1. Eq. (2.6) gives the following system of equations for $\xi_{(1)}^1, \xi_{(1)}^2, \eta_{(1)}$:

$$\begin{aligned} \xi_{(1)x}^1 + u_x \xi_{(1)u}^1 &= 0, \quad k(u_x) \left[-\xi_{(1)t}^1 + 2\xi_{(1)x}^2 + 2u_x \xi_{(1)u}^2 \right] \\ &= k'(u_x) \left[\eta_{(1)x} + (\eta_{(1)u} - \xi_{(1)x}^2)u_x - \xi_{(1)u}^2 u_x^2 \right], \quad f(u)(\eta_{(0)u} - \xi_{(0)t}^1) - f'(u)\eta_{(0)} + \eta_{(1)t} - u_x \xi_{(1)t}^2 \\ &= k(u_x) \left[\eta_{(1)xx} + (2\eta_{(1)xu} - \xi_{(1)xx}^2)u_x + (\eta_{(1)uu} - 2\xi_{(1)xu}^2)u_x^2 - \xi_{(1)uu}^2 u_x^3 \right], \end{aligned} \tag{2.8}$$

where $\xi_{(0)}^1, \xi_{(0)}^2, \eta_{(0)}$ are known functions that depend on the form of $k(u_x)$ (see [2]). In the case of an arbitrary function $k(u_x)$, system (2.8) splits into the system of equations

$$\begin{aligned} \xi_{(1)x}^1 &= 0, \quad \xi_{(1)u}^1 = 0, \quad 2\xi_{(1)x}^2 - \xi_{(1)t}^1 = 0, \quad \xi_{(1)u}^2 = 0, \quad \xi_{(1)t}^2 = 0, \\ \eta_{(1)x} &= 0, \quad \eta_{(1)u} - \xi_{(1)x}^2 = 0, \quad \eta_{(1)uu} - 2\xi_{(1)xu}^2 = 0, \\ 2\eta_{(1)xu} - \xi_{(1)xx}^2 &= 0, \quad f(u)(\eta_{(0)u} - \xi_{(0)t}^1) - f'(u)\eta_{(0)} + \eta_{(1)t} = 0. \end{aligned} \tag{2.9}$$

This system has the following solution:

$$\xi_{(1)}^1 = 2A_1 t + A_2, \quad \xi_{(1)}^2 = A_1 x + A_3, \quad \eta_{(1)} = A_1 u + \alpha(t),$$

where A_i are constants, $i = 1, 2, 3$, and the function $\alpha(t)$ satisfies the last equation of system (2.9)

$$\alpha'(t) = (C_1 u + C_2)f'(u) + C_1 f(u).$$

Note that the function α here depends only on t , while the right-hand side of this formula depends only on u . Therefore this equality is possible only if $\alpha'(t)$ is a constant. Let it be A_4 .

$$(C_1 u + C_2)f'(u) + C_1 f(u) = A_4. \tag{2.10}$$

If $f(u)$ is an arbitrary function, then coefficients $C_1 u + C_2$ and C_1 of Eq. (2.10) vanish, i.e. $C_1 u + C_2 = 0$ and $C_2 = 0$. It follows that $C_1 = 0, C_2 = 0$, and we obtain the six-dimensional Lie algebra spanned by the following generators:

$$\begin{aligned} X_1 &= \frac{\partial}{\partial t}, \quad X_2 = \frac{\partial}{\partial x}, \quad X_3 = \varepsilon \frac{\partial}{\partial t}, \quad X_4 = \varepsilon \frac{\partial}{\partial x}, \\ X_5 &= \varepsilon \frac{\partial}{\partial u}, \quad X_6 = \varepsilon 2t \frac{\partial}{\partial t} + \varepsilon x \frac{\partial}{\partial x} + \varepsilon u \frac{\partial}{\partial u}. \end{aligned} \tag{2.11}$$

Table 1
Group classification of $u_t = k(u_x)u_{xx}$.

$k(u_x)$	Generators
Arbitrary	$X_1 = 2t \frac{\partial}{\partial t} + x \frac{\partial}{\partial x} + u \frac{\partial}{\partial u}, X_2 = \frac{\partial}{\partial u}, X_3 = \frac{\partial}{\partial t}, X_4 = \frac{\partial}{\partial x}$
e^{u_x}	$X_5 = t \frac{\partial}{\partial t} - x \frac{\partial}{\partial u}$
$u_x^{\sigma-1}$, where $\sigma \geq 0, \sigma \neq 1$	$X_5 = (1 - \sigma)t \frac{\partial}{\partial t} + u \frac{\partial}{\partial u}$
$\frac{1}{u_x^{\sigma+1}} e^{\sigma \arctan u_x}$, where $\sigma \geq 0$	$X_5 = \sigma t \frac{\partial}{\partial t} + u \frac{\partial}{\partial x} - x \frac{\partial}{\partial u}$

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