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Short communication

Comparison of gradability performance of fuel cell hybrid electric and internal-combustion engine vehicles

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HIGHLIGHTS

► Gradability performance comparison between (4WD) FC hybrid vehicle and ICE vehicle.
► Different FC parameters affecting vehicle gradability performance are studied.
► FCV performance can be increased by controlling FC parameters.

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ABSTRACT

Fuel cell vehicles are currently undergoing extensive research and development due to their potential for low emissions and high efficiency. Fuel cells are rapidly appearing not only in on-road vehicles but also in off-road vehicles. Off-road vehicles require special geometrical and performance parameters to be able to work in different road conditions. Gradability is one of the most important parameters in off-road vehicle performance which is defined as vehicle's ability to climb a grade at a given speed. This paper presents a comparison study between four-wheel drive (4WD) fuel cell hybrid electric vehicle gradability performance and internal-combustion engine (ICE) 4WD vehicle using Matlab/Simulink software.

1. Introduction

Fuel cell hybrid electric vehicles are based on the same architecture as conventional internal combustion, however, with a fuel cell stack and electric motor instead of an ICE as the primary source of mechanical power for the vehicle. This design offers many of the same benefits to fuel cell vehicle designers; the hybrid design increases vehicle fuel efficiency. However, where hybrids are primarily motivated from an emissions perspective with internal combustion, cost reduction is often a major motivation with fuel cell designs.

In fuel cell hybrid vehicles, mechanical energy is produced from electric motor using the electricity generated from chemical reaction inside the fuel cell. There are different kinds of fuel cells of which PEM and SOFC are the most important ones. PEM fuel cells are the most suitable in automotive applications for their high power density, low operating temperature and quick start capability.

In fewer than 10 years, fuel cell vehicles have been upgraded from ordinary research novelties to operating prototypes and demonstration models. Government and industry in development countries, at the same time, have cooperated to invest billions of dollars in partnerships intended to commercialize fuel cell vehicles within the beginning of the 21st century.

Increasing research in fuel cell and its application in the automobile industry provide an appropriate background for remarkable research in this field, especially in PEM fuel cells. For example, Doss and his colleague in 1998 developed a model for fuel cell systems to demonstrate power generation in which the temperature of the fuel cell was lower than 300 K [1].

In 1999, Quyang studied five different fuels like liquefied natural gas, liquefied oil gas, methanol, hydrogen, de ethyl ether, fixture

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Table 1
Developed models specification.

Vehicle model	Specification
4WD internal-combustion engine vehicle, Fig. 2.	- Generic engine of 100 kW. - Torque converter with mechanical gearbox. - Front and rear differential.
4WD fuel cell vehicle, Fig. 3.	- 400 Cells, 288 Vdc, 100 kW proton exchange membrane (PEM) fuel cell stack. - Electrical motor of a 288 Vdc, 100 kW interior permanent magnet synchronous machine (PMSM). - Electric battery of 13.9 Ah, 288 Vdc, 25 kW lithium-ion battery.

tropes diesel and electricity in spark, diesel, hybrid electric, electric, and fuel cell vehicles. The results show that fuel cell vehicle has high performance and low pollution [2].

In 2000, the design and structure of fuel cell vehicle was tested using a device consisting of a small fuel cell stack for producing a requested average power and a battery for providing power in different moving conditions [3]. In 2001, a model for PEM fuel cell was presented to study fuel cell stack reactions using physical chemistry relationships [4].

In 2004, the transient phenomena in fuel cell PEM system were presented by a mathematical model for simulating [5]. In 2006, Kim and his colleague developed a strategy for power management to optimize fuel consumption in a fuel cell hybrid vehicle [6].

In 2009, Tremblay et al proposed a new approach for fuel cell modeling. The model is a generic model and able to simulate the performance of any fuel cell types fed with hydrogen and air. This model is integrated in SimPowerSystems™ and SimDriveline™ and used in the simulation of a Fuel Cell Vehicle (FCV). The vehicle is modeled with the characteristics of the Honda FCX-Clarity [7].

To continue from this previous study, in this paper, a comparison study of gradability performance on Honda FCX-Clarity vehicle powered by ICE and fuel cell stack/electric motor. The various effects in vehicle gradability performance such as fuel cell power, operating temperature, air flow, air supply pressure and fuel supply pressure are all studied.

2. The vehicle model analysis

Two multi-domain simulation of a vehicle power train based on SimPowerSystems and SimDriveline models are developed to compare ICE vehicle with FC vehicle performance, as shown in Table 1.

We will discuss one important parameter which is called gradability performance; it will be tested using the two developed models starting from the rest on ascending a 15° incline road as shown in Fig. 1, the tested vehicle specifications are shown in Table 2.

The overall reaction of the proton exchange membrane fuel cell (PEMFC) is given by:

Anode: $H_2 \rightarrow 2H^- + 2e^-$

Cathode: $2H^+ + 2e^- + ½\,O_2 \rightarrow H_2O$

The energy potential (the Gibbs free energy) of this reaction is given at standard temperature and pressure by [8]:

$$\Delta g^{\circ} = \Delta h^{\circ} - T_o \Delta s^{\circ} \tag{1}$$

Where:

Δg° Reaction Gibbs free energy
Δh° Reaction enthalpy
Δs° Reaction entropy
T_o Standard temperature (298 K)

The standard-state thermodynamic voltage is given by:

$$E^{\circ} = \frac{\Delta g^{\circ}}{zF} \tag{2}$$

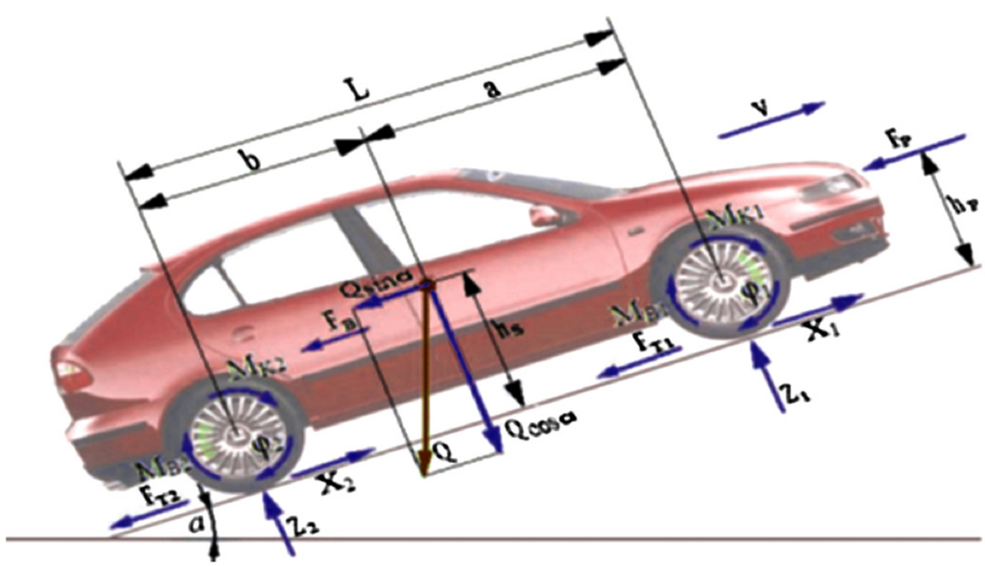

Fig. 1. System of forces and moments acting on the vehicle Q – vehicle weight, X_1, X_2 – longitudinal forces, F_T – rolling resistance, F_B – inertial force, F_P – aerodynamic drag force, Z_1, Z_2 – vertical forces, M_{K1}, M_{K2} – external torque wheel (driving torque or braking), M_{B1}, M_{B2} – moment of inertia wheel and related items, L – wheelbase, a, b – axis distance from the center of mass, v – vehicle velocity, h_p – pressure center distance above the road surface, h_s – height of center mass location, α – angle of the road, $\emptyset_1$, $\emptyset_2$ – angles of wheels' rotation.