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## A multiaxial creep-damage model for creep crack growth considering cavity growth and microcrack interaction

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#### ABSTRACT

This article presents a concise multiaxial creep-damage model for creep crack growth considering the cavity growth and microcrack interaction. Special emphasis is put on developing and validating the multiaxial creep ductility factor (MCDF) based on power-law creep controlled cavity growth theory. Good agreements with the theoretical and experimental data prove the effectiveness of the proposed MCDF. The application of the proposed creep-damage model through finite element simulation of the creep deformation and crack growth in C-Shaped Tension and Compact Tension specimens of 316H tested at 550 °C confirms the predictive capability of the proposed model.

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#### 1. Introduction

A number of metallic components inevitably containing defects are subjected to high temperatures in various industrial fields. For safety reasons, it is imperative to assess the integrity of such components operating in the creep regime. The analysis of creep crack growth based upon Continuum Damage Mechanics (CDM), which offers complementary possibilities to the Fracture Mechanics (FM), has received considerable attention in recent years. Within this approach, the whole process of initiation and propagation of creep crack may be directly related to the build-up of creep damage in the vicinity of the crack tip. When the damage variable,  $\omega$ , reaches a critical value, failure of material ahead of the crack tip is considered to occur, and thus crack growth can be characterized by a completely damaged zone. Following the pioneering work of Kachanov [1] and Rabotnov [2], dozens of creep-damage models have been presented according to the multifarious definitions of damage, with a single [3–10], double [11–13], triple [14–16] or even quadruple [17] damage variables. Damage evolution models in the abovementioned studies are generally stress-based, which can represent the creep damage process to some extent. However, many material parameters in these models need to be calibrated with caution before use. In many cases, obviously, the complex calibrations cannot be realistic for an engineering assessment.

If the critical-strain criterion [18] is employed as a local criterion at the crack tip under creep conditions, the number of undetermined material parameters in the damage models can be considerably reduced. As delineated in Fig. 1, the units of length increments in the area ahead of a creeping crack are compared to uniaxial specimens used in conventional creep tests [19]. The crack is assumed to propagate when the local accumulated creep strain at the crack tip reaches the critical creep ductility. And at the same time, the damage parameter approaches unity. In this sense, the damage evolution law can be given by

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Nomenclature	
a	crack length
u A	coefficient in the creen strain rate expression
d	grain size
ď	average diameter of cavitating grain boundary facets/micro-cracks
f.	area fraction of the cavities at which linkage occurs
f <sub>b</sub>	area fraction of holes on the grain boundary
f;	initial area fraction of the cavities
f	area fraction entering the bound calculation in the cavity growth theory
G	stress-state parameter used in the cavity growth theory
1	half distance between voids
Ĺ	diameter and height of the cylindrical cell containing a cavitating facet
т	time exponents in the time-hardening creep law
п	stress exponent in the creep strain rate expression
Ν	number of cavitating grain boundary facets/micro-cracks per unit volume
Р	applied load
$P_{v}/P_{x}$	biaxial stress ratio
r <sub>h</sub>	radius of growing void
t	time
t <sub>c</sub>	time to coalescence of cavities
$t_{c0}$	time to coalescence of cavities in the case of simple tension
Т	triaxial stress superimposed on the axial stress
V	volume of the cylinder
W	a distance entering the bound calculation in the cavity growth theory
α	stress-state parameter used in the cavity growth theory
α0	stress–state parameter used in the case of simple tension
$\varepsilon^{c}, \dot{\varepsilon}^{c}$	creep strain and creep stain rate, respectively
$\dot{\varepsilon}_a, \dot{\varepsilon}_r$	axial and radial creep strain rate of the cylinder, respectively
$\mathcal{E}_{ij}^{c},  \mathcal{E}_{ij}^{c}$	creep strain tensor and creep stain rate tensor, respectively
$\mathcal{E}_{f}, \mathcal{E}_{f}^{*}$	uniaxial and multiaxial creep failure strain, respectively
$\mathcal{E}_{SS}$	steady creep rate in absence of voids
ho	micro-crack damage parameter
$\sigma_a$	axial stress
$\sigma_{ij}$ , S $_{ij}$	stress tensor and deviatoric stress tensor, respectively
$\sigma_{eq}, \sigma_m$	equivalent (von Mises) and hydrostatic stress, respectively
$\omega, \omega$	Gamage Variable and damage rate, respectively
	Continuum Damage Mechanics
C(1)	Compact Tension [Enter Key]
CS(1)	C-shaped relision [Enter Key]
ГС FM	Innie element Fracture Mechanics
rivi MCDF	Flacture Mechanics
WICDI	multiaxial creep unching factor, defined as $c_f/c_f$



Fig. 1. Schematic diagram of the creep crack growth model in which the crack tip area is described by a series of pseudo uniaxial specimens.

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