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An advanced switching moving boundary heat exchanger model with pressure drop



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ABSTRACT

This paper presents an advanced heat exchanger model based on the moving boundary approach. Significant improvements have been made to overcome the deficiencies of the extant models. Air flow propagation is taken into account to provide a more accurate prediction of air side heat transfer for multi-row coils. Refrigerant pressure drop is calculated in a reasonably simple manner by solving the global momentum balance equation. The choice of state variables shows the benefits of mass conservation and good computational efficiency. Generalized switching schemes capable of supporting dynamic transition between all possible flow configurations are developed. Model integrity and stability are verified through simulations. The model is applied to explore the start-up transients of an R410a flash tank vapor injection system. Favorable agreement between simulation results and experimental data demonstrates that the proposed model can adequately capture the main transient heat transfer and fluid flow phenomena of the system.

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Un nouveau modèle d'échangeur de chaleur à frontière mobile avec chute de pression

Mots clés : Transitoire ; Modélisation ; Frontière mobile ; Échangeur de chaleur ; Injection de vapeur avec un réservoir instantané ; Volume fini

1. Introduction

The thermal inertia of the components, and more importantly the dynamics of the refrigerant flow, dictate the transient

behavior of vapor compression systems. Under normal operating conditions, most refrigerant resides inside heat exchangers, which are the major components that experience the exchange of mass, energy and momentum with other components, including the compressor and the expansion

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Nomenclature		Superscript	
Symbols		i	tube index
A	area [m ²]	Subscripts	
C	heat capacity per unit length [J m ⁻¹ K ⁻¹]	a	air
c _p	specific heat [J kg ⁻¹ K ⁻¹]	act	active
d	diameter [m]	cir	circuit
f	friction loss factor [-]	dry	dry condition
FPI	number of fins per inch [-]	eff	effective
G	mass flux [kg m ⁻²]	f	saturated liquid
h	enthalpy [J kg ⁻¹]	fg	liquid to gas
\bar{h}	enthalpy mean [J kg ⁻¹]	fin	fin
i	tube index [-]	g	saturated vapor
K	gain in the pseudo-state equations [s ⁻¹]	h	enthalpy
L	length [m]	i	internal
Le	Lewis number [-]	in	inlet
\dot{m}	mass flow rate [kg s ⁻¹]	j	zone index (1, 2 or 3)
M	mass [kg]	L	length
N	number [-]	lo	liquid only
p	pressure [N m ⁻²]	min	minimum
\bar{p}	pressure mean [N m ⁻²]	nz	new zone
P _r	row pitch [m]	o	external
P _t	tube pitch [m]	out	outlet
q	heat transfer rate [W]	pseudo	pseudo
q'	heat transfer rate per unit length [W m ⁻¹]	pz	parent zone
t	time [s]	r	refrigerant or tube row
T	temperature [K]	row	tube row
x	vapor quality [-]	sat	saturation
Δ	difference [-]	sc	subcooled
Δz	actual zone length [m]	sh	superheated
Greek letters		suc	suction
α	heat transfer coefficient [W m ⁻² K ⁻¹]	t	tube
β	percentage of a tube contributing to a specific zone [-]	tot	total
δ	thickness [m]	tp	two-phase
ε	minimum threshold [-]	tpz	total parent zone
γ	void fraction [-]	w	wall
$\bar{\gamma}$	void fraction mean [-]	water	condensate water
φ	two-phase pressure drop multiplier [-]	wet	wet condition
ρ	density [kg m ⁻³]	ρ	density
$\bar{\rho}$	density mean [kg m ⁻³]	γ	void fraction
ω	humidity ratio [kg H ₂ O / kg dry air]	1, 2, 3	zone index
ζ	normalized zone length [-]	12, 23	zone boundary

device as well as other auxiliary components, and with the secondary fluids (Björk and Palm, 2006a, 2006b). Consequently, it is essential to obtain accurate mathematical and physical representations for the main transient heat transfer and fluid flow phenomena in heat exchangers (Jakobsen et al., 1999; Kærn et al., 2011).

In general, there are two commonly used heat exchanger modeling paradigms, i.e., phase-independent finite volume method and phase-dependent moving boundary method (Bendapudi et al., 2008). Although they render more accurate predictions in heat transfer and fluid flow phenomena, distributed-parameter finite volume models are not well suited for controls design due to computational complexity, whereas low-order moving bound-

ary models are more favorable in this regard. The moving boundary method is characterized by dividing the heat exchanger into different control volumes, each of which exactly encompasses a particular fluid phase (vapor, two-phase or liquid) and is separated by a moving boundary where refrigerant phase transition occurs. The objective of moving boundary models is to capture the thermodynamic behavior inside these control volumes and the time-varying positions of phase boundaries.

The moving boundary method is based on the concept of the system mean void fraction model (Wedekind and Stoecker, 1968), which allows the two-phase flows to be analyzed in a simplified lumped-parameter manner. By casting the resulting equations into a linearized state-space form, moving

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