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Lévy statistics and beta model: A new solution of "wall" turbulence with a critical phenomenon

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ABSTRACT

By applying statistical mechanics Brown's motion leads to the macroscopic diffusion equation, and similar Lévy flights and the β model are the specific flux origin to derive the Difference-Quotient Turbulence Model (DQTM). It is applied to a turbulent flow in the overlap region close to a wall and leads to a mean velocity deficit power law, which may serve as a substitute for the "logarithmic law" with the von Karman constant. Its exponent is slightly dependent on the stress parameter (e.g. the Reynolds number) and is confirmed by the Princeton super pipe data. The solution of this fluid dynamic standard example reveals a physical order concept, just as known in the theory of critical phenomena.

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Statistiques de Lévy et modèle béta : nouvelle solution pour la turbulence proche de la paroi avec un phénomène critique

Mots clés : Écoulement turbulent ; Fluide ; Couche limite ; Paroi ; Recherche ; Modélisation

1. Introduction

Turbulent flows occur in nature and engineering wherever one looks. The earth's atmosphere including the jet stream, tornados and winds, the oceans with the Gulf Stream,

tsunamis, lakes and rivers, they all show turbulent phenomena. In engineering the flows over the wing of an aircraft, over cars, ships, etc. are usually turbulent. In refrigeration systems turbulence occurs in gas and liquid flows in pipes, after expansion valves, in heat exchangers, mixing

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Nomenclature		u v	velocity (m s $^{-1}$) velocity (m s $^{-1}$)
			· · · · · · · · · · · · · · · · · · ·
Symbol		х	space coordinate (m)
а	basic value for probability	У	space coordinate (m)
а	distance (m)	Greek syr	nbols
а	constant	α	constant
Α	constant	α	stress parameter
b	constant	β	constant
b	step size of a Lévy walk (m)	β	space filling factor
b	width (m)	β	order parameter
В	constant		distance (m)
С	constant	χ	
С	constant	δ	Kronecker symbol
d	space dimension	δ	width of boundary layer (m)
D	fractal dimension	€ .	energy transfer rate (W m ⁻³)
e	spectral energy density (J m ⁻²)	Δ	difference
E	specific turbulent kinetic energy (J m ⁻³)	Δt	eddy generation time (s)
– f	general function	η	dimensionless coordinate
h	scaling exponent (Hurst exponent)	К	auxiliary variable
	specific flux (m s ⁻¹)	λ	general constant
J k	wave number (m^{-1})	λ	structure function
_	· · · · · · · · · · · · · · · · · · ·	ν	viscosity (m ² s ⁻¹)
k	exponent	ρ	density (kg m $^{-3}$)
1	eddy diameter (m)	σ	constant
m	number of created eddies	τ	eddy creation time interval (s)
m	intermediate eddy generation number	τ	shear stress (N m ⁻²)
m	exponent	ω	constant
M	total number of eddies	Ω	auxiliary variable (dep., e.g. m ^{-2/3})
M	total specific momentum (kg m $^{-2}$ s $^{-1}$)	ξ	auxiliary variable
M	dimensionless magnetization		·
n	number of generation	Subscript	
n	integer number	active	active region of eddies in space
N	number related to largest Lévy step	channel	value for a channel
0	occupation number	crit	critical value
0	occupation number of all eddies	eddy	idealized fluid dynamic object
0	order parameter	liquid	liquid phase
р	probability distribution (–)	max	maximal value
p	integer number	min	minimal value
р	exponent	pole	pole value
p	specific eddy momentum (kg m ⁻² s ⁻¹)	solid	solid phase
p	production of turbulent kinetic energy (J m ⁻³)	wall	value at a wall
P P	pressure (Pa m $^{-2}$)	0	largest eddy
9	integer number	0	maximal (at leading edge)
	occupation probability	1	downstream
q Re	Reynolds number	11, 22	normal
	general step size (m)	2	perpendicular to main flow direction
S		21	shear
S	exponent	21	Silear
S	spin value	Superscri	pts
S	standard deviation (m)	*	general variable
S	stress parameter	*	friction variable
t	time (s)	,	fluctuation quantity
t	eddy turnover time (s)	+	dimensionless (inner variable)
T	eddy presence time (s)		mean value (time averaged)
T	transition region		spin up
и	eddy turning velocity (m $ m s^{-1}$)	↑	spin down
U	maximum velocity in a cross section (m s^{-1})	1	Spin down

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