



# Simplified estimates of the creep crack growth parameter $C(t)$ under primary/secondary stresses using the enhanced reference stress method



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## ABSTRACT

### Keywords:

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This paper describes simplified methods to estimate the fracture mechanics parameter,  $C(t)$ , related to creep crack growth rates in non-steady state creep conditions produced by primary or secondary stresses. The methods proposed incorporate effects from initial plasticity and redistribution during a short period after a loading dwell starts, in addition to the estimate of the steady state creep crack growth parameter  $C^*$  by the enhanced reference stress method. The methods have been validated by performing finite element elastic–plastic creep analyses of a circumferentially cracked cylinder subjected to load-controlled tension or thermal loads.

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## 1. Introduction

Assessment of crack-like defects in high temperature power plant components is frequently required to secure safe and reliable operation. To predict crack growth behaviour in the creep regime, a  $J$ -integral type fracture mechanics parameter,  $C(t)$ , needs to be calculated. Estimating  $C(t)$  in general conditions, however, needs costly detailed finite element analysis modelling of the cracked geometry, and thus using some simplified methods is favoured in practice.

The steady state crack growth parameter,  $C^*$  may be estimated by reference stress methods [1,2]. The effects of initial plasticity on  $C(t)$  may be incorporated into the evaluation based on some suggestions for limited conditions, where the stress exponents for plasticity and creep are the same and the loading is a combination of mechanical and thermal stresses [3]. Methods to estimate  $C(t)$  for more general conditions including pure thermal stresses are not fully established, although some proposals have been made [4,5].

The methods described in this paper employ the enhanced reference stress method [6] to improve the accuracy of estimates of the steady state (or in secondary stresses quasi-steady state) parameter  $C^*$ , and the small-scale creep solution in Ref. [7] to incorporate effects from initial plasticity into  $C(t)$ . Validation by performing elastic–plastic creep finite element analyses (FEA) of a

circumferentially cracked cylinder subjected to load-controlled tension or thermal loads is also reported.

## 2. Procedures to estimate $C(t)$

### 2.1. Description of stress–strain relations

Expressing stress–strain relations in power law type equations is convenient as the HRR singularity [8,9] is assumed for the stress field in the crack-tip vicinity. The elastic–plastic constitutive law is expressed by the following Ramberg–Osgood law:

$$\varepsilon = \frac{\sigma}{E} + \varepsilon_0^p \left( \frac{\sigma}{\sigma_Y} \right)^m \quad (1)$$

where  $\sigma$  is stress, and  $\varepsilon$  is strain in general. Material constants are  $E$  (elastic modulus),  $\sigma_Y$  (yield strength),  $\varepsilon_0^p$  (plastic strain at  $\sigma = \sigma_Y$ ), and  $m$  (stress exponent). An elastic–perfectly plastic body may be regarded as a special case with  $m \rightarrow \infty$ .

The creep strain rate is expressed by the following Norton law:

$$\dot{\varepsilon}^c = \varepsilon_0^c \left( \frac{\sigma}{\sigma_Y} \right)^n \quad (2)$$

where  $\dot{\varepsilon}^c$  is creep strain rate, and  $\varepsilon_0^c$  and  $n$  (stress exponent) are material constants.

Hoff's analogy [10] requires that the stress distribution for fully plastic response is identical to that in steady state creep if  $m = n$ .

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**Nomenclature**

$C^*$	steady state creep crack growth parameter
$C(t)$	non-steady state creep crack growth parameter
$C_0$	non-steady state creep crack growth parameter at loading dwell start ( $t = 0$ )
$C_L$	net section stress correction factor to compensate for inaccuracy of the stress categorization method
$E, E'$	elastic modulus, modified elastic modulus
$I_n$	dimensionless function related to stress and strain distributions in the HRR singular field
$J$	elastic–plastic $J$ -integral
$J^e$	elastic $J$ -integral
$J_0$	initial elastic–plastic $J$ -integral at the start of dwell
$J_{FEA}$	elastic–plastic $J$ -integral estimated by detailed elastic–plastic FEA
$J_{ref}$	elastic–plastic $J$ -integral estimated by the original reference stress method
$K_I$	stress intensity factor
$R_{in}$	inner radius of cylinder
$T_{max}$	maximum temperature producing thermal stresses
$Z$	elastic follow-up factor
$a$	crack depth
$m$	stress exponent for plasticity
$n$	stress exponent for creep
$w$	wall thickness of cylinder

$r$	radial distance (in a polar coordinate system)
$r_s$	radial distance between the skeletal point and the crack-tip
$t$	loading dwell time
$\gamma$	limit load correction factor
$\epsilon, \epsilon_{ij}$	total strain, total strain tensor
$\epsilon^c, \epsilon_{ij}^c$	creep strain, creep strain tensor
$\dot{\epsilon}^c, \dot{\epsilon}_{ij}^c$	creep strain rate, creep strain rate tensor
$\epsilon_0^c$	creep strain rate at $\sigma = \sigma_Y$
$\dot{\epsilon}_{ref}^c$	reference creep strain rate at $\sigma = \sigma_{ref}$
$\epsilon^p, \epsilon_{ij}^p$	plastic strain, plastic strain tensor
$\epsilon_0^p$	plastic strain at $\sigma = \sigma_Y$
$\tilde{\epsilon}_{ij}(\theta, n)$	dimensionless function related to the strain distribution in the HRR singular field
$\theta$	angle (in a polar coordinate system)
$\nu$	Poisson's ratio
$\sigma, \sigma_{ij}$	stress, stress tensor
$\bar{\sigma}_b, \bar{\sigma}_m$	von Mises type equivalent bending stress, and membrane stress
$\sigma_{ref}$	reference stress
$\dot{\sigma}_{ref}$	reference stress rate (differential value of $\sigma_{ref}$ with respect to time)
$\tilde{\sigma}_{ij}(\theta, n)$	dimensionless function related to the stress distribution in the HRR singular field

When a more complex constitutive law including primary creep is employed and a Norton type law may be used to describe the minimum creep rate in steady state creep, the steady state  $C^*$  may be estimated by the assumption of Eq. (2).

## 2.2. Enhanced reference stress method to estimate $C^*$

The enhanced reference stress method approximates  $C^*$  by the following equations.

$$C^* = \frac{\dot{\epsilon}_{ref}^c}{\sigma_{ref}/E} J^e \quad (3)$$

where  $\dot{\epsilon}_{ref}^c$  is the reference creep strain rate obtained by substituting the reference stress,  $\sigma_{ref}$  for  $\sigma$  in Eq. (2). The elastic  $J$ -integral,  $J^e$ ,

is estimated from the stress intensity factor,  $K_I$ , for an elastic body with the same loading conditions,

$$J^e = \frac{K_I^2}{E'} \quad (4)$$

where  $E'$  equals  $E$  for plane stress, and  $E/(1 - \nu^2)$  for plane strain conditions ( $\nu$ : Poisson's ratio).

The reference stress is defined as,

$$\sigma_{ref} = \frac{P}{\gamma P_L} \sigma_Y \quad (5)$$

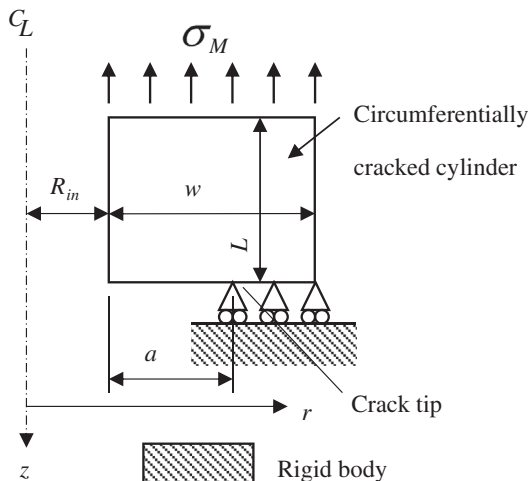
where  $P_L$  is the limit load for the component for a rigid plastic material (equivalent to the assumption of  $m \rightarrow \infty$  in Eq. (1)), and  $P$  is the actual applied load. The limit load correction factor,  $\gamma$ , is non-dimensional, and was introduced by Kim et al. [6] to compensate for inaccuracy of the original reference stress method [11], which may be regarded as a simple case with  $\gamma = 1$ . The limit load may be accurately estimated by performing FEA of an elastic-perfectly plastic body with increasing  $P$  until the cracked component collapses.

The reference stress method using limit analysis is embodied in codes such as R5 [12], although R5 also contains simplified expressions to estimate the reference stress based on the stress categorization concept:

**Table 1**

Cases analysed, dimensions of the cylinder, and applied primary stress.

Case no.	Case 1 MN	Case 2 MN	Case 1 MB	Case 2 MB
Wall thickness, $w$	10 mm			
Inner radius, $R_{in}$	100 mm			
Half cylinder length, $L$	100 mm			
Dimensionless crack depth, $a/w$	1/4	1/2	1/4	1/2
Tensile stress, $\sigma_M$	98 MPa			
Creep law	Secondary only		Primary plus secondary	



**Fig. 1.** Circumferentially cracked cylinder subjected to uniform tensile stress.

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