Contents lists available at ScienceDirect

Applied Mathematics Letters

www.elsevier.com/locate/aml

The properties of the solutions of the incompressible flows on an exterior domain

Jaiok Roh

Department of mathematics, Hallym University, Chuncheon, Kangwon-Do, 200-702, Republic of Korea

ABSTRACT

ARTICLE INFO

Article history: Received 6 February 2018 Received in revised form 4 April 2018 Accepted 4 April 2018 Available online 12 April 2018

Keywords: Euler equations Vorticity Bounded support Lebesque space

1. Introduction

It is also well known that if a domain $\varOmega \subset R^n$ is a bounded set then one has

$$\|\Omega\|^{-\frac{1}{p}} \|u\|_{L^{p}(\Omega)} \le \|\Omega\|^{-\frac{1}{q}} \|u\|_{L^{q}(\Omega)}, \quad \text{for} \quad 1 \le p < q \le \infty,$$
(1.1)

In this paper, we want to see the properties of the smooth solutions \mathbf{u} of the

incompressible flows on an exterior domain Ω of \mathbb{R}^2 . Specially, when the vorticity

 $\omega = \nabla \times \mathbf{u}$ has a bounded support, with suitable conditions we will show that there

exists a constant C(p,q) such that $\|\mathbf{u}\|_{L^{p}(\Omega)} \leq C \|\mathbf{u}\|_{L^{q}(\Omega)}$ for 1 .

where $u \in L^q(\Omega)$. But, generally above inequality is no longer true on an unbounded domain unless u has a bounded support. In this paper, we want to see if we can obtain similar inequality with (1.1) for the solutions of the incompressible flows on unbounded domains when the support of the vorticity is a bounded set. This paper was motivated to study the long time behavior of the solutions for the two dimensional Euler equations. Therefore, for the future work, with the results of this paper we will study the asymptotic behavior of the solutions for the two dimensional Euler equations on an exterior domain. This idea was first initiated by the paper Marchioro [1] that the vorticity $\omega(t)$ of the solutions **u** of the two dimensional Euler equations has a bounded support for all finite time when an initial vorticity ω_0 has a bounded support.

2. Main results

Theorem 2.1. Let $\mathbf{u}(x)$ be the globally smooth enough vector function on an exterior domain Ω of \mathbb{R}^2 where the curl $\nabla \times \mathbf{u}$ has a bounded support contained in a ball B(0, K). We also assume that $\nabla \cdot \mathbf{u}(x) = 0$

LSEVIER



© 2018 Elsevier Ltd. All rights reserved.



E-mail address: joroh@hallym.ac.kr.

https://doi.org/10.1016/j.aml.2018.04.006 $0893\text{-}9659/\odot$ 2018 Elsevier Ltd. All rights reserved.

for all $x \in \Omega$ and **u** vanishes sufficiently rapidly as $|x| \nearrow \infty$. Then, there exists a constant C(p,q) such that

$$\|\mathbf{u}\|_{L^{p}(\Omega)} \leq CK^{\frac{2}{p} - \frac{2}{q}} \|\mathbf{u}\|_{L^{q}(\Omega)}, \text{ for } 1
(2.1)$$

Proof. Let us consider a radial cut-off function $\sigma \in C^{\infty}(\mathbb{R}^2)$ such that

$$\sigma(x) = \sigma(|x|) = 0 \ \, \text{if} \ \, |x| < 1, \quad \sigma(x) = \sigma(|x|) = 1 \ \, \text{if} \ \, |x| > 2,$$

and $0 \le \sigma(x) = \sigma(|x|) \le 1$ for 1 < |x| < 2. And, for each R > 0, we define

$$\sigma\left(\frac{|x|}{R}\right) = \sigma_R(|x|) \in C^{\infty}(R^2).$$

One note that $\|\nabla \sigma_R\|_{L^2(\mathbb{R}^2)}$ is bounded by some constant η which is independent to R. Now, we define new radial cut-off function $\phi_r(x) \in C_0^{\infty}(\mathbb{R}^2)$,

$$\phi_r(x) = \phi_r(|x|) = \sigma\left(\frac{|x|}{K}\right) \left[1 - \sigma\left(\frac{|x|}{r}\right)\right], \text{ for large } r > 3K.$$

And, by the definition of ϕ_r , we can set as

$$\mathbf{v}(x) = \int_{R^2} N(x-y) [\phi_r(y)(\nabla \times \mathbf{u})(y)] dy = \int_{\Omega} N(x-y) [\phi_r(y)(\nabla \times \mathbf{u})(y)] dy,$$
(2.2)

where N be the fundamental function of $-\Delta$ on R^2 . We consider \mathbf{z} as $\mathbf{z} = (\mathbf{z}_1, \mathbf{z}_2, 0)$ to calculate $\nabla \times \mathbf{z}$ and denote $\nabla \times \mathbf{z}$ as $(\nabla \times \mathbf{z}) \cdot e_3 = \frac{\partial \mathbf{z}_2}{\partial x} - \frac{\partial \mathbf{z}_1}{\partial y}$ without any more comments. Then, since $\nabla \cdot \mathbf{u} = 0$, due to

$$\nabla \times \nabla \times F = \nabla (\nabla \cdot F) - \nabla^2 F$$
 and $\phi_r (\nabla \times \mathbf{u}(y)) = \nabla \times (\phi_r \mathbf{u}) - (\nabla \phi_r) \times \mathbf{u}$,

we have from (2.2) that

$$\begin{split} \nabla\times\mathbf{v} &= \nabla\times\int_{R^2}N(x-y)(\nabla\times\phi_r\mathbf{u}(y))dy - \nabla\times\int_{R^2}N(x-y)(\nabla\phi_r)\times\mathbf{u}(y)dy\\ &= \phi_r\mathbf{u} - \nabla\times[N*((\nabla\phi_r)\times\mathbf{u})] + \nabla[N*(\mathbf{u}\cdot\nabla\phi_r)]. \end{split}$$

Since $\nabla \times \mathbf{v} = 0$ from the definition of ϕ_r , we obtain

$$\phi_r \mathbf{u} = \nabla \times [N * ((\nabla \phi_r) \times \mathbf{u})] - \nabla [N * (\mathbf{u} \cdot \nabla \phi_r)].$$
(2.3)

Now, we remind the Sobolev's Theorem (Theorem 9.3 in page 91 of [2]): For $\Psi(x) = \int_{\mathbb{R}^n} K(x,y)f(y)dy$ where $K(x,y) = \frac{1}{|x-y|^{\lambda}}$, $\lambda > 0$, if $f \in L^q(\mathbb{R}^n)$, $1 < q < \infty$ and $\lambda > n(1 - \frac{1}{q})$ then we have $c(q, n, \lambda)$ such that

$$\|\Psi\|_{L^s} \le c \|f\|_{L^q}, \quad \text{for } \frac{1}{s} = \frac{\lambda}{n} + \frac{1}{q} - 1.$$
 (2.4)

In this proof we denote

$$\begin{aligned} \Omega_0 &= \{ x \in R^2 : |x| \le K \}, \quad \Omega_1 = \{ x \in R^2 : K \le |x| \le 2K \}, \\ \Omega_2 &= \{ x \in R^2 : |x| > 2K \}, \quad \Omega_3 = \Omega_0 \cup \Omega_1. \end{aligned}$$

Since $\|\nabla \phi_r\|_{L^2(\mathbb{R}^2)} \leq 2\eta$ for some $\eta > 0$, due to (2.3) and (2.4), we obtain

$$\|\phi_{r}\mathbf{u}\|_{L^{p}(\mathbb{R}^{2})} \leq C_{p}\left(\|\mathbf{u}\|_{L^{p}(\Omega_{1})} + \|\mathbf{u}\|_{L^{p}(\Omega_{r})}\right), \quad \text{for } 2 (2.5)$$

Download English Version:

https://daneshyari.com/en/article/8053466

Download Persian Version:

https://daneshyari.com/article/8053466

Daneshyari.com