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A novel control strategy of regenerative braking system for electric vehicles under safety critical driving situations

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### ACCEPTED MANUSCRIPT

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#### 2 under safety critical driving situations

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- 8 Abstract

9 This paper mainly focuses on control strategy of the regenerative braking system of an electric 10 vehicle under safety critical driving situations. With the aims of guaranteeing the electric vehicle 11 stability in various types of tire-road adhesion conditions, based on the characteristics of an electrified 12 powertrain, a novel control strategy of regenerative braking system is proposed for electric vehicles during anti-lock braking procedures. Firstly, the main construction of the case-study electric car with 13 14 regenerative braking system is introduced. Next, based on the phase plane theory, the optimal brake 15 torque is calculated for ABS control of an electric vehicle. Then, an allocation control, wherein the 16 required optimal brake torque is divided into two parts that are disposed respectively by the friction and 17 regenerative brakes, is discussed. In addition, two parameters for evaluating regeneration braking 18 energy efficiency contribution while in the deceleration braking process are defined. Furthermore, a 19 novel regenerative braking control strategy named "serial control strategy" is proposed. Finally, the 20 road tests are implemented in four types of tire-road adhesion conditions under safety-critical driving 21 situations. The test results validate the effectiveness and feasibility of the proposed control strategy.

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