

Letter

Coupling model for waves propagating over a porous seabed

C.C. Liao^a, Z. Lin^b, Y. Guo^d, D.-S. Jeng^{c,*}^a Department of Civil Engineering, Shanghai Jiao Tong University, Shanghai 200240, China^b School of Engineering, University of Aberdeen, Aberdeen, UK^c Griffith School of Engineering, Griffith University Gold Coast Campus, Queensland, QLD 4222, Australia^d School of Engineering, University of Bradford, BD7 1DP, UK

ARTICLE INFO

Article history:

Received 23 October 2014

Accepted 29 December 2014

Available online 11 March 2015

*This article belongs to the Solid Mechanics

Keywords:

Coupled model

Momentum source

Internal wave-maker

Seabed response

Pore pressure

Liquefaction

ABSTRACT

The wave–seabed interaction issue is of great importance for the design of foundation around marine infrastructures. Most previous investigations for such a problem have been limited to uncoupled or one-way coupled methods connecting two separated wave and seabed sub models with the continuity of pressures at the seabed surface. In this study, a strongly coupled model was proposed to realize both wave and seabed processes in a same program and to calculate the wave fields and seabed response simultaneously. The information between wave fields and seabed fields were strongly shared and thus results in a more profound investigation of the mechanism of the wave–seabed interaction. In this letter, the wave and seabed models were validated with previous experimental tests. Then, a set of application of present model were discussed in prediction of the wave-induced seabed response. Numerical results show the wave-induced liquefaction area of coupled model is smaller than that of uncoupled model.

© 2015 The Authors. Published by Elsevier Ltd on behalf of The Chinese Society of Theoretical and Applied Mechanics. This is an open access article under the CC BY-NC-ND license (<http://creativecommons.org/licenses/by-nc-nd/4.0/>).

The wave–seabed interaction problems have been extensively studied by marine geotechnical engineers in recent years. One of reasons for this growing interest is that numerous marine installations have been reported to be damaged by wave-induced seabed instability [1], rather than by construction or material failure. Most existing studies for the phenomenon of wave–seabed interactions have been limited to either uncoupled or one-way coupling approach, which may not represent the real process in the marine environments. Therefore, it is necessary to develop a coupling model to provide better prediction of the wave-induced soil response in a porous seabed.

In this study, both oscillatory and residual mechanisms of the wave-induced pore pressure are considered. The oscillatory mechanism was modeled by the Biot consolidation theory [2], while the residual mechanism was modeled by plastic theory under cyclic loading. The existing plastic model for residual mechanism [3] will be extended to two-dimensional before we coupled it with the wave model. The wave process was simulated using a momentum source function. Both the wave process and seabed process were built in COMSOL Multiphysics environments. The advantage of this coupled model is to allow us to see the effects of both components (wave and seabed) on wave–seabed

interaction, unlikely previous one-way integrated models [4]. To the authors' best knowledge, this paper may be the first one solving the wave field and seabed response simultaneously in this field.

Two sub-modules are included in the proposed coupled wave–seabed model: wave generation module and seabed module. The wave module is established for generating waves and describing their propagation in a viscous fluid. The seabed module is used to determine the seabed responses to the waves, including the pore pressure, soil displacements, and effective stresses. Unlike any previous one-way integrating model, these two sub-modules are strongly coupled in COMSOL Multiphysics, in which wave and seabed model are simultaneously calculated.

In the wave model, the flow field inside and outside of the porous media is determined by solving the revised Reynolds-averaged Navier–Stokes (RANS) equations, which are derived by integrating the momentum source term over the traditional RANS equations. The flow motion of an incompressible fluid can be described by Navier–Stokes equations

$$\frac{\partial u_i}{\partial x_i} = 0, \quad (1a)$$

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + g_i + \frac{1}{\rho} \frac{\partial \tau_{ij}}{\partial x_j}, \quad (1b)$$

where $i, j = 1, 2, 3$ are for three-dimensional flows, u_i is the i -th component of the velocity vector, ρ is density, p is pressure, g_i is

* Corresponding author.

E-mail address: d.jeng@griffith.edu.au (D.-S. Jeng).

the j -th component of the gravitational acceleration, and τ_{ij} is the element of viscous stress tensor.

Equation (1a) represents the conservation of mass, which has been reduced to the requirement of zero divergence of velocity vector for incompressible fluids. Equation (1b) denotes the conservation of momentum. Generally speaking, there are several options to numerically generate a required wave via an internal wave-maker. One is to add a mass source term in the mass conservation equation (1a). Another is to introduce a momentum source term in the momentum conservation (1b). One can also use both the mass and momentum sources to generate a train of wave. Theoretically, this mass/momentum source could be a point source, a line source, or a finite volume source [5]. In this study, we used an internal wave-maker method for generating essentially directional waves in a two-dimensional domain using a momentum source function of the RANS equation [6]. More detailed information for wave generations, readers can refer to Ref. [6].

In the seabed model, the wave-induced pressure and stress oscillations, denoted by $P_b(x, t)$ and $\tau_b(x, t)$, that further induce the pore pressure p at a generic point in the soil bed to vary with time from the hydrostatic value p_s . Let $p_e = p - p_s$ denote the wave-induced excess pore pressure at a point at the time (t). As suggested in Ref. [3], p_e consists of two components, i.e.,

$$p_e = p_e^{(1)} + p_e^{(2)}, \quad (2)$$

where $p_e^{(1)}$ represents the oscillatory component, whose temporal average $\bar{p}_e^{(1)}$ over any wave cycle is zero. $p_e^{(2)}$ stands for the residual pore pressure, which essentially stems from cyclic plasticity (contractive behavior) of the soil.

The poro-elastoplastic theory was adopted in the present study intending to solve the wave-induced pore pressure, which consists of two components: elastic part for oscillatory pore pressure and plastic part for residual pore pressure. More detailed information, readers can refer Ref. [7] for oscillatory mechanism and Ref. [3] for residual mechanism.

To solve the flow and seabed fields, several boundary conditions are required. As to the wave module, first, the upper boundary of air layer in wave-module is set as a pressure outlet, where the pressure can flow in and out without any constrain. Second, continuity of pressure and fluid displacement is applied at the air/water interface. Then, at the bottom boundary of water domain, the displacement of the water particles is equal to that of the seabed surface.

To solve pore pressure $p_e^{(1)}$ and $p_e^{(2)}$ in seabed module, it is commonly accepted that the vertical effective normal stresses and shear stresses vanish and the oscillatory pore pressure is equal to the water pressures (P_b) at the seabed surface, i.e.

$$\begin{aligned} \sigma'_z &= 0, & \tau_{xz} &= \tau_b(x, t), \\ p_e^{(1)} &= P_b, & p_e^{(2)} &= 0, \quad \text{at } z = 0, \end{aligned} \quad (3)$$

where $P_b(x, t)$ and $\tau_b(x, t)$ are the dynamic wave pressures and bottom wave shear stresses at the seabed surface, respectively, and both can be obtained from the wave model outlined in Eqs. (1a) and (1b).

Second, for the soil resting on an impermeable rigid bottom, zero displacements are assumed. Furthermore, no vertical flow occurs at the horizontal bottom, i.e.,

$$u_s = w_s = 0, \quad \frac{\partial p_e^{(1)}}{\partial z} = \frac{\partial p_e^{(2)}}{\partial z} = 0, \quad \text{at } z = -h. \quad (4)$$

In coupling process, wave module is responsible for the simulation of the wave propagation and determines the pressure and stress acting on the seabed surface. Laminar two-phase

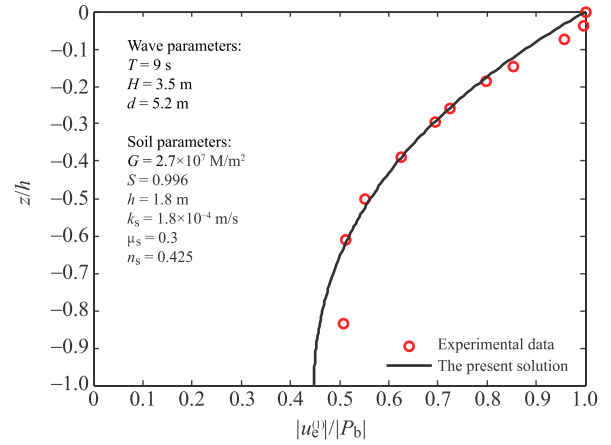


Fig. 1. Comparison with one-dimensional experimental data [8].

(air and water) flow theory with level set method and moving mesh method are used to model the fluid flow of two different, immiscible fluids, when the exact position of the interface is of interest. The interface position is tracked by a moving mesh, with boundary conditions that account for surface tension and wetting, as well as mass transport across the interface. The level set method tracks the fluid–fluid interface using an auxiliary function on a fixed mesh. Since the displacement of seabed surface from seabed module will definitely affect the flow field in the wave module, the authors used the moving mesh method to track the time-dependent displacement of seabed surface as well.

The seabed is modeled with the PDE interface to solve all the equations describing the elastoplastic soil. Both the oscillatory pore pressure and residual pore pressure were considered in the present theory. The pressure/force acting on the seabed were determined by the wave module and were provided to the seabed module to calculate the dynamic response of the seabed including the displacements, pore pressure and the effective stresses. Meanwhile, the information of seabed will in return feed back to the wave module to adjust the computation of flow field. Within a same time step, the information of seabed response and the flow field were strongly coupled and shared without any time lag.

In this letter, we re-produced the wave and seabed models within COMSOL Multiphysics environments. The main contribution of this study lies on the coupling two models through COMSOL, which is a challenge with the previous models.

Two kinds of seabed response will be verified here: oscillatory mechanism and residual mechanism. The oscillatory mechanism will be compared with a one-dimensional compressive test conducted by Liu and Jeng [8]. Then, the residual mechanism will be compared with the centrifuge tests under progressive wave and standing wave, separately.

Liu and Jeng [8] conduct a series of one-dimensional tests to have a better understanding of the wave-induced pore pressures in the vertical direction. As presented in their study, only oscillatory mechanism of pore pressure was observed. To validate the present model, the authors compare the results of our oscillatory pore pressure with the data from laboratory experiments [8]. The numerical results for the maximum vertical oscillatory pore pressure ($p_e^{(1)}/p_b$) versus relative soil depth (z/h) are illustrated in Fig. 1.

It should be noted that in their experiment, only the one-dimensional cylinder model facility was used. Thus, the wave length should be revised as infinite in the present model. Other input data used is also included in Fig. 1. As shown in the figure, the present model overall agrees with the one-dimensional experimental data, indicating a promising prediction of oscillatory pore pressure by present coupling model.

Download English Version:

<https://daneshyari.com/en/article/807653>

Download Persian Version:

<https://daneshyari.com/article/807653>

[Daneshyari.com](https://daneshyari.com)