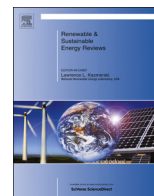




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Hierarchical control structure in microgrids with distributed generation: Island and grid-connected mode



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ABSTRACT

The hierarchical control structure of a microgrid can be described as having four levels responsible for processing, sensing and adjusting, monitoring and supervising, and maintenance and optimization. The responsibility of the hierarchical control level is to provide control over the production of power from renewable sources. This paper comprehensively investigates the principles of hierarchical control in microgrids from a technical point of view. In the first step, this article covers the control of the power generation using two popular renewable energy sources, namely wind turbines and photovoltaics. The synchronization and power flow between the microgrid and the main network is then investigated. Finally, some research questions are presented to improve the performance of the hierarchical control, especially in the secondary decentralized control and energy storage systems.

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Nomenclature

<i>DER</i>	Distribution Energy Resource	<i>MPPT</i>	Maximum Power Point Tracking
<i>DFIG</i>	Double Fed Induction Generator	<i>MS</i>	Microsource
<i>DG</i>	Distributed Generation	<i>MV</i>	Medium voltage
<i>DMS</i>	Distribution Management System	<i>P</i>	active power
<i>f</i>	frequency	<i>P^{ref}</i>	reference of active power
<i>f^{min}</i>	minimum value of frequency	<i>P^{max}</i>	maximum value of active power
<i>f^{ref}</i>	reference of frequency	<i>PV</i>	Photovoltaic
<i>f_{mg}^{ref}</i>	reference of frequency for microgrid	<i>PCC</i>	Point of Common Coupling
<i>f_{mg}</i>	frequency in microgrid	<i>PI</i>	Proportional integral
<i>f_{DG_i}</i>	frequency in individual DG	<i>PLL</i>	Phase locked loop
<i>f_{DG_k}</i>	average frequency for all DG units	<i>PR</i>	Proportional resonant
<i>FLL</i>	Frequency locked loop	ΔP	error of active power
Δf	error of frequency	<i>Q</i>	reactive power
Δf_{DG_k}	control signal providing by DG _k	<i>Q^{ref}</i>	reference of reactive power
<i>G_i</i>	integral gain	<i>Q^{max}</i>	maximum value of reactive power
<i>G_p</i>	proportional gain	<i>Q_{grid}^{ref}</i>	reference of reactive power for main grid
<i>G_{if}</i>	control parameters for frequency of secondary level compensator	<i>Q_{DG_k}</i>	average reactive power for all DG units
<i>G_{iv}</i>	control parameters for voltage of secondary level compensator	<i>Q_{DG_i}</i>	reactive power in individual DG
<i>G_{ip}</i>	control parameters for active power of tertiary level compensator	<i>Q_{grid}</i>	reactive power of main grid
<i>G_{iQ}</i>	control parameters for reactive power of tertiary level compensator	ΔQ	error of reactive power
<i>G_{pf}</i>	control parameters for frequency of secondary level compensator	ΔQ_{DG_k}	control signal providing by DG _k
<i>G_{pv}</i>	control parameters for voltage of secondary level compensator	<i>R</i>	Resistor
<i>G_{pp}</i>	control parameters for active power of tertiary level compensator	<i>RES</i>	Renewable energy source
<i>G_{PQ}</i>	control parameters for reactive power of tertiary level compensator	<i>T_p^(s)</i>	transfer function of active power
<i>HC</i>	Harmonic compensator	<i>T_{pi}^{abc}</i>	transfer function of PI controller in <i>abc</i> frame
<i>HV</i>	High voltage	<i>T_{pr}^{abc}</i>	transfer function of PR controller in <i>abc</i> frame
<i>LV</i>	Low voltage	<i>T_{pi}^{dq}</i>	transfer function of PI controller in <i>dq</i> frame
<i>MG</i>	Microgrid	<i>T_{pr}^{αβ}</i>	transfer function of PR controller in stationary frame
<i>MGCC</i>	Microgrid Central Controller	<i>T_{Qs}^(s)</i>	transfer function of Reactive power
		<i>V^{ref}</i>	reference of voltage
		<i>V^{min}</i>	minimum value of voltage
		<i>V_{mg}^{ref}</i>	reference of voltage for microgrid
		<i>V_{mg}</i>	voltage in microgrid
		<i>V_{DG_k}</i>	voltage in individual DG
		\bar{V}_{DG_k}	average voltage for all DG units
		<i>VSC</i>	Voltage source converter
		ΔV	error of voltage
		ΔV_{DG_k}	control signal providing by DG _k
		<i>X</i>	inductance

1. Introduction

Photovoltaic cells (PV) and wind power generation are the most popular of the energy sources that can be integrated into the main network in the form of Distributed Generators (DG) or Microgrids (MG). Indeed, MGs consist of a methodical organization of such DG systems [1–6]—an organization that leads to increase in system capacity and achieves high power quality [7].

From the control point of view, in a traditional system, distribution of electricity is managed with a multilayer process and connected to the main network [8]. However, in MG and DG systems (the modern approach), the management of electricity distribution is handled in different sectors for participation in active network management based on market terms [9–11].

As presented by Vandoorm et al. [12], in the modern approach, the control of generation units and systems—especially in island mode—have some significant conflicts with the conventional system, such as the lack of rotating inertia, the changes in the effect of line impedance on active and reactive power control, and the variations in power generation from RESs.

Since future distribution networks will require completely novel smart-grid concepts [13], it is necessary to conceive of flexible MGs that are capable of intelligently operating in both

grid-connected and island modes. In this regard, the authors present a control algorithm for MGs participating in the active network management in [14,15]. Moreover, along with the control algorithm, these papers present a general standardization of MGs for hierarchical control. This research is, however, theoretical and investigates standardization from a standards point view, so the objective of the present paper is to investigate the control algorithm, both technically and from the point of view of microgrid control, from power generation using RESs (*zero level*) to synchronizing the MG with the main network (*third level*).

Based on the previous research, controlling the DGs and MGs is critical, and it is necessary to implement a hierarchical control system for them [16]. As shown in Fig. 1, the hierarchical control structure of MGs can be classified into four control levels. In the first step, the paper focuses on the principle of how the power is generated with the two most popular RESs, namely photovoltaic and wind turbine generation. The output voltage and current from the grid-side power converter of these sources are input data for the inner control loop (*level zero*). Then, to achieve high impact management, accurate references are required, which is the responsibility of the *primary control*. The strategy of the control level is an independent local control for increasing the reliability of the power system. On the next level, the approach of *Secondary*

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