



DeltaComp: Fast and efficient compression of astronomical timelines

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ABSTRACT

Astronomical instruments commonly generate large data series in tabular format. To efficiently store and transmit these data series, carefully designed compression formats are welcome. We propose DeltaComp, a free open-source program suited for (relatively) smooth streams of data. DeltaComp is based on rather simple mechanisms; essentially it is a tailored combination of delta coding and context-based modeling. Following the methodology of the preceding work presenting Polycomp (Tomasi, 2016), we compress (i) the ephemeris table of Ganymede, and (ii) the publicly available timelines recorded by LFI, an array of microwave radiometers aboard the ESA Planck spacecraft. In the former case (with small data) the compression ratio advantage of DeltaComp over Polycomp is by a factor of about 1.4. For the Planck data, of size 4.24TB, the archives produced by DeltaComp are almost six times smaller than those from Polycomp, at somewhat smaller median quantization error (and much smaller maximum error), which translates to only 66GB of required storage. Importantly, DeltaComp is over three orders of magnitude faster than Polycomp.

1. Introduction

Astronomy is one of several fields (including also bioinformatics and high energy physics) in which modern instruments produce huge volumes of data (Stephens et al., 2015), for example, the Australian Square Kilometre Array Pathfinder (ASKAP) project acquires several terabytes of sample image data per second and upon completion it is expected to require storage of size about 1 exabyte (= 10^{18} bytes) per year. Merely storing those data is challenging and demands appropriately specialized data compression techniques, formats and related tools. Representing data succinctly is beneficial not only for storage and transmission costs, but may also speed up computations (analyses) by reducing I/O processing.

In astronomy, it is quite typical to deal with tabular numeric data, with strong correlation in columns. Recently, Tomasi (2016) presented Polycomp, a configurable compression tool to handle astronomical timelines. For example, one of the experiments presented in his paper was to compress (a portion of) the recently released Planck timelines (Planck Collaboration ES, 2015), limited to the timelines of the Low Frequency Instrument (LFI), which require over 4TB of disk space. His algorithm, described in detail in Section 3, applies differential encoding to the input data, then approximates them through polynomials of some (possibly low) order, and at the end applies a compressor from an existing library (zlib or bzip2). This is a lossy scheme, involving quantization, which means that the original input can only be approximately

recovered during the decompression. The maximum error per input sample is a program parameter (with a clear tradeoff between the maximum error and the attained compression ratio).

In this work, we simplify and improve the Polycomp approach. We do not (explicitly) apply polynomial approximation, but use a higher-order differential coding. Our backend compression is also more appropriate to the obtained output of the transform. As a result, our algorithm, DeltaComp, achieves a compression ratio about an order of magnitude higher than Polycomp on, e.g., the timelines of the LFI instrument onboard the Planck spacecraft. The compression reduces the storage from 4.24TB, in the uncompressed form, to about 66GB, for a reasonable lossy setting. In speed, the difference is even more striking in favour of DeltaComp.

2. Data compression basics

We start with a few definitions. A *compression algorithm* takes an input $\{d_i\}$ of n symbols, of b bits each, and compresses them to mb bits. In practice, b is often 8, which corresponds to bytes (letters of text, pixels of greyscale images etc. are often kept in single bytes) or 32 (32-bit integers, single-precision floating-point numbers), or 64 (double-precision floating-point numbers). The *compression ratio* is defined as $C_r = n/m$. If C_r is very close to 1, we say that the input data are incompressible (at least with the applied algorithm). In many domains, including measurement data in astronomy, we are satisfied with *lossy*

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| original data | d0 | d1 | d2 | d3 | d4 | d5 | bytes for d3 |
|---------------------|----------|----------|-----------|-----------|------------|------------|------------------------|
| 1.67570799242307356 | 34910583 | 34910583 | 34910583 | 34910583 | 34910583 | 34910583 | {246, 2, 20, 177, 119} |
| 1.67760573897480803 | 34950120 | 39537 | -34871046 | -69781629 | -104692212 | -139602795 | {247, 4, 40, 200, 125} |
| 1.67950255680698390 | 34989637 | 39517 | -20 | 34871026 | 104652655 | 209344867 | {246, 2, 20, 22, 242} |
| 1.68139843250048204 | 35029134 | 39497 | -20 | 0 | -34871026 | -139523681 | {0} |
| 1.68329335261744162 | 35068612 | 39478 | -19 | 1 | 1 | 34871027 | {2} |
| 1.68518730370098435 | 35108069 | 39457 | -21 | -2 | -3 | -4 | {3} |
| 1.68708027227493873 | 35147506 | 39437 | -20 | 1 | 3 | 6 | {2} |
| 1.68897224484356157 | 35186922 | 39416 | -21 | -1 | -2 | -5 | {1} |
| 1.69086320789126776 | 35226317 | 39395 | -21 | 0 | 1 | 3 | {0} |
| 1.69275314788235054 | 35265691 | 39374 | -21 | 0 | 0 | -1 | {0} |
| 1.69464205126071166 | 35305043 | 39352 | -22 | -1 | -1 | -1 | {1} |
| 1.69652990444958496 | 35344373 | 39330 | -22 | 0 | 1 | 2 | {0} |
| 1.69841669385126504 | 35383681 | 39308 | -22 | 0 | 0 | -1 | {0} |
| 1.70030240584683567 | 35422967 | 39286 | -22 | 0 | 0 | 0 | {0} |
| 1.70218702679589717 | 35462230 | 39263 | -23 | -1 | -1 | -1 | {1} |
| 1.70407054303629546 | 35501470 | 39240 | -23 | 0 | 1 | 2 | {0} |
| 1.70595294088385296 | 35540686 | 39216 | -24 | -1 | -1 | -2 | {1} |
| 1.70783420663209706 | 35579879 | 39193 | -23 | 1 | 2 | 3 | {2} |
| 1.70971432655199407 | 35619048 | 39169 | -24 | -1 | -2 | -4 | {1} |
| 1.71159328689167856 | 35658193 | 39145 | -24 | 0 | 1 | 3 | {0} |
| 1.71347107387618691 | 35697314 | 39121 | -24 | 0 | 0 | -1 | {0} |
| 1.71534767370719066 | 35736410 | 39096 | -25 | -1 | -1 | -1 | {1} |
| 1.71722307256272999 | 35775481 | 39071 | -25 | 0 | 1 | 2 | {0} |
| 1.71909725659694868 | 35814526 | 39045 | -26 | -1 | -1 | -2 | {1} |
| 1.72097021193983091 | 35853546 | 39020 | -25 | 1 | 2 | 3 | {2} |
| 1.72284192469693442 | 35892540 | 38994 | -26 | -1 | -2 | -4 | {1} |
| 1.72471238094913093 | 35931508 | 38968 | -26 | 0 | 1 | 3 | {0} |
| 1.72658156675234209 | 35970449 | 38941 | -27 | -1 | -1 | -2 | {1} |
| 1.72844946813728040 | 36009364 | 38915 | -26 | 1 | 2 | 3 | {2} |
| 1.73031607110918406 | 36048251 | 38887 | -28 | -2 | -3 | -5 | {3} |

Fig. 1. Delta coding on a small sample of quantized LFI27M data (Θ angles). Five rounds of delta coding shown. The most successful number of rounds is 3 and for the respective obtained values our byte coding variant is applied (the rightmost column).

Table 1

Ganymede compression ratios and compression times (in seconds), per coordinate. Polycomp worked with 48 threads, DeltaComp was single-threaded.

| Algorithm | Ratio | | | Compression time | | |
|-----------|-------|-------|-------|------------------|-------|-------|
| | x | y | z | x | y | z |
| Polycomp | 13.15 | 13.26 | 24.35 | 93.21 | 93.46 | 35.80 |
| DeltaComp | 17.89 | 18.15 | 35.70 | 0.30 | 0.33 | 0.27 |

compression, which means that the decompressed (recovered) data may only approximate the input submitted to the compression procedure. Many error measures are used in lossy compression (e.g., for multimedia data), yet here, following Tomasi (2016), we characterize the quality of the approximation by the maximal error $\epsilon_c = \max_{i=1..n} |d_i - \tilde{d}_i|$, where \tilde{d}_i are the decompressed symbols.

Data compression techniques consist of modeling and coding. The

Table 2

Planck compression ratios and times. Times are given in format h:mm. Polycomp time estimated for 24-core Xeon machine. DeltaComp times for parallel execution of the algorithm for various datasets using 24 cores.

| Algorithm | Max. error [marsec] | Med. error [marsec] | Compression ratios | | | Compression times | | |
|-----------|------------------------|------------------------|--------------------|--------|--------|-------------------|--------|--------|
| | | | 30 GHz | 44 GHz | 70 GHz | 30 GHz | 44 GHz | 70 GHz |
| Polycomp* | 1000 | ~ 30 | 7.39 | 9.18 | 12.67 | 4340 | 7360 | 31060 |
| DeltaComp | 500 | ~ 250 | 76.61 | 91.02 | 121.95 | 1:36 | 2:57 | 8:32 |
| DeltaComp | 50 | ~ 25 | 44.05 | 53.69 | 73.40 | 1:36 | 2:57 | 7:42 |
| DeltaComp | 5 | ~ 2.5 | 23.17 | 29.47 | 41.48 | 2:24 | 4:08 | 8:39 |
| DeltaComp | 0.5 | ~ 0.25 | 12.58 | 15.96 | 22.39 | 3:00 | 5:26 | 11:58 |

modeling phase is the way to look at the input data: they may be perceived as bits, bytes, pixels, words, 64-bit floating-point numbers, and so on. They may be transformed in different ways, in order to seek for various kinds of repetitions and regularities. The output of the modeling phase is submitted to a coder, which basically works according to the golden rule of compression: shorter codewords should be assigned to frequent (i.e., more probable) symbols, and longer codewords to the symbols which are rare.

Let us now briefly present some compression techniques. They are essentially lossless, but at least some of them are often used, as components, in lossy solutions. More information on the presented ideas can be found, e.g., in Salomon and Motta (2010).

2.1. Run-length encoding (RLE)

RLE is probably the simplest and most obvious compression technique, with very limited applications. It replaces runs of the same

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