## ARTICLE IN PRESS

Physics Letters A ••• (••••) •••-•••



Contents lists available at ScienceDirect

Physics Letters A



PLA:25021

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# Novel algebraic aspects of Liouvillian integrability for two-dimensional polynomial dynamical systems

van der Pol system are constructed.

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#### ARTICLE INFO

#### ABSTRACT

Article history: Received 27 January 2018 Received in revised form 22 March 2018 Accepted 23 March 2018 Available online xxxx Communicated by C.R. Doering

Keywords: Invariant algebraic curves Darboux polynomials Liouvillian first integrals Duffing oscillator Duffing–van der Pol oscillator

#### 1. Introduction

Integrating a dynamical system is one of the major problems of analysis. Existence of invariant algebraic curves and exponential factors is a substantial measure of integrability. In this article our goal is to derive the general structure of irreducible invariant algebraic curves for a generic two-dimensional polynomial dynamical system. We apply our results to the famous Duffing and Duffing-van der Pol oscillators arising in a variety of applications, see [1] and references therein. These models and their generalizations have been intensively studied in recent years [2–7]. We solve completely the problem of Liouvillian integrability for the classical force-free Duffing and Duffing-van der Pol oscillators. It seems that this problem for generic values of the parameters has not yet been studied.

A polynomial vector field in  $\mathbb{C}^2$  can be defined as

$$X = P(x, y)\frac{\partial}{\partial x} + Q(x, y)\frac{\partial}{\partial y}, \quad P(x, y), Q(x, y) \in \mathbb{C}[x, y].$$
(1.1)

By  $\mathbb{C}[x, y]$  we denote the ring of polynomials in the variables *x* and *y* with coefficients in  $\mathbb{C}$ . The dynamical system associated to *X* reads as

$$x_t = P(x, y), \quad y_t = Q(x, y).$$
 (1.2)

https://doi.org/10.1016/j.physleta.2018.03.037 0375-9601/© 2018 Elsevier B.V. All rights reserved. A non-constant function  $I: \mathbb{C}^2 \to \mathbb{C}$  is called a first integral of the polynomial vector field X on an open subset  $D \subset \mathbb{C}^2$  if I(x(t), y(t)) = C with C being a constant for all values of t such that the solution (x(t), y(t)) of X is defined on D. We say that the vector field X is Liouvillian integrable if there exists a Liouvillian first integral I of X. Generally speaking, a function is Liouvillian if it can be expressed using quadratures of elementary functions, for more details and strict definitions see [8–10].

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The general structure of irreducible invariant algebraic curves for a polynomial dynamical system in  $\mathbb{C}^2$ 

is found. Necessary conditions for existence of exponential factors related to an invariant algebraic curve

are derived. As a consequence, all the cases when the classical force-free Duffing and Duffing-van der Pol

oscillators possess Liouvillian first integrals are obtained. New exact solutions for the force-free Duffing-

An algebraic curve F(x, y) = 0,  $F(x, y) \in \mathbb{C}[x, y] \setminus \mathbb{C}$  is an invariant algebraic curve (or a Darboux polynomial) of the vector field *X* if it satisfies the following equation  $XF = \lambda(x, y)F$ , i.e.

$$P(x, y)F_x + Q(x, y)F_y = \lambda(x, y)F, \qquad (1.3)$$

where  $\lambda(x, y) \in \mathbb{C}[x, y]$  is a polynomial called the cofactor of the invariant curve F(x, y). It is straightforward to find that the polynomial  $\lambda(x, y)$  is of degree at most m - 1, where m is the degree of  $X: m = \max\{\deg P, \deg Q\}, [8,9]$ .

The function  $E = \exp(g/f) \notin \mathbb{C}$  with coprime polynomials  $g, h \in \mathbb{C}[x, y]$  is an exponential factor of the vector field X whenever it satisfies the equation  $XE = \varrho(x, y)E$ . The polynomial  $\varrho(x, y) \in \mathbb{C}[x, y]$  is called the cofactor of the exponential factor E and is of degree at most m - 1. It can be easily shown that if the exponential factor  $E = \exp(g/f)$  contains a non-constant polynomial f, then f is an invariant algebraic curve of X [11,12]. The exponential factors arise, when invariant algebraic curves degenerate [11,12]. This concept of degenerate invariant algebraic curves was introduced by Christopher [11,12].

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Please cite this article in press as: M.V. Demina, Novel algebraic aspects of Liouvillian integrability for two-dimensional polynomial dynamical systems, Phys. Lett. A (2018), https://doi.org/10.1016/j.physleta.2018.03.037

2

A non-constant function  $R: \mathbb{C}^2 \to \mathbb{C}$  is an integrating factor of the polynomial vector field *X* on an open subset  $D \subset \mathbb{C}^2$  if  $XR = -R \operatorname{div}(X)$  on *D*. Recall that  $\operatorname{div}(X) = P_X + Q_Y$ .

It is known that the problem of proving Liouvillian integrability or non-integrability of a polynomial vector field X and associated dynamical system (1.2) can be reduced to the problem of constructing all irreducible invariant algebraic curves of X and all exponential factors of X [8–12]. Note that there exist Liouvillian integrable polynomial dynamical systems that have no invariant algebraic curves [13].

The following powerful theorems are valid.

**Theorem 1.1.** Let  $F_j = 0$ ,  $j = 1, ..., r \in \mathbb{N}_0$  be irreducible invariant algebraic curves of X and  $E_k = \exp(g_k/f_k)$ ,  $k = 1, ..., s \in \mathbb{N}_0$  be exponential factors of X. Then the function

$$F_1^{d_1} \dots F_r^{d_r} E_1^{e_1} \dots E_s^{e_s}, \quad d_1, \dots, d_r \in \mathbb{C}, \quad e_1, \dots, e_s \in \mathbb{C},$$
(1.4)

is a first integral (possibly, multi-valued) of X if and only if  $d_j$ ,  $e_k$  are not all zero and the following condition is valid

$$\sum_{j=1}^{r} d_j \lambda_j + \sum_{k=1}^{s} e_k \varrho_k = 0,$$
(1.5)

where  $\lambda_j$  is a cofactor of  $F_j$ ,  $\varrho_k$  is a cofactor of  $E_k$ .

Note that the function of the form (1.4) is called a Darboux function. Obviously, any Darboux function is Liouvillian.

**Theorem 1.2.** Under the assumptions of Theorem 1.1 the polynomial vector field X has a Liouvillian first integral if and only if it has an integrating factor of the form (1.4).

**Theorem 1.3.** Under the assumptions of Theorem 1.1 the Darboux function given in (1.4) is an integrating factor of X if and only if the following condition is valid

$$\sum_{j=1}^{r} d_{j}\lambda_{j} + \sum_{k=1}^{s} e_{k}\varrho_{k} = -di\nu(X).$$
(1.6)

Theorems 1.1 and 1.3 follow from classical theory of Darboux integrability, see [8,9,14]. Theorem 1.2 was proved by Singer [10] and further strengthened by Christopher [11]. A considerable impact in the study of Liouvillian integrability of polynomial dynamical systems has been made by Llibre and Valls, see for example [15,16].

Our aim in the present article is to establish the structure of irreducible invariant algebraic curves of a polynomial vector field X. Regarding the variable y as dependent and the variable x as independent, we find that the function y(x) satisfies the following first-order ordinary differential equation

$$P(x, y)y_{x} - Q(x, y) = 0.$$
(1.7)

In what follows we suppose that the polynomials P(x, y), Q(x, y) do not have non-constant common factors.

A Puiseux series in a neighborhood of the point  $x = \infty$  is defined as

$$y(x) = \sum_{k=0}^{+\infty} b_k x^{\frac{l_0}{n} - \frac{k}{n}}$$
(1.8)

where  $l_0 \in \mathbb{Z}$ ,  $n \in \mathbb{N}$ . It follows from the classical results that a Puiseux series of the form (1.8) that satisfy the equation F(x, y) = 0,  $F(x, y) \in \mathbb{C}[x, y]$  is convergent in a neighborhood of the point

 $x = \infty$  (the point  $x = \infty$  is excluded from domain of convergence if  $l_0 < 0$ ) [17]. The set of all Puiseux series of the form (1.8) forms a field, which we denote by  $\mathbb{C}_{\infty}\{x\}$ . In the next section we shall prove that if y(x) is a Puiseux series solving the equation F(x, y) = 0,  $F_y \neq 0$  with F(x, y) being an invariant algebraic curve of the polynomial vector field *X*, then the series y(x) satisfies equation (1.7).

Recall that if n > 1 then the convergence of the corresponding series is understood in the sense that a certain branch of the *n*-th root is chosen and a cut forbidding going around the branch point is introduced. Further, there exists a compact subset in the domain of convergence of the Puiseux series satisfying the equation F(x, y) = 0 such that convergence of the corresponding series is uniform.

All the Puiseux series that solve equation (1.7) can be obtained with the help of the Painlevé methods [14,18–20], for more details see section 3.

The main contributions of the present article are the following five theorems.

**Theorem 1.4.** Let  $F(x, y) \in \mathbb{C}[x, y] \setminus \mathbb{C}$ ,  $F_y \neq 0$  be an irreducible invariant algebraic curve of polynomial vector field X and related dynamical system (1.2). Then F(x, y) takes the form

$$F(x, y) = \left\{ \mu(x) \prod_{j=1}^{N} \left\{ y - y_j(x) \right\} \right\}_+, \quad N \in \mathbb{N},$$
(1.9)

where  $\mu(x) \in \mathbb{C}[x]$  and  $y_1(x), \ldots, y_N(x)$  are pairwise distinct Puiseux series in a neighborhood of the point  $x = \infty$  that satisfy equation (1.7). The symbol  $\{W(x, y)\}_+$  means that we take the polynomial part of the expression W(x, y). Moreover, the degree of F(x, y) with respect to y does not exceed the number of distinct Puiseux series of the form (1.8) satisfying equation (1.7) whenever the latter is finite.

Consequence. If neither Puiseux series in a neighborhood of the point  $x = \infty$  satisfy equation (1.7) nor the functions of the form (1.9) constructed with the help of all possible combinations of admissible Puiseux series are polynomial, then invariant algebraic curves of vector X (if any) are of the form F(x). Here an admissible Puiseux series means that this series is of the form (1.8) and satisfies equation (1.7).

The inverse theorem is also valid.

**Theorem 1.5.** Suppose that  $y_1(x), \ldots, y_N(x)$  are pairwise distinct *Puiseux series in a neighborhood of the point*  $x = \infty$  *that satisfy equation (1.7). Let the polynomial*  $\mu(x) \in \mathbb{C}[x]$  *be such that the following expression* 

$$F(x, y) = \mu(x) \prod_{j=1}^{N} \left\{ y - y_j(x) \right\}$$
(1.10)

is an irreducible in  $\mathbb{C}[x, y]$  polynomial, i.e. the non-polynomial part in (1.10) vanishes producing the polynomial F(x, y), then F(x, y) is an irreducible invariant algebraic curve of the polynomial vector field X and related dynamical system (1.2).

*Remark.* Theorems 1.4 and 1.5 introduce a novel algebraic tool for finding all irreducible invariant algebraic curves explicitly. At the first step, one should obtain all the Puiseux series near the point  $x = \infty$  that satisfy equation (1.7). At the second step, it is necessary to consider different combinations of the Puiseux series and require that the non-polynomial part of expression (1.10) vanishes. Restrictions on the polynomial  $\mu(x)$  (if any) can be found balancing higher-order terms (with respect to y) in equation (1.3).

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