# On the stability of the cut locus 

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## A R T I C L E I N F O

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#### Abstract

In $\mathbb{R}^{d}$ we consider a Riemannian metric, $g$, and an open bounded subset, $\Omega$. We study the stability of the cut locus associated with $\Omega$ and $g$ w.r.t. perturbations both of the set $\Omega$ and of the metric $g$. In order to have the stability of the cut locus, we assume $C^{2}$ regularity of the data, the metrics and the sets (in the case of sets with $C^{1,1}$ boundaries, the cut locus may be unstable). We prove that to $C^{2}$ perturbations both of the set and of the metric correspond small changes of the cut locus w.r.t. the Hausdorff distance, i.e. the cut locus is stable in the $C^{2}$ category. We give some examples showing that $C^{1}$ perturbations may lead to large variations of the cut locus.


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## 1. Introduction and statement of the result

Let $\Omega^{\prime}$ be an open bounded subset of $\mathbb{R}^{d}$. Set

$$
\mathcal{A}\left(\Omega^{\prime}\right)=\left\{\Omega \subset \subset \Omega^{\prime} \mid \Omega \text { is an open set with boundary of class } C^{2}\right\}
$$

and

$$
\mathcal{G}\left(\Omega^{\prime}\right)=\left\{g \mid g \text { is a Riemannian metric with } C^{2} \text { coefficients defined in } \Omega^{\prime}\right\} .
$$

Let $\Omega \in \mathcal{A}\left(\Omega^{\prime}\right)$ and let $g \in \mathcal{G}\left(\Omega^{\prime}\right)$. By using the metric $g$, given a piecewise differentiable curve on $\bar{\Omega}$, $\gamma:[0,1] \longrightarrow \bar{\Omega}$, we can measure its length,

$$
L(\gamma)=\int_{0}^{1} \sqrt{g_{\gamma(t)}\left(\gamma^{\prime}(t)\right)} d t
$$

Hence, for every couple of points $x, y \in \Omega$, we denote by $d(x, y)$ the distance between $x$ and $y$, i.e.

$$
d(x, y)=\inf L(\gamma)
$$

[^0](the infimum is taken in the set of all the piecewise differentiable curves on $\bar{\Omega}$ connecting $x$ with $y$ ). We consider the distance function from the boundary of $\Omega, \partial \Omega$, defined as
$$
d_{\partial \Omega}(x)=\inf _{y \in \partial \Omega} d(x, y), \quad(x \in \Omega) .
$$

Let $\gamma$ be a geodesic starting at a point of $\partial \Omega$. We say that a point of $\gamma, z$, is a cut point of $\partial \Omega$ (along $\gamma$ ) if it is the first point on $\gamma$ such that for any point $y$ in $\gamma$ beyond $z$, there exists a geodesic from a point of $\partial \Omega$ to $y$ shorter than $\gamma$. We denote by $\operatorname{cut}(\Omega, g)$ the set of all the cut points of $\partial \Omega$ (in $\Omega$ ) associated with the Riemannian metric $g$.

We study the stability of the cut locus w.r.t. perturbations both of the set $\Omega$ and of the metric $g$.
We recall some basic properties of the cut locus:
(1) the cut locus has measure zero ${ }^{1}$ (see e.g. [14] for general and precise rectifiability results).
(2) The $C^{2}$ regularity of the Riemannian metric and of the boundary implies that the cut locus is a closed set (for a discussion of such a property we refer the reader to Remark 2.1 in the sequel).
(3) The cut locus, $\operatorname{cut}(\Omega, g)$, has the same homotopy type as the set $\Omega$ (see e.g. [4]).
(4) The cut locus stays away from the boundary of the open set under exam, $\partial \Omega$, (see e.g. [1]).

In particular, $\operatorname{cut}(\Omega, g) \subset \Omega$ is a compact set, for every $\Omega \in \mathcal{A}\left(\Omega^{\prime}\right)$ and for every $g \in \mathcal{G}\left(\Omega^{\prime}\right)$.
We measure the variations of the cut locus by using the Hausdorff distance between compact sets: given two compact sets $K, L \subset \Omega^{\prime}$ we define

$$
d_{H}(K, L)=\max \left\{\max _{x \in K} d_{L}^{e}(x), \max _{L} d_{K}^{e}(x)\right\}
$$

Hereafter $d_{K}^{e}(x)$ denotes the Euclidean distance function of $x$ from the set $K$.
For every $g \in \mathcal{G}\left(\Omega^{\prime}\right)$ we have

$$
\begin{equation*}
g_{x}(\xi)=\langle G(x) \xi, \xi\rangle, \quad x \in \Omega^{\prime}, \xi \in \mathbb{R}^{d} . \tag{1.1}
\end{equation*}
$$

Here $\langle\cdot, \cdot\rangle$ stands for the standard Euclidean product in $\mathbb{R}^{d}$ and $G(\cdot)$ is a family of positive definite matrices, with entries of class $C^{2}$.

Definition 1.1 (Convergence of the Metrics and of the Sets).
(i) For $k=1,2$, we say that the sequence $g_{j} \in \mathcal{G}\left(\Omega^{\prime}\right)$ converges to $g \in \mathcal{G}\left(\Omega^{\prime}\right)$ in $C^{k}$ if

$$
\lim _{j \rightarrow \infty} \sum_{|\alpha| \leq k} \sup _{x \in \Omega^{\prime}}\left\|\partial_{x}^{\alpha}\left(G_{j}-G\right)(x)\right\|=0 .
$$

(Here $\|\cdot\|$ stands for a norm in the space of the positive definite $d \times d$ matrices.)
(ii) For $k=1,2$, we say that the sequence $\Omega_{j} \in \mathcal{A}\left(\Omega^{\prime}\right)$ converges to $\Omega \in \mathcal{A}\left(\Omega^{\prime}\right)$ in $C^{k}$ if
(1) there exists an open neighbourhood of $\partial \Omega, W \subset \Omega^{\prime}$, such that $\partial \Omega_{j} \subset W, j=1,2, \ldots$.
(2) Denoting by $\operatorname{dist}\left(x, \partial \Omega_{j}\right)=d_{\Omega^{\prime} \backslash \Omega_{j}}^{e}(x)-d_{\Omega_{j}}^{e}(x)$ the (Euclidean) signed distance of $x$ from $\partial \Omega_{j}$, $\operatorname{dist}(\cdot, \partial \Omega)$ and $\operatorname{dist}\left(\cdot, \partial \Omega_{j}\right)$ are in $C^{k}(W), j=1,2, \ldots$
(3) $\lim _{j \rightarrow \infty} \sum_{|\alpha| \leq k} \sup _{x \in W}\left|\partial_{x}^{\alpha}\left(\operatorname{dist}\left(x, \Omega_{j}\right)-\operatorname{dist}(x, \Omega)\right)\right|=0$.

[^1]
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[^0]:    E-mail address: paolo.albano@unibo.it.

[^1]:    ${ }^{1}$ This property holds under weaker regularity conditions on the boundary of $\Omega$ : the cut locus associated with a closed set $C \subset \mathbb{R}^{d}$ has measure zero (see [5]).

