



Renormalized solutions to nonlinear parabolic problems in generalized Musielak–Orlicz spaces



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ABSTRACT

We will present the proof of existence of renormalized solutions to a nonlinear parabolic problem $\partial_t u - \operatorname{div}(a(\cdot, Du)) = f$ with right-hand side f and initial data u_0 in L^1 . The growth and coercivity conditions on the monotone vector field a are prescribed by a generalized $\mathcal{N}$ -function M which is anisotropic and inhomogeneous with respect to the space variable. In particular, M does not have to satisfy an upper growth bound described by a Δ_2 -condition. Therefore we work with generalized Musielak–Orlicz spaces which are not necessarily reflexive. Moreover we provide a weak sequential stability result for a more general problem: $\partial_t \beta(\cdot, u) - \operatorname{div}(a(\cdot, Du) + F(u)) = f$, where β is a monotone function with respect to the second variable and F is locally Lipschitz continuous. Within the proof we use truncation methods, Young measure techniques, the integration by parts formula and monotonicity arguments which have been adapted to nonreflexive Musielak–Orlicz spaces.

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1. Introduction

1.1. Statement of the problem

Let Ω be a bounded domain in $\mathbb{R}^d$ ($d \geq 1$) with Lipschitz boundary $\partial\Omega$ if $d \geq 2$ and let $[0, T]$ be a finite time interval, and $Q_T = (0, T) \times \Omega$. We are interested in existence of renormalized solutions to the following nonlinear parabolic problem

$$\begin{aligned} \partial_t \beta(x, u(t, x)) - \operatorname{div}(a(x, Du(t, x)) + F(u(t, x))) &= f \quad \text{in } Q_T, \\ u &= 0 \quad \text{on } (0, T) \times \partial\Omega, \\ \beta(x, u(0, x)) &= b_0 \quad \text{in } \Omega, \end{aligned} \tag{P, f, b_0}$$

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where $f \in L^1(Q_T)$, $F : \mathbb{R} \rightarrow \mathbb{R}^d$ is locally Lipschitz continuous and

B1: $\beta : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a monotone (with respect to the second argument), single-valued Carathéodory function.

B2: $\beta(x, 0) = 0$ for a.a. $x \in \Omega$.

B3: for all $l \in \mathbb{R}$ $\beta(\cdot, l) \in L^1(\Omega)$.

Moreover, we assume that $a : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ satisfies the following conditions:

A1: $a : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$ is a Carathéodory function.

A2: there exist generalized $\mathcal{N}$ -functions $M, M^* : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, where M^* is a conjugate function to M (for definitions see Section 2), a constant $c_a \in (0, 1]$ and a nonnegative integrable function a_0 such that

$$a(x, \xi) \cdot \xi \geq c_a \{M^*(x, a(x, \xi)) + M(x, \xi)\} - a_0(x) \quad (1)$$

for a.a. $x \in \Omega$ and all $\xi \in \mathbb{R}^d$.

A3: $a(\cdot, \cdot)$ is monotone, i.e.

$$(a(x, \xi) - a(x, \eta)) \cdot (\xi - \eta) \geq 0 \quad (2)$$

for a.a. $x \in \Omega$ and all $\xi, \eta \in \mathbb{R}^d$.

Additionally, we assume that

M1: there exist $c_M > 0, \nu > 0$ and $\xi_0 \in \mathbb{R}^d$ such that

$$M(x, \xi) \geq c_M |\xi|^{1+\nu} \quad \text{for a.a. } x \in \Omega \text{ and all } \xi \in \mathbb{R}^d, |\xi| \geq |\xi_0|. \quad (3)$$

M2: the conjugate function

$$M^* \text{ satisfies the } \Delta_2\text{-condition,} \quad (4)$$

i.e., there exist some nonnegative, integrable on Ω function g_{M^*} and a constant $C_{M^*} > 0$ such that

$$M^*(x, 2\xi) \leq C_{M^*} M^*(x, \xi) + g_{M^*}(x) \quad \text{for all } \xi \in \mathbb{R}^d \text{ and a.a. } x \in \Omega. \quad (5)$$

M3: the conjugate function M^* satisfies

$$\lim_{|\xi| \rightarrow \infty} \operatorname{ess\,inf}_{x \in \Omega} \frac{M^*(x, \xi)}{|\xi|} = \infty. \quad (6)$$

Example 1.1. The following examples of $\mathcal{N}$ -functions fit into our setting:

- $M(x, \xi) = |\xi|^{p(x)}$, with $p : \Omega \rightarrow (p^-, \infty)$ measurable and $p^- := \operatorname{ess\,inf}_{x \in \Omega} p(x) > 1$.
- $M(x, \xi) = \sum_{i=1}^d |\xi_i|^{p_i(x)}$, $p_i : \Omega \rightarrow (p_i^-, \infty)$ measurable, $p_i^- := \operatorname{ess\,inf}_{x \in \Omega} p_i(x) > 1, i = 1, \dots, d$ and $\xi = (\xi_1, \dots, \xi_d) \in \mathbb{R}^d$.

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