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On the energy inequality for weak solutions to the Navier–Stokes equations of compressible fluids on unbounded domains

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ABSTRACT

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1. Introduction

Let T > 0 be fixed and let $\Omega \subset \mathbb{R}^3$ be an exterior domain (an unbounded domain with compact Lipschitz boundary $\partial \Omega$). We consider the Navier–Stokes equations of a compressible isentropic viscous fluid

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0, \tag{1.1}$$

We consider the Navier–Stokes equations of compressible isentropic viscous fluids

on an unbounded three-dimensional domain with a compact Lipschitz boundary.

Under the condition that the total mass of the fluid is finite, we show the existence

of globally defined weak solutions satisfying the energy inequality in differential

$$\partial_t(\rho \mathbf{u}) + \operatorname{div}_x(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla_x \rho^\gamma = \operatorname{div}_x \mathbb{S},\tag{1.2}$$

in the unknown variables

$$\varrho = \varrho(x,t) : \Omega \times (0,T) \to \mathbb{R} \quad \text{and} \quad \mathbf{u} = \mathbf{u}(x,t) : \Omega \times (0,T) \to \mathbb{R}^3$$

representing the density and velocity of the fluid, respectively. The adiabatic constant γ is subjected to the technical constraint

$$\gamma > \frac{3}{2},$$

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while the viscous stress tensor S fulfills Newton's rheological law

$$\mathbb{S}(\nabla_x \mathbf{u}) = \mu \left(\nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I},$$

with shear viscosity coefficient μ and bulk viscosity coefficient η satisfying

$$\mu > 0$$
 and $\eta \ge 0$

Accordingly, we may write

$$\operatorname{div}_x \mathbb{S} = \mu \Delta \mathbf{u} + (\lambda + \mu) \nabla_x \operatorname{div}_x \mathbf{u},$$

where

$$\lambda = \eta - \frac{2}{3}\mu$$

As the underlying physical domain is unbounded, the system is supplemented with the far field conditions

$$\lim_{|x|\to\infty} \varrho(x,t) = 0, \qquad \lim_{|x|\to\infty} \mathbf{u}(x,t) = 0,$$

and the no-slip boundary condition

$$\mathbf{u}(x,t)_{|x\in\partial\Omega} = 0.$$

Finally, we prescribe the initial conditions

$$\varrho(0) = \varrho_0$$
 and $(\varrho \mathbf{u})(0) = \mathbf{q}_0$

where ρ_0 and q_0 are given functions, complying with the following assumptions:

- $\varrho_0 \in L^1(\Omega) \cap L^{\gamma}(\Omega)$ and $\varrho_0 \ge 0$ almost everywhere. $q_0 \in L^{\frac{2\gamma}{\gamma+1}}_{\text{loc}}(\overline{\Omega}; \mathbb{R}^3)$ is such that $q_0(x) = 0$ whenever $\varrho_0(x) = 0$. Moreover

$$\frac{|\boldsymbol{q}_0|^2}{\varrho_0} \in L^1(\Omega).$$

Under the above general assumptions on the structural coefficients and the initial data, the compressible Navier–Stokes equations (1.1)–(1.2) are known to admit at least one globally defined weak solution¹ (ρ, \mathbf{u}) (see [5,12,14]). In particular, for the energy functional

$$E(t) = \int_{\Omega} \left[\frac{1}{2} \rho |\mathbf{u}|^2(t) + \frac{1}{\gamma - 1} \rho^{\gamma}(t) \right] \mathrm{d}x,$$

the weak solutions can be constructed to fulfill the energy inequality in the integral form

$$E(t) + \int_0^t \int_\Omega \left[\mu |\nabla_x \mathbf{u}|^2 + (\lambda + \mu) |\operatorname{div}_x \mathbf{u}|^2 \right] \mathrm{d}x \,\mathrm{d}r \le E_0 \tag{1.3}$$

for almost any $t \in [0, T]$, where

$$E_0 = \int_{\Omega} \left[\frac{1}{2} \frac{|\boldsymbol{q}_0|^2}{\varrho_0} + \frac{1}{\gamma - 1} \varrho_0^{\gamma} \right] \mathrm{d}x.$$

¹ See Section 3 for the precise definition.

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