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Nonlinear Analysis

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ABSTRACT

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1. Introduction

We consider, in a bounded domain $\Omega \subset \mathbb{R}^n$, $n \leq 3$, with a C^2 boundary $\partial \Omega = \Gamma$ and for a finite time T > 0, the following nonlinear parabolic system:

$$\begin{cases} C_p \frac{\partial}{\partial t} u + \frac{\ell}{2} \frac{\partial}{\partial t} \varphi = k \Delta u + f_1(t, x) & \text{in } Q \\ \alpha \xi \frac{\partial}{\partial t} \varphi = \xi \Delta \varphi + F(\varphi) + s_{\xi} u + f_2(t, x) & \text{in } Q, \end{cases}$$
(1.1)

This paper studies a Caginalp phase-field transition system endowed with a general reg-

ular potential, as well as a general class, in both unknown functions, of nonlinear and

non-homogeneous (depending on time and space variables) boundary conditions. We first

prove the existence, uniqueness and regularity of solutions to the Allen–Cahn equation, subject to the nonlinear and non-homogeneous dynamic boundary conditions. The exis-

tence, uniqueness and regularity of solutions to the Caginalp system in this new formula-

tion are also proved. This extends previous works concerned with regular potential and

nonlinear boundary conditions, allowing the present mathematical model to better ap-

proximate the real physical phenomena, especially phase transitions.

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Nonlinear

with nonlinear and non-homogeneous Cauchy–Neumann boundary conditions on the unknown function *u* and nonlinear and non-homogeneous dynamic boundary conditions on the unknown function φ , namely:

$$\begin{cases} k \frac{\partial}{\partial \nu} u + hu + g_1(t, x, u) = w_1(t, x) & \text{on } \Sigma \\ \xi \frac{\partial}{\partial \nu} \varphi + \alpha \xi \frac{\partial}{\partial t} \varphi - \Delta_{\Gamma} \varphi + c_0 \varphi + g_2(t, x, \varphi) = w_2(t, x) & \text{on } \Sigma, \end{cases}$$
(1.2)

and with the initial conditions

$$u(0, x) = u_0(x), \qquad \varphi(0, x) = \varphi_0(x) \quad \text{in } \Omega,$$
 (1.3)

where $Q = (0, T] \times \Omega$, $\Sigma = (0, T] \times \partial \Omega$, and:

- u(t, x) represents the reduced temperature distribution in Q;
- $\varphi(t, x)$ is the phase function (the order parameter), used to distinguish between the states (phases) of a material which occupies the region Ω at every time $t \in [0, T]$;
- $C_p = \rho c$ (ρ is the density, c is the specific heat capacity), ℓ , k, α , ξ , h are physical parameters representing: the latent heat, the thermal conductivity, the relaxation time, the measure of the interface thickness, the heat transfer coefficient, respectively, while $s_{\xi} = \frac{m[S]_E}{2\sigma} T_E$ is a bounded and positive quantity expressed by positive and bounded physical parameters (see [5]); • c_0 is a positive constant and Δ_{Γ} is the Laplace-Beltrami operator;
- $f_1 \in L^p(Q), f_2 \in L^q(Q)$ are given functions (which can be interpreted as *distributed controls*), where p and q satisfy (see also [2,15,16,18,17])

$$q \ge p \ge 2; \tag{1.4}$$

• $F : \mathbb{R} \longrightarrow \mathbb{R}$ is a real function having the structure

$$F(\varphi) = f(\varphi) - a_{s} |\varphi|^{s-1} \varphi, \quad \forall \varphi \in \mathbb{R},$$
(1.5)

with $a_s > 0$ and $s \ge 3$ satisfying (see also relation (1.14))

$$\frac{n+2}{n+2-2p} > s \quad \text{if } \frac{1}{p} - \frac{2}{n+2} > 0, \tag{1.6}$$

while $f(\varphi) \in C^1(\mathbb{R})$ fulfills, for constants $b_1, b_2 > 0$, the following properties:

$$|f'(\varphi)| \le b_1(1+|\varphi|^{s-2}), \quad \forall \varphi \in \mathbb{R}$$

$$(1.7)$$

and

$$f(\varphi_1) - f(\varphi_2))(\varphi_1 - \varphi_2) \le b_2(\varphi_1 - \varphi_2)^2, \quad \forall \varphi_1, \varphi_2 \in \mathbb{R}.$$
 (1.7)

- Examples of nonlinearities F depending on t, x and φ can be found in [9,16]. Here we take $F(\varphi)$ independent of the space variable because the main difficulty in treating the parabolic nonlinear problem (1.1) lies in the nonlinearity with respect to φ (see [5,7,15,17,19] and references therein);
- $w_1, w_2 \in W_p^{1-\frac{1}{2p}, 2-\frac{1}{p}}(\Sigma)$ are given functions (which can be interpreted as *boundary controls*); $g_i: \Sigma \times \mathbb{R} \to \mathbb{R}, i = 1, 2$, are Carathéodory functions, i.e., $g_i(\cdot, \cdot, z): \Sigma \to \mathbb{R}$ is measurable, $\forall z \in \mathbb{R}$, and $g_i(t, x, \cdot)$: $\mathbb{R} \to \mathbb{R}$ is continuous, $\forall (t, x) \in \Sigma$, with $g_i(\cdot, \cdot, 0) \in L^{\infty}(\Sigma)$. Moreover, the following hypotheses are assumed to be satisfied (i = 1, 2):

$$G_1: (g_i(t, x, z_1) - g_i(t, x, z_2))(z_1 - z_2) \ge c_1(z_1 - z_2)^2, \ \forall (t, x) \in \Sigma, z_1, z_2 \in \mathbb{R}, \text{ for a constant } c_1 > 0;$$

G₂: there is a function $\overline{G}: \Sigma \times \mathbb{R}^2 \to \mathbb{R}$ verifying the relations

$$\left(g_i(t, x, z_1) - g_i(t, x, z_2) \right)^2 \le \bar{G}(t, x, z_1, z_2)(z_1 - z_2)^2, \bar{G}(t, x, z_1, z_2) \le c_2(1 + |z_1|^{2(r'-1)} + |z_2|^{2(r'-1)}), \quad \forall (t, x) \in \Sigma, \ z_1, z_2 \in \mathbb{R}$$

for a constant $c_2 > 0$ and $r' \ge 1$ such that (see relation (2.8))

$$\frac{n+2}{n+2-2p} \ge r' \quad \text{if } \frac{1}{p} - \frac{2}{n+2} > 0; \tag{1.8}$$

 G_3 : $g_i(t, x, z)z \ge c_3 z^2$, $\forall (t, x) \in \Sigma$, $z \in \mathbb{R}$, with $c_3 > 0$.

• $u_0 \in W_p^{2-\frac{2}{p}}(\Omega)$, with $k\frac{\partial}{\partial v}u_0 + hu_0 + g_1(0, x, u_0) = w_1(0, x)$, and $\varphi_0 \in W_q^{2-\frac{2}{q}}(\Omega)$, with $\xi\frac{\partial}{\partial v}\varphi_0 - \Delta_{\Gamma}\varphi_0 + c_0\varphi_0 + c_0\varphi_0$ $g_2(0, x, \varphi_0) = w_2(0, x).$

Let us point out the following remark regarding the nonlinearity $F(\varphi)$ in (1.1), whose form is defined by (1.5).

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