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Nonlinear

Analysis

Nonlinear Analysis 69 (2008) 1666-1674

The convexity of the solution set of a pseudoconvex inequality

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Abstract

For a pseudoconvex function f on a nonempty convex set C in a real normed vector space X, we present several equivalent conditions for the convexity of the set

$$C_x := \{c \in C : f(x) \le f(c)\} \text{ for } x \in C.$$

These conditions turn out to be very useful in characterizing the solution set of a pseudoconvex minimization problem of f over C_x and the pseudolinearity of a Gâteux differentiable function f. We hence extend several existing results about characterizations of the solutions to a convex program and a pseudolinear program.

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MSC: 90C25; 52A05

Keywords: Convex solution sets; Pseudoconvex programs; Characterizations of pseudolinearity

1. Introduction

Let C be a nonempty convex set in a real normed vector space X whose dual space is X^* . We say that a function $f: X \to (-\infty, +\infty)$ is pseudoconvex on C if it is Gâteaux differentiable at each $x \in C$ and, for $y \in C$,

$$\langle \nabla f(x), y - x \rangle \ge 0 \Rightarrow f(y) \ge f(x),$$

where $\nabla f(x)$ is the Gâteaux derivative of f at x which lies in X^* and satisfies

$$\langle \nabla f(x), v \rangle = \lim_{t \to 0^+} \frac{f(x + tv) - f(x)}{t}$$
 for all $v \in X$.

If -f is pseudoconvex on C, then f is said to be *pseudoconcave* on C. A function f is *pseudolinear* on C if it is both pseudoconvex and pseudoconcave on C. The concept of pseudoconvexity was introduced by Mangasarian in [9] to generalize that of the convexity of a differentiable function.

For
$$(x, y) \in C \times C$$
, we denote

$$xty := x + t(y - x)$$
 for $t \in [0, 1]$;

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$$[x, y] := \{xty : t \in [0, 1]\};$$

$$C_x := \{c \in C : f(x) \le f(c)\};$$

$$D_x := \{c \in C : f(x) \ge f(c)\};$$

$$E_x := \{c \in C : f(x) = f(c)\}.$$

Clearly E_x is the solution set of the programming problem to minimize f over C_x and

$$f(x) = f(y) \Leftrightarrow C_x = C_y \Leftrightarrow D_x = D_y \Leftrightarrow E_x = E_y$$
.

In addition, for a pseudoconvex function f on C,

$$C = \{c \in C : \langle \nabla f(x), c - x \rangle > 0\} \Leftrightarrow C_x = C.$$

When $C_x = C$, the solution set of the minimization problem of f over C is

$$E_x = \{ y \in C : \langle \nabla f(y), c - y \rangle \ge 0 \text{ for all } c \in C \}.$$

It is interesting to characterize the solution set of a minimization problem so that we can know more about the nature of its solutions. In \mathbb{R}^n , when x is an optimal solution, the set \mathbb{E}_x has been characterized in terms of the gradient ∇f by Mangasarian in [10] for a twice continuously differentiable convex program and by Jeyakumar and Yang [6] for a pseudolinear program. For the nondifferentiable convex case, the reader is referred to [2,5,10,12].

We note that the convexity of C_x plays an important role in characterizing the set E_x (no matter whether $C_x = C$ or not). Our main purpose in this paper is to present several equivalent conditions for the convexity of C_x in the pseudoconvex case. With these conditions we also characterize E_x to unify the corresponding results in [10,6]. Furthermore we use them to derive several results about the pseudolinearity of a function in a normed vector space under weaker conditions than in [3,7,8,11].

2. The convexity of C_x for a pseudoconvex function

It is easy to see that C_x may be nonconvex for each $x \in C$ with $C_x \neq C$ even for the convex case. For example, when $f(x) = x^2$ for $x \in C = [-1, 2]$, C_x is not convex for each $x \in [-1, 0) \cup (0, 1]$. However, for $x \in (1, 2]$, C_x is convex. We note that $\langle \nabla f(x), y - x \rangle \geq 0$ for all $x \in (1, 2]$ and for all $y \in C_x$. Indeed, this is one of the equivalent conditions for C_x to be convex as we state in our first simple result below.

Proposition 2.1. Let f be pseudoconvex at $x \in C$. Then the following are equivalent:

- (i) C_x is convex.
- (ii) For each $y \in C_x$, $[x, y] \subseteq C_x$.
- (iii) $\langle \nabla f(x), y x \rangle \ge 0$ for all $y \in C_x$.

Proof. It suffices to show (iii) \Rightarrow (i) since (i) \Rightarrow (ii) \Rightarrow (iii) is trivial.

Let (iii) be true. Then for any $y_1, y_2 \in C_x$,

$$\langle \nabla f(x), y_1 - x \rangle \ge 0$$
 and $\langle \nabla f(x), y_2 - x \rangle \ge 0$,

so $\langle \nabla f(x), y_1 t y_2 - x \rangle \ge 0$ for all $t \in [0, 1]$. By the pseudoconvexity of f at $x, y_1 t y_2 \in C_x$ for all $t \in [0, 1]$. This shows (i).

In Proposition 2.1, we only assume that the function f is pseudoconvex at the point x. When the function is pseudoconvex on the whole set C_x we have more equivalent statements for the convexity of C_x .

Theorem 2.2. Let C be a nonempty convex set in a normed vector space X and $x \in C$. If f is pseudoconvex on C_x , then (i)–(iii) in Proposition 2.1 and the following are equivalent:

(iv) For each $y \in C_x$ there exist p(x, y) > 0 and q(x, y) > 0 such that $p(x, y) \le 1$ and

$$f(y) \ge f(x) + p(x, y) \langle \nabla f(x), y - x \rangle \ge f(x) + q(x, y) \langle \nabla f(x), y - x \rangle^2.$$

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