### **Accepted Manuscript**

Resting-state functional connectivity predicts the ability to adapt to robot-mediated force fields

Irene Faiman, Sara Pizzamiglio, Duncan L. Turner

PII: \$1053-8119(18)30264-7

DOI: 10.1016/j.neuroimage.2018.03.054

Reference: YNIMG 14823

To appear in: Neurolmage

Received Date: 23 November 2017

Revised Date: 2 March 2018
Accepted Date: 22 March 2018

Please cite this article as: Faiman, I., Pizzamiglio, S., Turner, D.L., Resting-state functional connectivity predicts the ability to adapt to robot-mediated force fields, *NeuroImage* (2018), doi: 10.1016/j.neuroimage.2018.03.054.

This is a PDF file of an unedited manuscript that has been accepted for publication. As a service to our customers we are providing this early version of the manuscript. The manuscript will undergo copyediting, typesetting, and review of the resulting proof before it is published in its final form. Please note that during the production process errors may be discovered which could affect the content, and all legal disclaimers that apply to the journal pertain.



### **ACCEPTED MANUSCRIPT**

# Resting-state functional connectivity predicts the ability to adapt to robot-mediated force fields.

Irene Faiman<sup>a, b</sup>, Sara Pizzamiglio<sup>a</sup> and Duncan L. Turner<sup>a\*</sup>

E-mail address: d.l.turner@uel.ac.uk

<sup>&</sup>lt;sup>a</sup> NeuroRehabilitation Unit, School of Health, Sport and Bioscience, College of Applied Health and Communities, University of East London, Water Lane, E15 4LZ London, United Kingdom.

<sup>&</sup>lt;sup>b</sup> Faculty of Psychology and Neuroscience, Maastricht University, Universiteitssingel 40, 6229 ER Maastricht, Netherlands.

<sup>\*</sup>Correspondence to Professor Duncan L. Turner at University of East London

#### Download English Version:

## https://daneshyari.com/en/article/8686939

Download Persian Version:

https://daneshyari.com/article/8686939

<u>Daneshyari.com</u>