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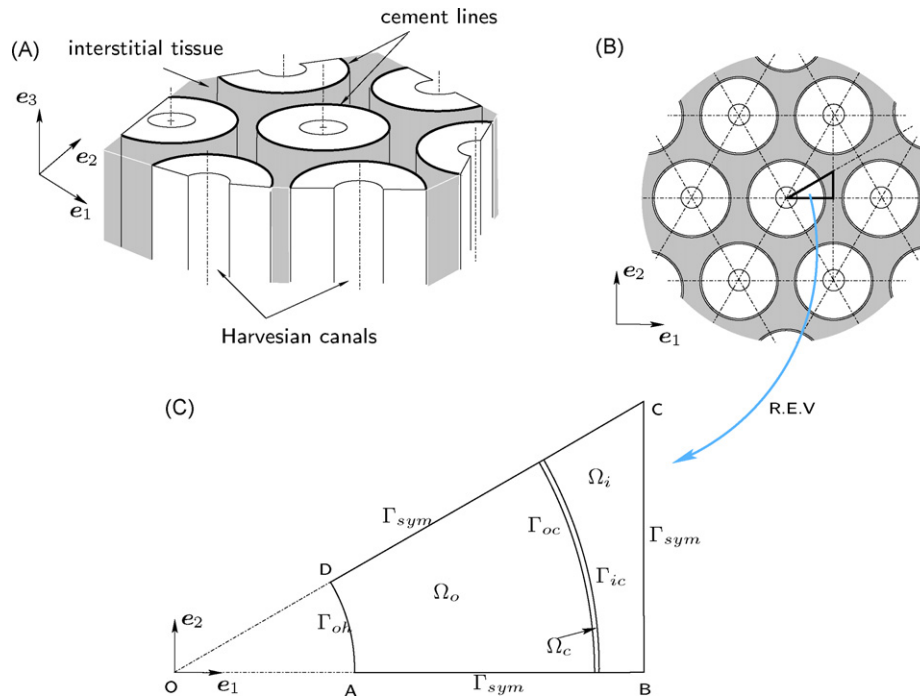


Fig. 1. Cortical tissue: (A) three-dimensional representation; (B) two-dimensional projection; (C) representative elementary volume.

formulations. Finally, Section 4 provides some numerical results of the fluid velocity, considering different geometrical and textural properties of cortical tissue under various loading conditions. The interest of these results for bone remodelling, mechanotransduction and cell stimulation is also discussed.

2. Description of the configuration and formulation of the problem

2.1. Geometrical configuration

In the osteonal bone matrix, Haversian canals run longitudinally through the bone cortex and are transversely inter-connected by Volkmann canals. Each osteon is developed concentrically around one Haversian canal and presents a cylinder-like form. For simplification purposes, the osteonal zone that is considered here is assumed to be far enough from transverse Volkmann canals, so that the influence of these canals can be neglected. Without this assumption, a large complex 3D model would have to be done.

We consider a representative matrix of osteons containing Haversian canals (see Fig. 1(A)). Let $\mathbf{R}(O; \mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ be the Cartesian frame of reference where O is the origin of the space equipped with an orthonormal basis $(\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$. The osteons, which all run in the vertical direction \mathbf{e}_3 , are modelled as thick-walled hollow cylinders. They are assumed to be identical and parallel. Moreover, they are arranged periodically in the horizontal plane $(\mathbf{e}_1, \mathbf{e}_2)$ (see Fig. 1(B)). Each osteon is coated by a thin layer called the cement line. The tissue found outside of the cement lines, i.e. the tissue that fills the space between the osteons, is the osteonal matrix formed by the remnants of old osteons.

The position \mathbf{x} of the particle of the medium is specified through the coordinates (x_1, x_2, x_3) with respect to \mathbf{R} . The time is denoted by t . Moreover, the Einstein summation convention, which stipulates that repeated indices are implicitly summed over, is used.

In what follows, superscripts referring to different material components of the cortical medium are introduced: Haversian canal (h), osteon (o), cement line (c) and interstitial tissues (i).

2.2. Three-dimensional governing poroelastic equations

The bone tissue materials (osteons, cement lines and interstitial matrix) are considered as saturated anisotropic poroelastic media. Neglecting body forces, the governing poroelastic equations for anisotropic material in the low frequency range are given by [1,3]:

$$\rho \ddot{\mathbf{u}} - \text{div } \boldsymbol{\sigma} = \mathbf{0}, \quad (1)$$

$$\frac{1}{M} \dot{p} - \text{div}(\mathbf{k} \text{grad } p) + \boldsymbol{\alpha} : \dot{\boldsymbol{\varepsilon}} = 0, \quad (2)$$

where $\rho = \phi \rho_f + (1 - \phi) \rho_s$ is the mixture density which is defined from the porosity ϕ and the densities ρ_f and ρ_s of the fluid and solid phases, respectively; \mathbf{u} and $\boldsymbol{\varepsilon}$ are the displacement vector and the strain tensor of the solid skeleton, respectively; $\boldsymbol{\sigma}$ is the total stress tensor; p is the fluid pressure in saturated pores; \mathbf{k} is the anisotropic permeability tensor; $\boldsymbol{\alpha}$ is the Biot tensor and M is the Biot modulus. The operators div and grad are respectively the divergence and gradient. Differentiation with respect to time t is denoted by superposed dot and the symbol ‘:’ between tensors of any order denotes their contraction.

Note that the permeability \mathbf{k} is the textural parameter allowing to quantify the ability of a porous material to transmit fluids through the Darcy law:

$$\mathbf{v} = -\mathbf{k} \text{grad } p, \quad (3)$$

where \mathbf{v} is the filtration velocity vector defined by $\mathbf{v} = \phi(\dot{\mathbf{u}}^f - \dot{\mathbf{u}})$ where \mathbf{u}^f is the velocity of the interstitial fluid. The tensor \mathbf{k} may be evaluated by $\mathbf{k} = \boldsymbol{\kappa} / \eta$ where $\boldsymbol{\kappa}$ is the intrinsic permeability and η the pore fluid dynamic viscosity.

The stress tensor $\boldsymbol{\sigma}$ is linearly related to the skeleton strain $\boldsymbol{\varepsilon}$ of the porous solid and to the fluid pressure p . Therefore, the constitutive relationship is given by:

$$\boldsymbol{\sigma} = \mathbb{C} : \boldsymbol{\varepsilon} - \boldsymbol{\alpha} p, \quad (4)$$

where \mathbb{C} is the stiffness tensor of the drained material.

For an orthotropic material, \mathbb{C} is defined by nine independent parameters and $\boldsymbol{\alpha}$ is a diagonal tensor defined by three independent

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