# Six-dimensional product Lie algebras admitting integrable complex structures 

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## A R T I C L E I N F O

## Article history:

Received 7 October 2016
Received in revised form 20 April 2017
Available online xxxx
Communicated by J. Huebschmann
MSC:
17B40; 53C15; 53C30


#### Abstract

We classify the 6-dimensional Lie algebras of the form $\mathfrak{g} \times \mathfrak{g}$ that admit an integrable complex structure. We also endow a Lie algebra of the kind $\mathfrak{o}(n) \times \mathfrak{o}(n)(n \geq 2)$ with such a complex structure. The motivation comes from geometric structures à la Sasaki on $\mathfrak{g}$-manifolds.


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## 1. Introduction

A complex structure on a Lie algebra $\mathfrak{h}$ is an endomorphism $\mathcal{J}: \mathfrak{h} \rightarrow \mathfrak{h}$ such that $\mathcal{J}^{2}=-i d$. It corresponds to a left invariant almost complex structure on any Lie group $H$ with $T_{e} H=\mathfrak{h}$. We say that a complex structure $\mathcal{J}$ on $\mathfrak{h}$ is integrable if

$$
N(v, w):=[v, w]+\mathcal{J}[\mathcal{J} v, w]+\mathcal{J}[v, \mathcal{J} w]-[\mathcal{J} v, \mathcal{J} w]=0
$$

for any $v, w \in \mathfrak{h}$. By the Newlander-Nirenberg theorem, via a left invariant trivialisation of the tangent bundle of $H$, this condition is likewise equivalent to the integrability of the corresponding left invariant almost complex structure on $H$.

Classification of integrable complex structures on real Lie algebras is a well established problem, cf. a summary of results on their existence in [9]. In dimension 6, the question is settled only for special abelian - complex structures, cf. [1], and for nilpotent algebras, cf. [2,7]. The present paper focuses on a different class of 6 -dimensional Lie algebras that split as a product $\mathfrak{g} \times \mathfrak{g}$ for a 3-dimensional Lie algebra $\mathfrak{g}$. We identify all such algebras admitting integrable complex structures. This problem was studied in the special cases of $\mathfrak{o}(3) \times \mathfrak{o}(3)$ and $\mathfrak{s l}(2, \mathbb{R}) \times \mathfrak{s l}(2, \mathbb{R})$ by Magnin in [4,5], where he also classified all possible

[^0]integrable complex structures. Such a complete description will not be our concern here, but we note that the classification given in [2] covers types (1), (2), and (3) of our Proposition 1.

Our main motivation comes from differential geometry. As explained in detail in [3], the existence of complex structures on 6 -dimensional product algebras has immediate applications to the recently developed theory of non-abelian, higher-dimensional structures à la Sasaki. To get an idea of the problem, consider a 3 -dimensional Lie group $G$ acting freely on an odd-dimensional manifold $M$. Suppose that this action preserves some transverse complex structure - a complex structure on the sub-bundle $\nu$ transverse to the orbits. We cannot hope to extend this complex structure to the whole tangent bundle - since the dimension is odd - but an interesting problem is to extend it to the $T(M \times G)$. Since the tangent space at a point $x$ in that product splits (as a vector space) $T_{x}(M \times G)=\nu_{x} \times \mathfrak{g} \times \mathfrak{g}$, this rises - and reduces to - the question of finding an integrable complex structure on $\mathfrak{g} \times \mathfrak{g}$. Then the transverse complex structure on $M$ can be studied in terms of an ordinary complex structure on $M \times G$. Recall that a manifold $S$ is Sasakian if its Riemannian cone $S \times \mathbb{R}$ is Kähler - and thus the above approach is a starting point for natural generalisations.

We point out that an integrable complex structure on its Lie algebra does not turn a Lie group into a complex Lie group. In fact, every compact Lie group of even dimension admits an integrable left invariant complex structure, cf. [8,10], while it is well-known that only tori can be compact complex Lie groups.

In the last section we provide an explicit integrable complex structure for every algebra of the type $\mathfrak{o}(n) \times \mathfrak{o}(n)$.

## 2. Complex structures on 6-dimensional product algebras

Recall that the 3 -dimensional Lie algebras were classified into 9 types by Bianchi. We use a variant, a classification from [6] by the dimension of the derived algebra and Jordan decomposition of certain automorphism acting upon it. We include the statement for convenience.

Proposition 1. [6] Let $e_{1}$, $e_{2}$ and $e_{3}$ be a basis of $\mathbb{R}^{3}$. Up to isomorphism of Lie algebras, the following list yields all Lie brackets on $\mathbb{R}^{3}$
(1) $\left[e_{1}, e_{3}\right]=0,\left[e_{2}, e_{3}\right]=0,\left[e_{1}, e_{2}\right]=0$
(2) $\left[e_{1}, e_{3}\right]=0,\left[e_{2}, e_{3}\right]=0,\left[e_{1}, e_{2}\right]=e_{1}$
(3) $\left[e_{1}, e_{3}\right]=0,\left[e_{2}, e_{3}\right]=0,\left[e_{1}, e_{2}\right]=e_{3}$
(4) $\left[e_{1}, e_{3}\right]=e_{1},\left[e_{2}, e_{3}\right]=\theta e_{2},\left[e_{1}, e_{2}\right]=0$ for $\theta \neq 0$ (the case $\theta=1$ is considered to be Bianchi's ninth type)
(5) $\left[e_{1}, e_{3}\right]=e_{1},\left[e_{2}, e_{3}\right]=e_{1}+e_{2},\left[e_{1}, e_{2}\right]=0$
(6) $\left[e_{1}, e_{3}\right]=\theta e_{1}-e_{2},\left[e_{2}, e_{3}\right]=e_{1}+\theta e_{2},\left[e_{1}, e_{2}\right]=0$ for $\theta \neq 0$
(7) $\left[e_{1}, e_{3}\right]=e_{2},\left[e_{2}, e_{3}\right]=e_{1},\left[e_{1}, e_{2}\right]=e_{3}$
(8) $\left[e_{1}, e_{3}\right]=-e_{2},\left[e_{2}, e_{3}\right]=e_{1},\left[e_{1}, e_{2}\right]=e_{3}$

We fix some notation. Whenever we write $(x, y, z) \in \mathfrak{g}$, it is understood in the appropriate basis above. If any other basis $\{u, v, w\}$ is used, we write $X u+Y v+Z w$.

The direct product $\mathfrak{g} \times \mathfrak{g}$ inherits the bracket operation on each factor from $\mathfrak{g}:[(u, v),(t, s)]=([u, t],[v, s])$. We keep the distinction between the two copies of $\mathfrak{g}$ inside $\mathfrak{g} \times \mathfrak{g}$ by adding asterisks to the second copy. Any vector decorated with an asterisk is understood to lie in $\mathfrak{g}^{*}=0 \times \mathfrak{g}$, while those without it lie in $\mathfrak{g}=\mathfrak{g} \times 0$. We tacitly use the natural isomorphism between the two copies, $(v, 0)^{*}=(0, v)$. We also distinguish the two components of a complex structure $\mathcal{J}$ - it will be convenient to work with $J$ and $J^{*}$ as in $\mathcal{J} v=\left(J v, J^{*} v\right)$ to indicate its $\mathfrak{g}$ - and $\mathfrak{g}^{*}$-parts separately. As a rule, virtually every vector on which we act in the lengthy proofs lies in $\mathfrak{g}$.

To finish the preliminaries we note the following to use frequently in what follows.

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    http://dx.doi.org/10.1016/j.jpaa.2017.06.010
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