

A simplified approach to Fiedler-like pencils via block minimal bases pencils



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MSC: 65F15 ABSTRACT

The standard way of solving the polynomial eigenvalue problem associated with a matrix polynomial is to embed the matrix coefficients of the polynomial into a matrix pencil, transforming the problem into an equivalent generalized eigenvalue problem. Such pencils are known as linearizations. Many of the families of linearizations for matrix polynomials available in the literature are extensions of the so-called

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1. Introduction

Matrix polynomials and their associated polynomial eigenvalue problems appear in many areas of applied mathematics, and they have received in the last years considerable attention. For example, they are ubiquitous in a wide range of problems in engineering, mechanics, control theory, computer-aided graphic design, etc. For detailed discussions of different applications of matrix polynomials, we refer the reader to the classical references [25,30,45], the modern surveys [3, Chapter 12] and [39,46] (and the references therein), and [35–37]. For those readers not familiar with the theory of matrix polynomials and polynomial eigenvalue problems, those topics are briefly reviewed in Section 2.

The standard way of solving the polynomial eigenvalue problem associated with a matrix polynomial is to *linearize* the polynomial into a matrix pencil (i.e., matrix polynomials of grade 1), known as linearization [15,24,25]. The linearization process transforms the polynomial eigenvalue problem into an equivalent generalized eigenvalue problem, which, then, can be solved using eigensolvers such as the QZ algorithm or the staircase algorithm, in the case of singular matrix polynomials [40,48,49]. Ideally, to make a set of linearizations desirable for numerical applications, it should satisfy the following list of properties:

- (i) the linearizations should be *strong linearizations*, regardless whether the matrix polynomial is regular or singular;
- (ii) the linearizations should be easily constructible from the coefficients of the matrix polynomials (ideally, without any matrix operation other than scalar multiplication);

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