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### Linear Algebra and its Applications

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# Some remarks on the complex J-symmetric eigenproblem



LINEAR Algebra

Applications

Peter Benner<sup>a</sup>, Heike Faßbender<sup>b,\*</sup>, Chao Yang<sup>c</sup>

 <sup>a</sup> Max Planck Institute for Dynamics of Complex Technical Systems, Sandtorstr. 1, 39106 Magdeburg, Germany
<sup>b</sup> AG Numerik, TU Braunschweig, Universitätsplatz 2, 38106 Braunschweig, Germany

<sup>c</sup> Computational Research Division, Lawrence Berkeley National Laboratory, Berkeley, CA 94720, USA

#### A R T I C L E I N F O

Article history: Received 19 July 2015 Accepted 10 January 2018 Submitted by C. Mehl

MSC: 65F15

Keywords: Complex J-symmetric eigenproblem Real Hamiltonian matrix Complex Hamiltonian matrix Structure-preserving SR algorithm

#### ABSTRACT

The eigenproblem for complex J-symmetric matrices  $H_C = \begin{bmatrix} A & C \\ D & -A^T \end{bmatrix}$ ,  $A, C = C^T$ ,  $D = D^T \in \mathbb{C}^{n \times n}$  is considered. A proof of the existence of a transformation to the complex J-symmetric Schur form proposed in [21] is given. The complex symplectic unitary QR decomposition and the complex symplectic SR decomposition are discussed. It is shown that a QR-like method based on the complex symplectic unitary QR decomposition is not feasible here. A complex symplectic SR algorithm is presented which can be implemented such that one step of the SR algorithm can be carried out in  $\mathcal{O}(n)$  arithmetic operations. Based on this, a complex symplectic Lanczos method can be derived. Moreover, it is discussed how the  $2n \times 2n$  complex J-symmetric matrix  $H_C$  can be embedded in a  $4n \times 4n$  real Hamiltonian matrix.

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\* Corresponding author.

 $\label{eq:https://doi.org/10.1016/j.laa.2018.01.014} 0024-3795 \ensuremath{\oslash}\ 0218 \ Elsevier \ Inc. \ All \ rights \ reserved.$ 

E-mail address: h.fassbender@tu-braunschweig.de (H. Faßbender).

#### 1. Introduction

The basic algebraic structures and properties of the following classes of matrices

$H_C \in \mathbb{C}^{2n \times 2n}$	complex $J$ -symmetric	$JH_C = (JH_C)^T$
$H_H \in \mathbb{C}^{2n \times 2n}$	J-Hermitian	$JH_H = (JH_H)^H$
	(complex Hamiltonian)	
$H \in \mathbb{R}^{2n \times 2n}$	real Hamiltonian	$JH = (JH)^H = (JH)^T$

are well-known, see, e.g., [11,18,19]. Here  $J = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix}$  and I is the  $n \times n$  identity matrix.  $X^T$  denotes transposition,  $Y = X^T$ ,  $y_{ij} = x_{ji}$ , no matter whether X is real or complex, while  $X^H$  denotes conjugate transposition,  $Y = X^H$ ,  $y_{ij} = \overline{x_{ji}}$ . In case  $H \in \mathbb{R}^{2n \times 2n}$ , the structures coalesce, H is complex J-symmetric and J-Hermitian. Each of the three classes of matrices forms a Lie algebra. The eigenvalues of real Hamiltonian matrices H and of complex J-symmetric matrices  $H_C$  display a symmetry [19]: they appear in pairs  $(\lambda, -\lambda)$ . If x is the right eigenvector corresponding to  $\lambda$ ,  $Bx = \lambda x$ , then Jx is the left eigenvector corresponding to the eigenvalue  $-\lambda$  of B = H or  $B = H_C$ ,  $(Jx)^T B = -\lambda(Jx)^T$ . Moreover, the matrices in these two classes can always be written in block form  $\begin{bmatrix} A & C \\ D & -A^T \end{bmatrix}$  with  $C = C^T$ ,  $D = D^T$ , where either  $A, C, D \in \mathbb{R}^{n \times n}$  or  $A, C, D \in \mathbb{C}^{n \times n}$ . In contrast, complex Hamiltonian matrices have a block form  $\begin{bmatrix} A & C \\ D & -A^H \end{bmatrix}$  with  $A, C = C^H$ ,  $D = D^H \in \mathbb{C}^{n \times n}$ ; the eigenvalues display the symmetry  $(\lambda, -\overline{\lambda})$ .

A particular instance of the *J*-symmetric eigenproblem arises in the context of estimating the absorption spectra in molecules and solids using the Bethe–Salpeter equations [22,23] for determining electronic excitation energies. Solving the Bethe–Salpeter equations numerically, the eigenvalue problem  $H_{BS}x = \lambda x$  for complex matrices

$$H_{BS} = \begin{bmatrix} A & -D^H \\ D & -A^T \end{bmatrix} \in \mathbb{C}^{2n \times 2n}, \quad A = A^H, D = D^T \in \mathbb{C}^{n \times n}$$
(1)

arises. The matrices  $H_{BS}$  belong to the slightly more general class of matrices of complex J-symmetric matrices

$$H_C = \begin{bmatrix} A & C \\ D & -A^T \end{bmatrix} \in \mathbb{C}^{2n \times 2n}, \quad A, C = C^T, D = D^T \in \mathbb{C}^{n \times n}.$$
(2)

As already discussed, the eigenvalues of  $H_C$  display the symmetry  $(\lambda, -\lambda)$ . Clearly,  $H_{BS}$  inherits these properties. There is even more structure in the eigenvalues and eigenvectors of  $H_{BS}$ .

**Theorem 1.** Eigenvalues of  $H_{BS}$  that are real or purely imaginary appear in pairs  $(\lambda, -\lambda)$ , other eigenvalues appear in quadruples  $(\lambda, -\lambda, \overline{\lambda}, -\overline{\lambda})$ . Moreover, for  $\lambda \in \mathbb{C}$ ,  $H_{BS}x = \lambda x$  implies  $H_{BS}K\overline{x} = -\overline{\lambda}K\overline{x}$  and  $H_{BS}y = -\lambda y$  implies  $H_{BS}K\overline{y} = \overline{\lambda}K\overline{y}$  with

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