

Available online at [www.sciencedirect.com](http://www.sciencedirect.com)

ScienceDirect

Ann. I. H. Poincaré – AN ●●● (●●●●) ●●●●●●

ANNALES  
DE L'INSTITUT  
HENRI  
POINCARÉ  
ANALYSE  
NON LINÉAIRE[www.elsevier.com/locate/anihpc](http://www.elsevier.com/locate/anihpc)

# Divergence-free positive symmetric tensors and fluid dynamics

Denis Serre

École Normale Supérieure de Lyon, U.M.P.A., UMR CNRS–ENSL # 5669, 46 allée d'Italie, 69364 Lyon cedex 07, France

Received 19 May 2017; accepted 7 November 2017

## Abstract

We consider  $d \times d$  tensors  $A(x)$  that are symmetric, positive semi-definite, and whose row-divergence vanishes identically. We establish sharp inequalities for the integral of  $(\det A)^{\frac{1}{d-1}}$ . We apply them to models of compressible inviscid fluids: Euler equations, Euler–Fourier, relativistic Euler, Boltzman, BGK, etc. We deduce an *a priori* estimate for a new quantity, namely the space–time integral of  $\rho^{\frac{1}{n}} p$ , where  $\rho$  is the mass density,  $p$  the pressure and  $n$  the space dimension. For kinetic models, the corresponding quantity generalizes Bony's functional.

© 2017 Elsevier Masson SAS. All rights reserved.

**Keywords:** Conservation laws; Gas dynamics; Functional inequalities

**Notations.** The integer  $d \geq 2$  is the number of independent variables, which are often space–time coordinates. It serves also for the size of square matrices. If  $1 \leq j \leq d$  and  $x \in \mathbb{R}^d$  are given, we set  $\widehat{x}_j = (\dots, x_{j-1}, x_{j+1}, \dots) \in \mathbb{R}^{d-1}$ ; the projection  $x \mapsto \widehat{x}_j$  ignores the  $j$ -th coordinate. The transpose of a matrix  $M$  is  $M^T$ . If  $A \in \mathbf{M}_d(\mathbb{R})$ , its cofactor matrix  $\widehat{A}$  satisfies

$$\widehat{A}^T A = A \widehat{A}^T = (\det A) I_d, \quad \det \widehat{A} = (\det A)^{d-1}.$$

Because we shall deal only with symmetric matrices, we have simply  $\widehat{A} A = A \widehat{A} = (\det A) I_d$ . The space of  $d \times d$  symmetric matrices with real entries is  $\mathbf{Sym}_d$ . The cones of positive definite, respectively positive semi-definite, matrices are  $\mathbf{SPD}_d$  and  $\mathbf{Sym}_d^+$ . If  $u \in \mathbb{R}^d$ ,  $u \otimes u \in \mathbf{Sym}_d^+$  denotes the rank-one matrix of entries  $u_i u_j$ .

The unit sphere of  $\mathbb{R}^d$  is  $S^{d-1}$ . The Euclidean volume of an open subset  $\Omega$  of  $\mathbb{R}^d$  is denoted  $|\Omega|$ . If the boundary  $\partial\Omega$  is rectifiable, we denote the same way  $|\partial\Omega|$  its area, and  $ds(x)$  the area element. For instance, the ball  $B_r$  of radius  $r$  and its boundary, the sphere  $S_r$ , satisfy  $|B_r| = \frac{r}{d} |S_r|$ . If  $\Omega$  has a Lipschitz boundary, its outer unit normal  $\bar{n}$  is defined almost everywhere.

If  $f : \Omega \rightarrow \mathbb{R}$  is integrable, its average over  $\Omega$  is the number

$$\int_{\Omega} f(x) dx := \frac{1}{|\Omega|} \int_{\Omega} f(x) dx.$$

*E-mail address:* [denis.serre@ens-lyon.fr](mailto:denis.serre@ens-lyon.fr).

<https://doi.org/10.1016/j.anihpc.2017.11.002>

0294-1449/© 2017 Elsevier Masson SAS. All rights reserved.

Given a lattice  $\Gamma$  of  $\mathbb{R}^d$ , and  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  a  $\Gamma$ -periodic, locally integrable function, we denote

$$\int_{\mathbb{R}^d/\Gamma} f(x) dx$$

the value of the integral of  $f$  over any fundamental domain. We define as above the average value

$$\overline{f} = \int_{\mathbb{R}^d/\Gamma} f(x) dx.$$

For our purpose, a *tensor* is a matrix-valued function  $x \mapsto T(x) \in \mathbf{M}_{p \times q}(\mathbb{R})$ . If  $q = d$  and if the derivatives make sense (say as distributions), we form

$$\text{Div} T = \left( \sum_{j=1}^d \partial_j t_{ij} \right)_{1 \leq i \leq p},$$

which is vector-valued. We emphasize the uppercase letter D in this context. We reserve the lower case operator **div** for vector fields.

If  $1 \leq p \leq \infty$ , its conjugate exponent is  $p'$ .

### Acknowledgments

This research benefited from discussions that I had with various persons, and references that I got from others. I thank warmly Grégoire Allaire, Yann Brenier, Vincent Calvez, Guido de Philippis, Reinhard Illner, Grégoire Loeper, Petru Mironescu, Jean-Christophe Mourrat, Laure Saint-Raymond, Bruno Sévenec and Cédric Villani.

## 1. Introduction

We first define the mathematical object under consideration.

**Definition 1.1.** Let  $\Omega$  be an open subset of  $\mathbb{R}^d$ . A *divergence-free positive symmetric tensor* (in short, a *DPT*) is a locally integrable tensor  $x \mapsto A(x)$  over  $\Omega$  with the properties that  $A(x) \in \mathbf{Sym}_d^+$  almost everywhere, and  $\text{Div} A = 0$ .

The following fact is obvious.

**Lemma 1.1 (Congruence.).** *If  $A$  is a DPT and  $P \in \mathbf{GL}_d(\mathbb{R})$  is given, then the tensor*

$$B(y) := PA(P^{-1}y)P^T$$

*is also a DPT.*

### 1.1. Motivations: Where do the divergence-free positive symmetric tensors occur?

Most of our examples, though not all of them, come from fluid dynamics, where a DPT contains a stress tensor.

**Compressible gas.** In space dimension  $n \geq 1$ , a gas is described by a mass density  $\rho \geq 0$ , a velocity  $u$  and a pressure  $p \geq 0$ . These fields obey the Euler equations (conservation of mass and momentum)

$$\partial_t \rho + \text{div}_y(\rho u) = 0, \quad \partial_t(\rho u) + \text{Div}_y(\rho u \otimes u) + \nabla_y p = 0.$$

Here  $x = (t, y)$  and  $d = 1 + n$ . The tensor

$$A(t, y) = \begin{pmatrix} \rho & \rho u^T \\ \rho u & \rho u \otimes u + p I_n \end{pmatrix}$$

is a DPT.

Download English Version:

<https://daneshyari.com/en/article/8898106>

Download Persian Version:

<https://daneshyari.com/article/8898106>

[Daneshyari.com](https://daneshyari.com)