



Nonlocal Cahn–Hilliard–Navier–Stokes systems with shear dependent viscosity



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ABSTRACT

We consider a diffuse interface model for the phase separation of an incompressible and isothermal non-Newtonian binary fluid mixture in three dimensions. The averaged velocity \mathbf{u} is governed by a Navier–Stokes system with a shear dependent viscosity controlled by a power $p > 2$. This system is nonlinearly coupled through the Korteweg force with a convective nonlocal Cahn–Hilliard equation for the order parameter φ , that is, the (relative) concentration difference of the two components. The resulting equations are endowed with the no-slip boundary condition for \mathbf{u} and the no-flux boundary condition for the chemical potential μ . The latter variable is the functional derivative of a nonlocal and nonconvex Ginzburg–Landau type functional which accounts for the presence of two phases. We first prove the existence of a weak solution in the case $p \geq 11/5$. Then we extend some previous results on time regularity and uniqueness if $p > 11/5$.

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1. Introduction

We consider a mixture of incompressible, isothermal and (partially) immiscible binary fluids in a given bounded domain $\Omega \subset \mathbb{R}^3$. We suppose that they both have density equal to one and we denote by \mathbf{u} their (volume) averaged velocity and by φ the (relative) concentration difference. A well-known diffuse interface model (see, e.g., [4,25,26]) for the phase separation of the mixture is given by

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \operatorname{div} \mathcal{S}(\varphi, D\mathbf{u}) + \nabla \pi = \mu \nabla \varphi + \mathbf{h}(t) \quad (1.1)$$

$$\operatorname{div} \mathbf{u} = 0 \quad (1.2)$$

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$$\partial_t \varphi + (\mathbf{u} \cdot \nabla) \varphi = \Delta \mu \quad (1.3)$$

$$\mu = -\Delta \varphi + F'(\varphi) \quad (1.4)$$

in $\Omega \times (0, T)$, $T > 0$. Here the mobility and other constants have been taken equal to one, F is a double well potential (e.g., $F(r) = (r^2 - 1)^2$, $r \in \mathbb{R}$) which accounts for the presence of two components, \mathbf{h} is an external force. The stress tensor \mathcal{S} , up to the pressure term, depends on the symmetric gradient $D\mathbf{u} := (\nabla \mathbf{u} + \nabla^T \mathbf{u})/2$ of the velocity field \mathbf{u} and, possibly, on φ , through a suitable constitutive law. If, for instance, we have

$$\mathcal{S}(\varphi, D\mathbf{u}) = \nu(\varphi) D\mathbf{u}, \quad (1.5)$$

ν being a given strictly positive function, then we are in presence of a Newtonian mixture. The corresponding system (1.1)–(1.4) is called Cahn–Hilliard–Navier–Stokes system (see, e.g., [1,8,9,20,30,34,36]). When the mixture has non-Newtonian features, then the stress tensor itself depends on some power of $|D\mathbf{u}|$. A typical example is given by

$$\mathcal{S}(\varphi, D\mathbf{u}) = (\nu_1(\varphi) + \nu_2(\varphi)|D\mathbf{u}|^{p-2}) D\mathbf{u}, \quad (1.6)$$

where ν_i , $i = 1, 2$, are strictly positive functions and $p > 1$. Concerning the single non-Newtonian fluids see, for instance, [32] for the physical background, and [31] for the basic mathematical theory; cf. also [10,13] and its references for more advanced development. The system (1.1)–(1.4) has also recently been investigated in a number of contributions (see [2,7,23,24,27]). In those papers, the chemical potential μ (see (1.1)) is the functional derivative of the Ginzburg–Landau type functional

$$\mathcal{F}(\varphi) = \int_{\Omega} \left(\frac{|\nabla \varphi(x)|^2}{2} + F(\varphi(x)) \right) dx.$$

However, this is a phenomenological assumption and a more rigorous approach shows that the functional should be nonlocal (see [21,22]). For instance, following [5], we can take

$$\mathcal{E}(\varphi) = \frac{1}{4} \int_{\Omega \times \Omega} J(x-y) |\varphi(x) - \varphi(y)|^2 dx dy + \int_{\Omega} F(\varphi(x)) dx. \quad (1.7)$$

Here $J : \mathbb{R} \rightarrow \mathbb{R}$ is a sufficiently smooth interaction kernel such that $J(x) = J(-x)$. With this choice the chemical potential becomes

$$\mu = a\varphi - J * \varphi + F'(\varphi),$$

where

$$a(x) := \int_{\Omega} J(x-y) dy, \quad (J * \varphi)(x) = \int_{\Omega} J(x-y) \varphi(y) dy. \quad (1.8)$$

Therefore we have the following nonlocal system in $\Omega \times (0, T)$

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} - \operatorname{div} \mathcal{S}(\varphi, D\mathbf{u}) + \nabla \pi = \mu \nabla \varphi + \mathbf{h}(t) \quad (1.9)$$

$$\operatorname{div} \mathbf{u} = 0 \quad (1.10)$$

$$\partial_t \varphi + (\mathbf{u} \cdot \nabla) \varphi = \Delta \mu \quad (1.11)$$

$$\mu = a\varphi - J * \varphi + F'(\varphi). \quad (1.12)$$

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