



# Predetermining the number of periodic steps in multi-step Newton-like methods for solving equations and systems of equations

I.K. Argyros<sup>a,\*</sup>, St. Mărușter<sup>b</sup>

<sup>a</sup> Department of Mathematical Science, Cameron University, Lawton, OK 73505, USA

<sup>b</sup> West University of Timișoara, Department of Mathematics and Computer Science, Timișoara 30174, Romania

## ARTICLE INFO

MSC:  
45G10  
47H17  
65J15  
65G99

### Keywords:

Multi-step Newton-type method  
Banach space  
Euclidean space  
Semi-local convergence  
Center-Lipschitz and Lipschitz conditions  
Systems of differential equations

## ABSTRACT

The goal of this paper is to predetermine the steps  $m$  after which the first derivative is re-evaluated for multi-step Newton-type method used to approximate solutions of equations.

© 2018 Elsevier Inc. All rights reserved.

## 1. Introduction

Numerous problems in computational sciences and also in engineering such as, problems from optimization; economic equilibrium theory; astrophysics; elasticity; neutron transport; dynamical systems to mention a few, can be brought in a form like

$$F(x) = 0 \quad (1.1)$$

using mathematical modeling [1,4–6,11–13]. Here,  $F: D \subseteq B_1 \rightarrow B_2$  is a Fréchet differentiable operator,  $B_1, B_2$  are Banach spaces and  $D$  is a convex subset of  $B_1$ . Finding a solution  $p$  of Eq. (1.1) is a great challenge in general. One wishes to obtain a solution  $p$  in closed form but this is possible only in spacial cases. That explains why most solution methods for Eq. (1.1) are usually iterative.

There is a plethora of high convergence order iterative methods for solving Eq. (1.1) involving high order derivatives [1–15]. However, these methods are unattractive, since they are very expensive. Currently, there is an increasing interest in developing iterative methods of high convergence order using the first Fréchet derivative and its inverse. In particular, we consider the  $k$ -step Newton-type method defined for each  $n = 0, 1, 2, \dots, k$  where  $k$  is a natural number, and some starting point  $x_0 = x_0^0 \in D$  by

\* Corresponding author.

E-mail addresses: [iargyros@cameron.edu](mailto:iargyros@cameron.edu), [ioannisa@cameron.edu](mailto:ioannisa@cameron.edu) (I.K. Argyros), [maruster@info.uvt.ro](mailto:maruster@info.uvt.ro) (St. Mărușter).

$$\begin{aligned}
x_n^1 &= x_n^0 - F'(x_n^0)^{-1}F(x_n^0) \\
x_n^2 &= x_n^1 - F'(x_n^0)^{-1}F(x_n^1) \\
&\vdots \\
x_n^k &= x_n^{k-1} - F'(x_n^0)^{-1}F(x_n^{k-1}) \\
x_{n+1}^0 &= x_n^k
\end{aligned} \tag{1.2}$$

The convergence of such methods has been studied under Lipschitz-conditions and  $w$ -type conditions by several authors [4–10]. The convergence order is  $k + 1$ . The convergence domain of method (1.2) is small in general under the mentioned conditions limiting the applicability of method (1.2). In the present study, we use center-Lipschitz conditions for the computation of the upper bound on the inverses  $\|F'(x_n^0)^{-1}F'(x_0^0)\|$  instead of the less accurate Lipschitz conditions. Moreover, we locate a more precise domain than before, where the iterates lie leading to smaller Lipschitz constants. We also use our method of recurrent functions that has been effective in the study of iterative methods [1–4]. This way, we obtain the following advantages (I):

- ( $i_1$ ) Larger convergence domain.
- ( $i_2$ ) Tighter error bounds on the distances  $\|x_m^m - x_n^{m-1}\|$ ,  $\|x_n^m - p\|$ ,  $m = 2, 3, \dots, k$ .
- ( $i_3$ ) More precise information on the location of the solution  $p$ .

We also provide some results on how to predetermine the choice of  $k$  in the general case of a Banach space setting as well as in the special case when  $B_1 = B_2 = \mathbb{R}^j$  ( $j$  a natural number).

The rest of the paper is structured as follows: The semi-local convergence analysis is presented in Section 2 and the applications in Section 3.

## 2. Semi-local convergence analysis

We need an auxiliary result on majorizing sequences for method (1.2).

**Lemma 1.** Let  $L_0$ ,  $L$  and  $\eta$  be positive numbers with  $L_0 \leq L$ . Define the scalar sequence  $\{t_{n,m}\}$  for each  $n = 0, 1, 2, \dots$ ,  $m = 1, 2, \dots, k$  by

$$\begin{aligned}
t_{0,0} &= 0, \quad t_{0,1} = \eta, \\
t_{n,2} &= t_{n,1} + \frac{L}{2} \frac{(t_{n,1} - t_{n,0})^2}{1 - L_0 t_{n,0}} \quad \text{for } m = 2,
\end{aligned} \tag{2.1}$$

and for  $m \neq 2$

$$t_{n,m} = t_{n,m-1} + \frac{L}{2} \frac{[(t_{n,m-1} - t_{n,0}) + (t_{n,m-2} - t_{n,0})](t_{n,m-1} - t_{n,0})}{1 - L_0 t_{n,0}}$$

$$t_{n,k} = t_{n+1,0}$$

Denote by  $\xi = \xi(k) = \xi_k$  the smallest positive root of the function  $\varphi_k$  defined on the interval  $[0, 1]$  by

$$\varphi_k(t) = L(t^k - 1)[(1 + t + \dots + t^{k-1}) + (1 + t + \dots + t^{k-2})] + 2L_0(1 + t + \dots + t^{k-1})t^{k+1}. \tag{2.2}$$

Suppose that

$$0 \leq \frac{L(t_{0,k} + t_{0,k-1})}{2(1 - L_0 t_{0,k})} \leq \xi < 1 - L_0 \eta. \tag{2.3}$$

Then, scalar sequence  $\{t_{n,m}\}$  is increasing, bounded from above by

$$t^{**} = \frac{\eta}{1 - \xi} \tag{2.4}$$

and converges to its unique least upper bound  $t^*$  satisfying

$$\eta \leq t^* \leq t^{**}. \tag{2.5}$$

Moreover, for each  $n = 0, 1, 2, \dots$ ,  $m = 1, 2, \dots, k$ , the following items hold

$$t_{n,m-1} \leq t_{n,m} \tag{2.6}$$

$$t^* < \frac{1}{L_0} \tag{2.7}$$

$$0 \leq t_{n,m} - t_{n,m-1} \leq \xi(t_{n,m-1} - t_{n,m-2}) \tag{2.8}$$

and

Download English Version:

<https://daneshyari.com/en/article/8901087>

Download Persian Version:

<https://daneshyari.com/article/8901087>

[Daneshyari.com](https://daneshyari.com)